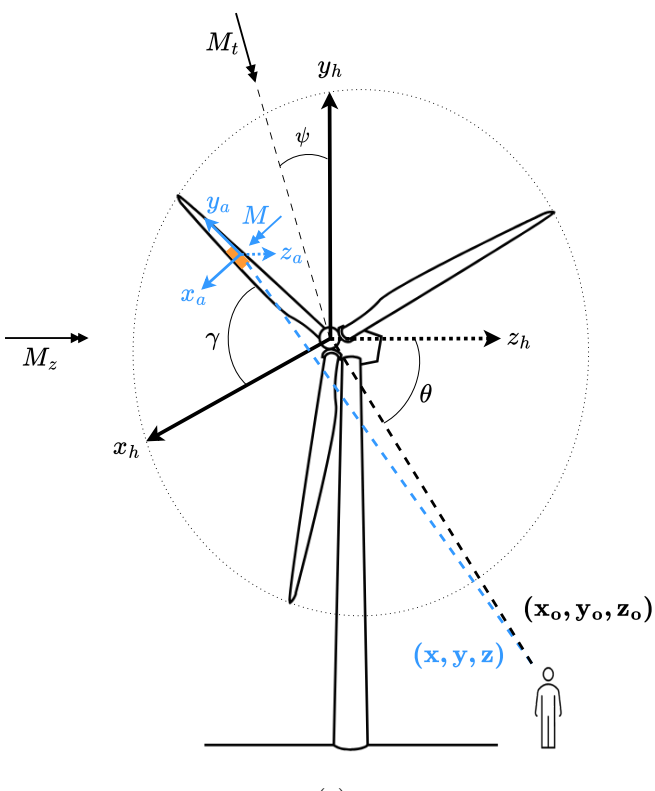
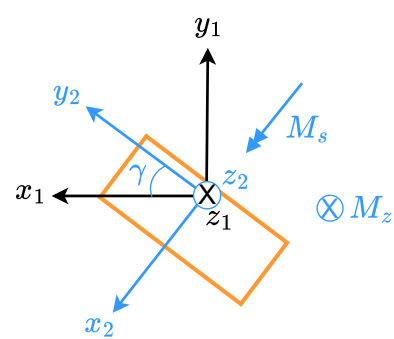
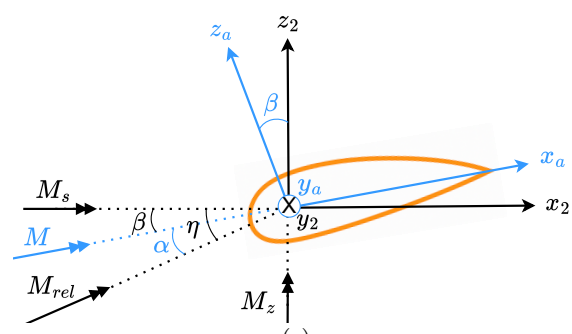

M_t
y_h
ψ
y_a
M
z_a
x_a
γ
M_z
z_h
θ
x_h
$(\mathbf{x_o, y_o, z_o})$
$(\mathbf{x, y, z})$

(a)


y_1
y_2
M_s
γ
z_2
x_1
z_1
$\otimes M_z$
x_2

(b)


z_a
z_2
β
x_a
M_s
y_a
x_2
β
M
α
η
y_2
M_{rel}
M_z

(c)