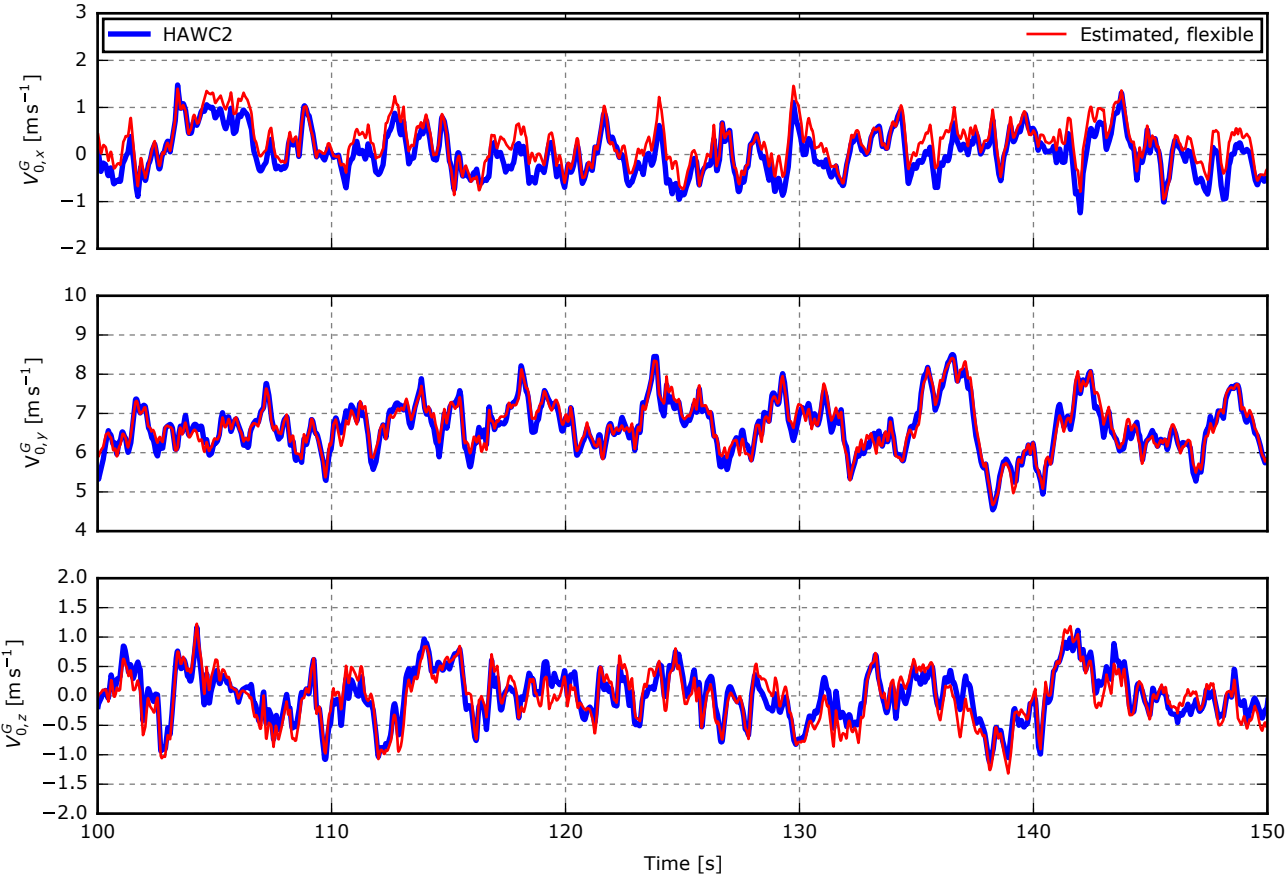
HAWC2
Estimated, flexible
$V^G_{0,x}$ [m s^{-1}]
$V^G_{0,y}$ [m s^{-1}]
$V^G_{0,z}$ [m s^{-1}]
Time [s]
3
2
1
0
−1
−2
10
9
8
7
6
5
4
2.0
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
−2.0
100
110
120
130
140
150