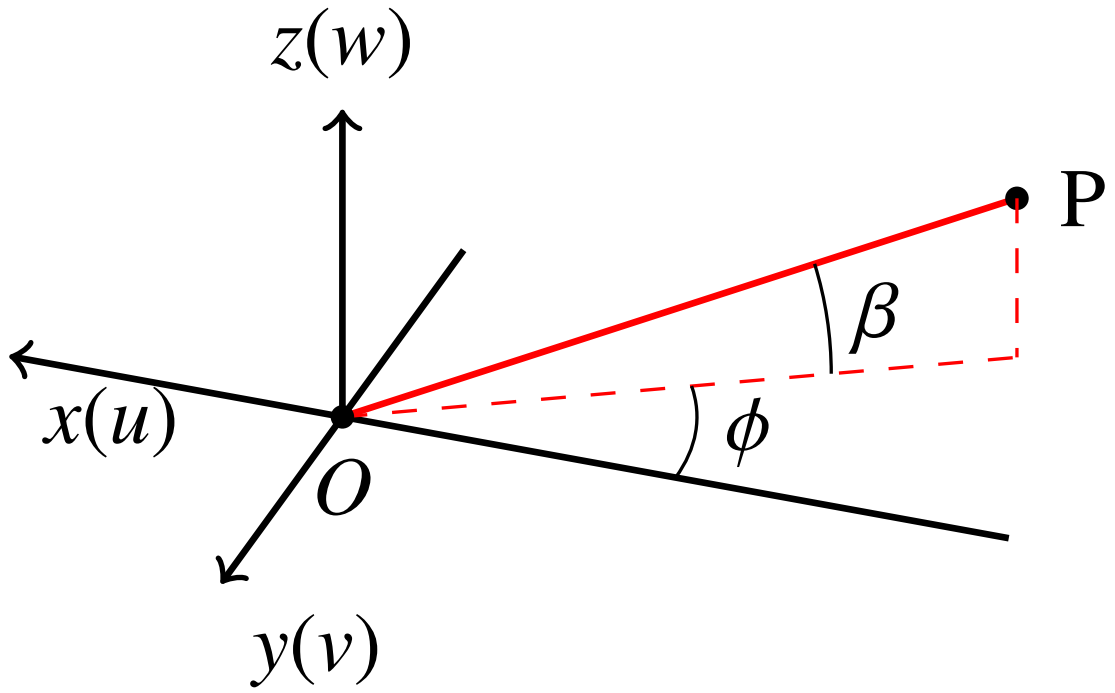
z(w)
P
β
x(u)
ϕ
O
y(v)