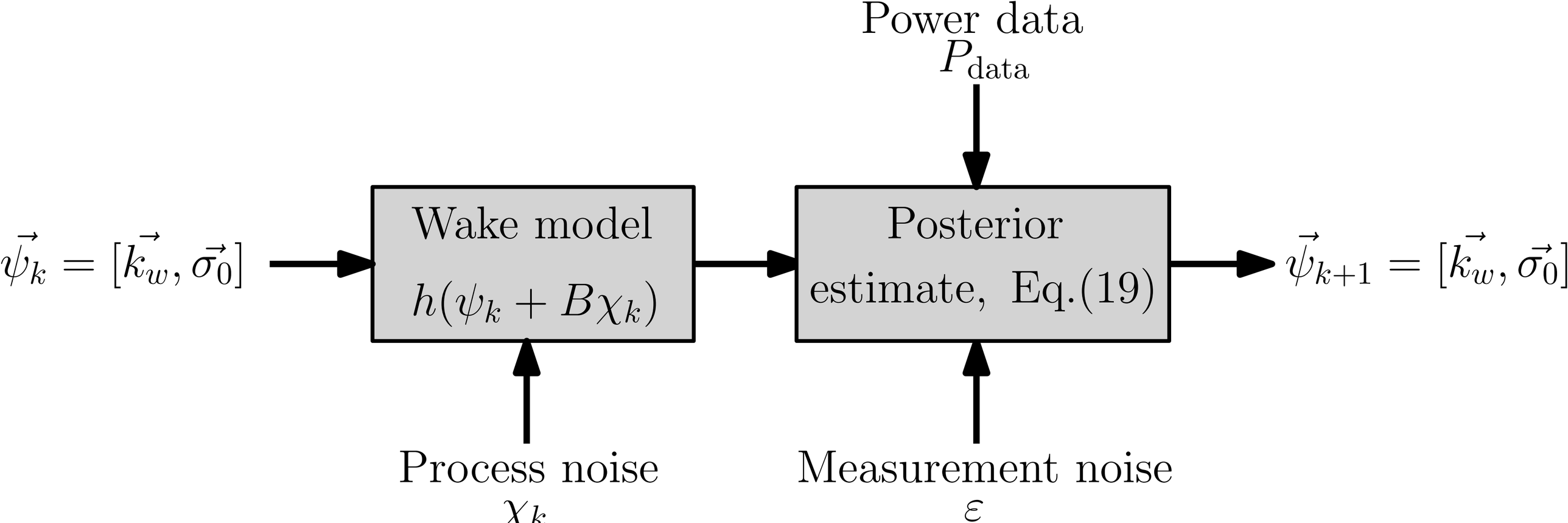
Power data
P_{data}
$\vec{\psi}_k = [\vec{k_w}, \vec{\sigma_0}]$
Wake model
$h(\psi_k + B\chi_k)$
Posterior
estimate, Eq.(19)
$\vec{\psi}_{k+1} = [\vec{k_w}, \vec{\sigma_0}]$
Process noise
χ_k
Measurement noise
ε