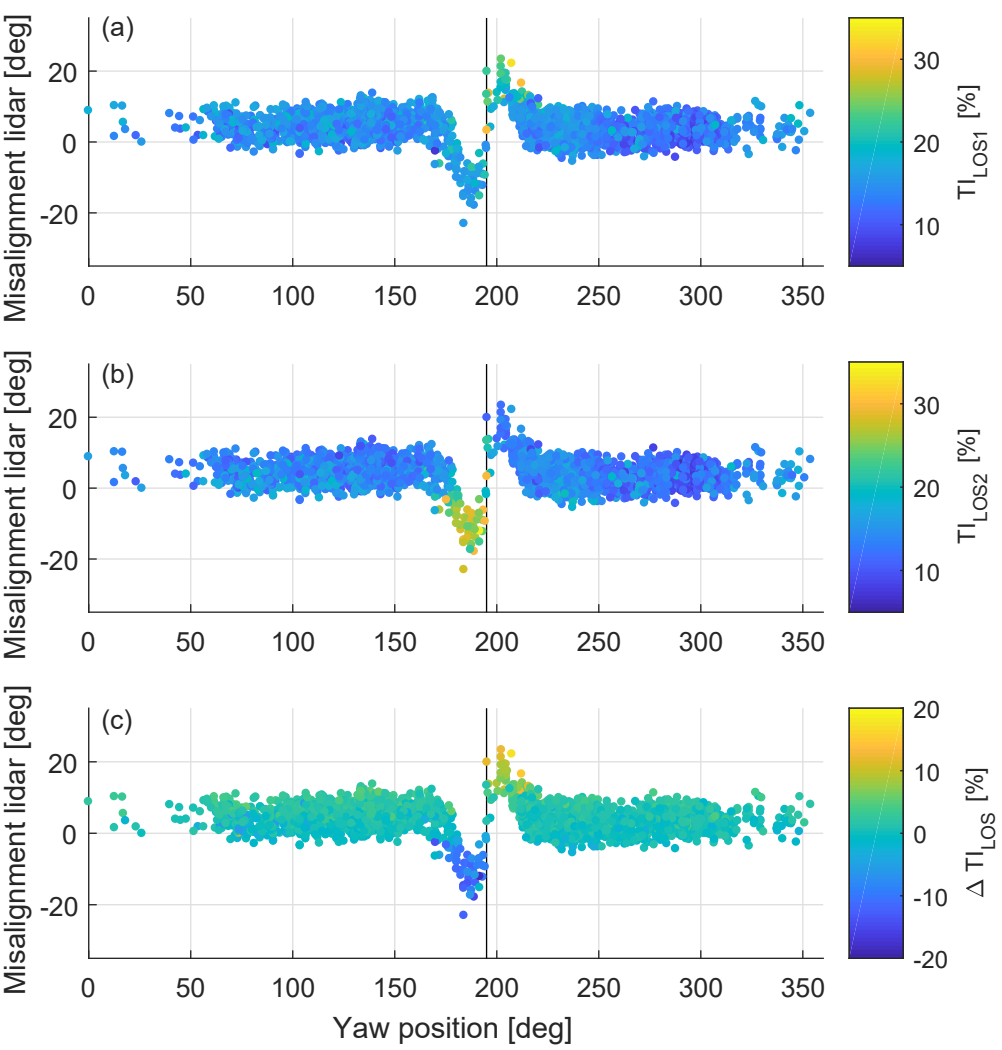
(a)
(b)
(c)
Misalignment lidar [deg]
Yaw position [deg]
TI_LOS1 [%]
TI_LOS2 [%]
Δ TI_LOS [%]