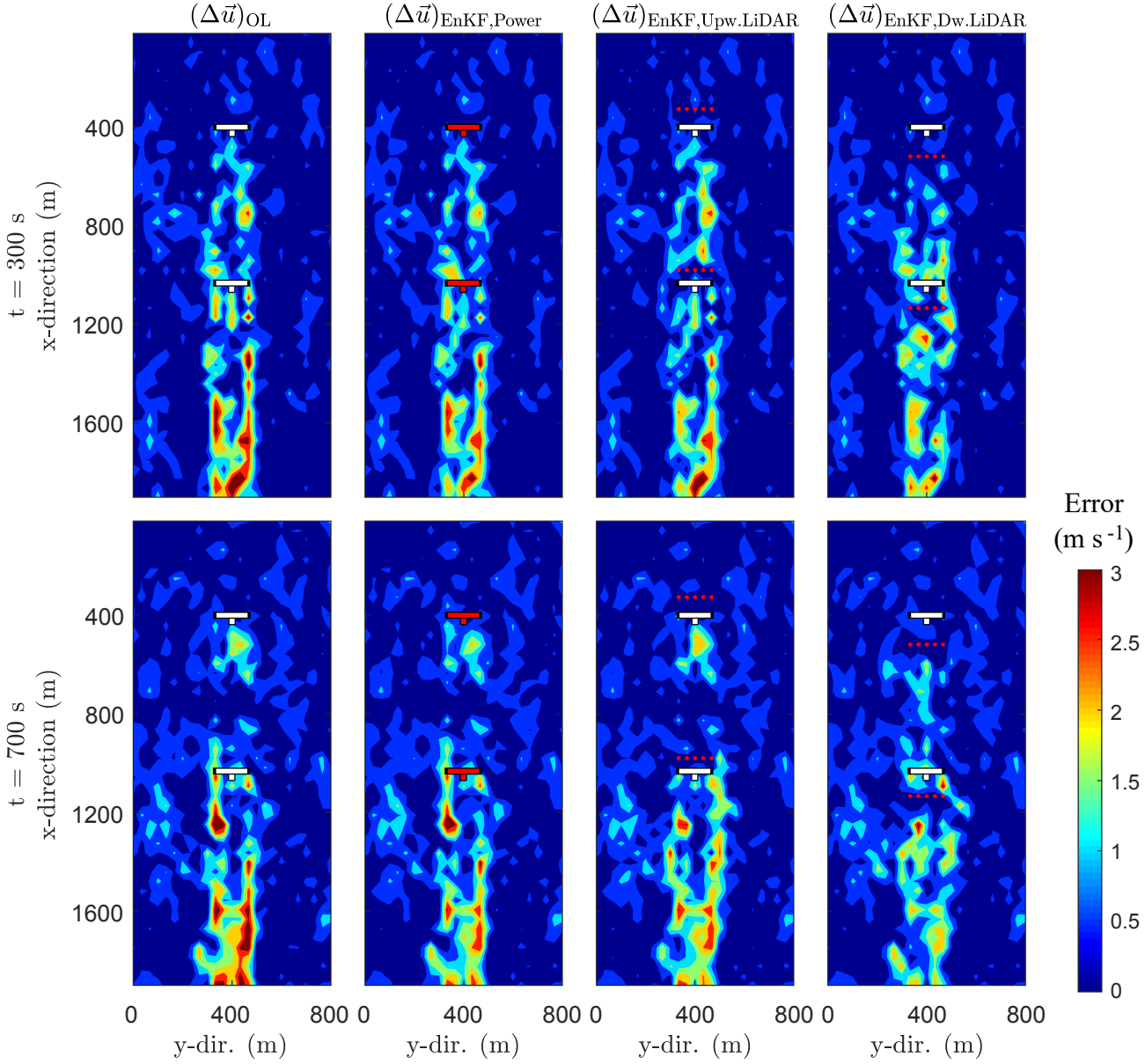
$(\Delta\vec{u})_{\mathrm{OL}}$
$(\Delta\vec{u})_{\mathrm{EnKF,Power}}$
$(\Delta\vec{u})_{\mathrm{EnKF,Upw.LiDAR}}$
$(\Delta\vec{u})_{\mathrm{EnKF,Dw.LiDAR}}$
t = 300 s
t = 700 s
x-direction (m)
400
800
1200
1600
0
400
800
y-dir. (m)
Error
(m s^{-1})
3
2.5
2
1.5
1
0.5
0