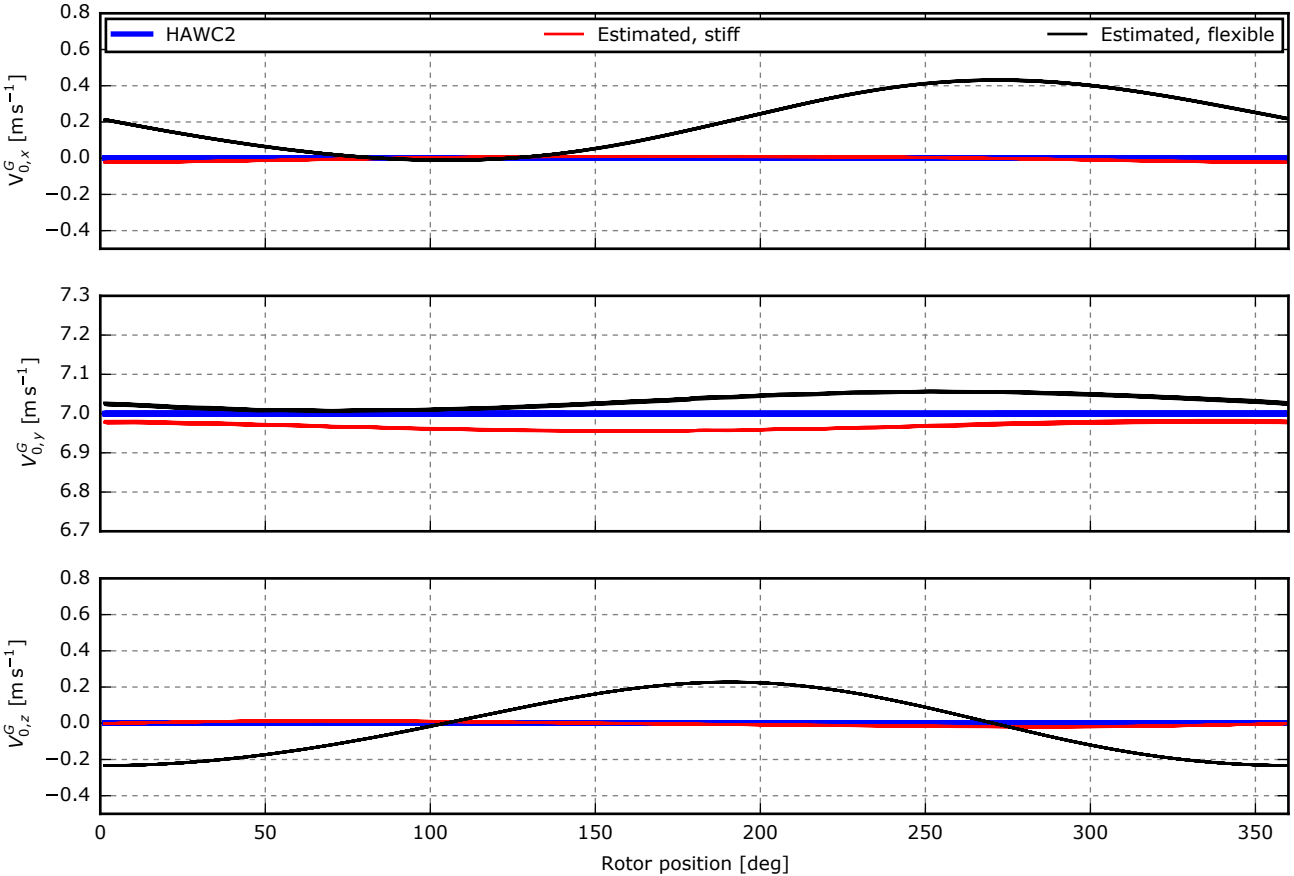
HAWC2
Estimated, stiff
Estimated, flexible
$V^G_{0,x}$ [m s^{-1}]
$V^G_{0,y}$ [m s^{-1}]
$V^G_{0,z}$ [m s^{-1}]
Rotor position [deg]