Effect of atmospheric stability on the wind resource extrapolating models for large capacity 1 wind turbines: A comparative analysis of power law, log law, Deaves and Harris model

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10 Abstract

2

11 To observe accurate wind climate from the available met mast measured wind data at different heights an accurate 12 wind shear model is necessary. Since WAsP and windPRO is software package which provides the better 13 representation of wind profile over homogeneous terrain only. Though, a separate module named as WAsP CFD has 14 been added in both of the software to predict correct wind resource in complex terrain also. Nowadays wind 15 resource assessment has been widely dependent on terrain and become a key issue for the researchers. It has been 16 found experimentally from earlier work that Deaves and Harris model shows better representation of wind profiles 17 on flat terrain at higher heights in comparison to other models such as the PL (power law), the LogL (log law) and 18 the LogLL (Log linear law). This study presents a comparative analysis of three different wind extrapolation 19 models. Based on 2 year measured wind data from the met mast the at 10 m, 50 m, 80 m, 100 m and 102 m heights, 20 results were compared in different stability classes using Monin-Obukhuv similarity theory. The RMSE (root mean 21 square error) and NRMSE (normalized root mean square error were found to be least in case of log linear model 22 which is 0.11 and 0.01784 respectively in compare to the PL and Deaves and Harris models.

23 Keywords: Atmospheric boundary layer, LIDAR, Monin-Obukhov length, Richardson Number, WAsP, 24 windPRO

25	Nomenclature	
26		
27	Abbreviations	
28	WT	Wind turbine
29	WAsP	Wind resource analysis and application programme
30	windPRO	Wind energy project design and planning
31	PL	Power law
32	LogL	Log linear law
33	ABL	Atmospheric boundary Layer
34	MOST	Monin-Obukhov similarity theory
35	LogLL	log-linear law
36	MLM	Maximum likelihood method
37	MMLM	Modified maximum likelihood method
38	Ri	Richardson number
39	CFD	Computational fluid dynamics
40	LIDAR	Light detection and ranging
41	PD	Panofsky and Dutton (PD) model
42		
43	Variables	
44	V	wind speed [m/s]
45	k	shape factor

46	с	size factor [m/s]
47	u*	friction velocity [m/s]
48	Zo	roughness length [m]
49	Κ	von Karman's constant (assuming 0.4)
50	L	Monin-Obukhuv length [m]
51	ρ	air density [kg/m ³]
52	C _p	specific heat at constant pressure [J/kg.k]
53	Н	sensible heat flux [k. m.s ⁻¹]
54	Т	temperature in Kelvin [k]
55	$\Phi_{ m m}$	Monin-Obukhov stability function
56	α	wind shear exponent
57	Vg	geostropic wind speed [m/s]
58	h	atmospheric boundary layer height [m]
59	f	Coriolis parameter [s ⁻¹]
60		
61	Statistical para	meter

62 total number of data n 63 number of measured data m 64 number of calculated data с 65 $\overline{m_i}$ mean of n measured values $\mu_{\rm m}$ 66 standard deviation of n measured values $\sigma_{\rm m}$ 67 μ_{c} $\overline{c_i}$ mean of n calculated values 68 standard deviation of n calculated values σ_{c} 69 RMSE root mean square error 70 NRMSE normalized root mean square error

71 1. Introduction

72 Accurate measurement of wind resource is necessary to project a wind farm. Earlier method uses cup anemometer 73 and wind vane to measure the wind velocity and direction. Due to advancement of wind power technology attention 74 of researchers had turned to increase the hub height. To measure the wind data at more than 100 m height by using 75 conventional method through met mast is now becoming the costly and time consuming process. Henry W. 76 Tieleman 2008 compared the observations from the power law, the logarithmic law and Deaves and Harris model in 77 terms of mean wind speed and turbulence intensity. At 10 m height non neutral thermal stability affects the wind 78 velocity profile and should not be neglected. Daniel R. Drew et. al. 2013 observed that Deaves and Harris wind 79 speed extrapolating model was found to be best fit at non equilibrium conditions in urban areas. Hideki Kikumoto 80 et. al. 2017 investigated the accuracy of wind speed measurement using the PL in low speed region. The results were 81 compared and analyzed with Doppler Lidar and ultrasonic measured wind data in the urban boundary layer of Tokyo 82 Japan. Nicholas J. Cook 1997 compared the wind speed profile with the power law and D&H. The D&H model 83 fitted the profile near the ground and top of the ABL due to satisfying the criteria of both boundary conditions. 84 Giovanni Gualtieri, Sauro Secci 2011 compared and investigated the accuracy of prediction of wind speed over a 85 flat and rough region at 10 m and 50 m height agl in which the role of atmospheric stability and surface roughness 86 had discussed. Giovanni Gualtieri 2016 had investigated the time varying relation of wind exponent with 87 atmospheric stability. The model was compared with the power law and found to be the finest and accurate approach 88 in terms of wind speed profile and energy yield calculation in neutral conditions. A number of equilibrium wind 89 speed model namely as the PL, the LogL and DH had been discussed by Davenport 1960; Simiu and Scanlan 1996; 90 Deaves and Harris 1978. Panofsky and Dutton 1984 and Elliott 1958 studied the effect of inner boundary layer with 91 a step change in surface roughness for the wind profile predictions. Deaves 1981 utilized the concept for 92 heterogeneous terrain in wind speed extrapolating methods. Giovanni Gualtieri 2017 tested and compared the DH

- 93 model with the PL with all stability conditions. The DH model found to be best fitted and tuned and its accuracy
- seems to be increased with height from 80 m to 140 m agl. Due to increasing demand of energy, wind resource
- 95 prediction has become a crucial issue markedly for energy investors to accurately analyze the wind speed at different
- hub height of wind turbine. It is essential during the feasibility study to abate the cost of wind farm installation.
- 97 There are many researchers who worked on different wind extrapolating models such as the PL, the LogL, the
- LogLL and DH. Every model has its own significance and assumptions depending on the type of terrain where wind
 speed has to be predicted. Sharma et. al. 2014 had optimized 150 m higher wind monitoring tower using ANSYS.
- 100 Sharma et. al. 2014 extended earlier work with the incorporation of nano and piezoelectric materials in their design.
- 101

102 2. Wind Profile extrapolating models

103 It was the first time when, Davenport 1960 originally proposed the PL for the purpose of designing the wind load 104 especially in structural engineering. Due to the simplicity of the PL model which can be applied to larger height in 105 compare to the logarithmic law subjected to various terrain conditions as per Counihan, 1975. Following models had 106 been generally adopted for the wind profile predictions under certain assumptions:

107 2.1 Deaves and Harris (D&H) model

108 This model was developed in two stages in strong wind conditions. In the first stage it was developed for the ABL in 109 equilibrium over uniform roughness and in the second stage to account for multiple step changes in roughness. The 110 model was further developed to different kind of heterogeneous terrain. UK, Australia and New Zealand have

adapted this model into its wind design codes. If u_* is the friction velocity, k is the von Karman constant = 0.4), z_0 is

112 the roughness length, h is atmospheric boundary layer height then velocity v has been defined as:

113 The D&H model is also known as "logarithmic with parabolic defect" speed profile equation:

114
$$V = \frac{u_*}{k} \left[\ln \frac{z}{z_0} + 5.75 \left(\frac{z}{h} \right) - 1.88 \left(\frac{z}{h} \right)^2 - 1.33 \left(\frac{z}{h} \right)^3 + 0.25 \left(\frac{z}{h} \right)^4 \right]$$
(1)

115
$$h = \frac{u_*}{6 f}$$
 (2)

here, f is the Coriolis factor which depend on the site latitude angle. The extended model of D&H with step changein roughness had been given the concept of transition from outer and inner boundary layer. It is described as:

118
$$u_{*,inner} = u_{*,outer} \left[1 - \frac{\ln \left(\frac{z_{0,outer}}{z_{o,inner}} \right)}{0.42 + \ln m_o} \right]$$
 (3)

119
$$m_0 = \frac{0.32 X}{z_{o,inner} (\ln m_o - 1)}$$
 (4)

120 X is the downward distance towards the change in surface roughness and m_0 is the constant parameter.

121

122 As per similarity theory,

123
$$\frac{V}{u_*} \cong \frac{1}{k} \ln\left(\frac{z}{z_o}\right) \text{ when } z \cong h$$
 (5)

124
$$V \to V_G \text{ and } \frac{dV}{dz} \to 0 \text{ as } z \to h$$
 (6)

125 V_G stands for the geostrophic wind speed satisfies the criteria of upper and lower boundary conditions to the ABL. 126 Geostrophic wind speed calculated when the thermal flux generated by the heat and friction are equal.

127 2.2 Log- Law model

128 The log law model was derived from Eq. (5) and holds over a ground surface:

$$129 \qquad V = \frac{u_*}{k} \ln(\frac{z}{z_o}) \tag{7}$$

130 It is clear from Eq. (7) that log law satisfies the lower boundary conditions only not the upper one. Typically, it has131 been found that the power law does not fit well at the higher height ranger (typically more than 150 m).

132 2.3 Power law model

133 The wind speed at a height z uses the empirical formula:

134
$$\frac{V}{V_{ref}} = \left(\frac{z}{z_{ref}}\right)^{\alpha}$$
(8)

here, V_{ref} refers to the wind speed at the height say z_{ref} . The Power law indicates the increment of surface wind speed with respect to height z. The PL neither satisfies the upper boundary nor the lower boundary conditions. In comparison to log law model it fits well for the wind speed profile at larger height, which is one of the critical reason for its preference. Though, it had not been recommended to use it very close to the ground. Most of the research matched well with the PL over the height value from 30 m to 300 m a.g.l. The value of α varies with respect to wind speed, height and surface roughness. In practice, the wind shear exponent α often assumed as equivalent to the aerodynamic roughness length z_0 .

142 2.4 Estimation of Monin-Obukhov length

143 The turbulence within the surface boundary layer is defined by Monin- Obukhuv length scale L as:

$$L = -\frac{\rho C_p T u_*^3}{k.e.H}$$
(9)

where ρ stands for air density at temperature T, C_p is the specific heat at constant pressure, k is the Von Karman constant u_{*} is the friction velocity and H is the sensible heat flux. The Monin- Obukhuv length scale L can be calculated by computing the Bulk Richardson number which requires only single wind speed and temperature measurements at two heights. Gradient and bulk Richardson number can be defined as:

149
$$R_{i} = \frac{g\Delta z\Delta\theta}{\theta_{1}\Delta u^{2}}$$
(10)

150 where $\Delta \theta = \theta_2 - \theta_1$, $\Delta z = z_2 - z_1$ and $\Delta u = u_2 - u_1$ are the measured parameter at two height. When the temp. and wind 151 speed measurement is available only at single height (Barker and Baxter, 1975)

152
$$R_{ib} = \frac{gz_2 \Delta \theta}{\theta_2 u_2^2}$$
(11)

153
$$\varepsilon = \frac{\Psi m}{\omega_b} R_i$$
 (Businger et.al., 1971) suggested (12)

154 $\frac{\bar{z}}{L} = \varepsilon$, \bar{z} stands for geometrical mean height of z_1 and z_2 , and φ_m and φ_h are the non dimensional functions related to 155 Wind shear and temperature gradient, as per (Dyer, 1974) φ_m and φ_h :

156
$$\varphi_{\rm m} = \begin{cases} \left(1 - \gamma \varepsilon\right)^{-\frac{1}{4}}, \ \varepsilon < 0\\ \left(1 + \beta \gamma\right), \ \varepsilon \ge 0 \end{cases}$$
(13)

157
$$\varphi_{h} = \begin{cases} R \left(1 - \dot{\gamma} \epsilon \right)^{\frac{1}{2}}, \ \epsilon < 0 \\ (R + \beta' \gamma), \ \epsilon \ge 0 \end{cases}$$
 (14)

(Binkowski, 1975) found the following results, the function based on two stability conditions

159
$$\epsilon = \begin{cases} \frac{R_{i}}{R} \left(1 - \dot{\gamma}R_{i}\right)^{\frac{1}{2}} / \left(1 - \dot{\gamma}R_{i}\right)^{\frac{1}{2}} & R_{i} \leq 0 \\ \frac{R_{i}}{\frac{R_{i}}{R}} & 0 < \frac{R_{i}\beta^{2}}{\beta} & <1 \end{cases}$$
(15)

161
$$\bar{z} = \frac{z_1 + z_2}{2}$$
, \bar{z} is the mean height (16)

162
$$\frac{z_2}{L} = \frac{kR_{ib}F^2}{C}$$

163
$$F = \frac{u}{u_{+}} \begin{cases} ln\left[\left(\frac{z_{2}}{z_{0}}\right)\left(\frac{\eta_{0}^{2}+1}{\eta_{2}^{2}+1}\right)\left(\frac{\eta_{0}+1}{\eta_{2}+1}\right)^{2}\right] + 2 \tan^{-1}\left(\frac{\eta_{0}-\eta_{2}}{1+\eta_{0}\eta_{2}}\right), \quad L \leq 0 \end{cases}$$
(18)

(17)

163
$$F = \frac{1}{u_*} \left\{ ln\left(\frac{z_2}{z_o}\right) + \frac{\beta z_2}{L}, \qquad L \ge 0 \right\}$$
164 L depends upon two stability conditions (1)

164 165

166

$$G = \frac{\Delta \theta u_*}{(-w'\theta')} = \begin{cases} R \ln \left[\left(\frac{z_2}{z_0} \right) \left(\frac{\lambda_1 + 1}{\lambda_2 + 1} \right)^2 \right] \right], \quad L \le 0 \\ R \left[\ln \left(\frac{z_2}{z_0} \right) + \frac{\beta'(z_2 - z_1)}{L} \right], \quad L \ge 0 \end{cases}$$
(19)

167
$$\eta_2 = (1 - \gamma z_2 / L)^{\frac{1}{4}}_{1}$$
 (20)

168
$$\eta_0 = (1 - \gamma z_0 / L)^{\frac{1}{4}}$$
 (21)
169 $\lambda_0 = (1 - \gamma z_0 / L)^{\frac{1}{2}}$ (22)

109
$$\lambda_1 = (1 - \gamma z_1 / L)^2$$
 (22)
170 $\lambda_2 = (1 - \gamma' z_2 / L)^{\frac{1}{2}}$ (23)

171 Where
$$\eta_2 \eta_0 \lambda_1 \lambda_2$$
 are the function of Monin- Obukhuv length L. G is the function of Ri and mean gradient height z
172 F stands for logarithmic function of speed and friction velocity.
173

174 **3.** Observation and site details

Jamgodrani hills have a huge potential in terms of power production. The 100m mast is located in District Dewas at Jamgodrani Hills. The elevation of the mast location is 573m above mean sea level. Site coordinate has been converted into UTM (Universe Transverse Mercator) system to perform line and area roughness calculation purpose using WAsP and windPRO. There were five wind anemometers and wind vane had mounted on the mast to measure wind speed and direction respectively. To verify the Monin- Obukhuv Similarity theory two temperatures and one pressure sensor had also installed. Table 1 and Fig.1 shows the mast details and location respectively.

181 Table 1 Site Details

Site Coordinate	(E)Longitude- 76°09'2.50"		
	(N) Latitude- 22°58' 58.20"		
	UTM-2542426 N, 619480 E		
Duration	2015 to 2017		
Site name	Jamgodrani Hills		
District	Dewas		
State name	Madhya Pradesh		
Mast Height	100m		
Elevation	573mAMSL		
Location of Anemometer	10m, 25m, 50m, 80m, 100m.		
Location of Wind vane	10m, 25m, 50m, 80m, 100m		
Location of Pressure sensors	2m, 10m		
Location of temperature sensors	2m, 10m		



183

185

184

Fig. 1 Met mast location (The point shows the met mast location, Source Google Earth)

Weibull parameter (k and c) was calculated by two different methods namely as MLM and MMLM. It is very much
clear from the Table 3 in compare to Table 2 Weibull parameter are more than Table 2. Experimentally, it has been
found that the Weibull parameters calculated y the MMLM provides more accurate results in comparison to MLM.
MLM is a widely accepted method to estimate the Weibull parameter. It requires more extensive mathematical
calculations. In the first step k is calculated by using the following equation.

191
$$k = \left(\frac{\sum_{i=1}^{n} v_{i}^{k} \ln(v_{i})}{\sum_{i=1}^{n} v_{i}^{k}} - \frac{\sum_{i=1}^{n} \ln(v_{i})}{n}\right)^{-1}$$
(24)

192
$$c = \left(\frac{1}{n}\sum_{i=1}^{n} v_{i}^{k}\right)^{\frac{1}{k}}$$
 (25)

193 n stands no of observation of zero wind speed and $v_i i_{th}$ operation wind speed.

194

195 This method is similar to MLM and estimated by iteratively using the following two equations. It is used when wind 196 data is available in frequency distribution form. If v_i is the wind speed related to bin i, $f(v_i)$ is the frequency range 197 within the region of bin i, n is the total no of bins and $f(v \ge 0)$ is the probability of wind speed.

198
$$k = \left(\frac{\sum_{i=1}^{n} v_{i}^{k} \ln(v_{i}) f(v_{i})}{\sum_{i=1}^{n} v_{i}^{k} f(v_{i})} - \frac{\sum_{i=1}^{n} \ln \mathbb{E} v_{i}}{f(v \ge 0)}\right)^{-1}$$
(26)

199
$$c = \left(\frac{1}{f(v\geq 0)}\sum_{i=1}^{n} v_i^k\right)^{\frac{1}{k}}$$
 (27)

200 Table 2 Weibull parameter by MLM

100m		00m 80m		50m		10m	
k	с	k	с	k	с	k	с
2.24	7.131	2.219	6.70	2.3621	6.25	2.164	4.193

201

203 Table 3 Weibull parameter by MMLM

100m		80m		50m		10m		
k	с	k	с	k	с	k	с	
2.431	7.67	2.42	7.24	2.57	6.78	2.45	4.736	

*Roughness length=0.3183m, *Class= 2.8

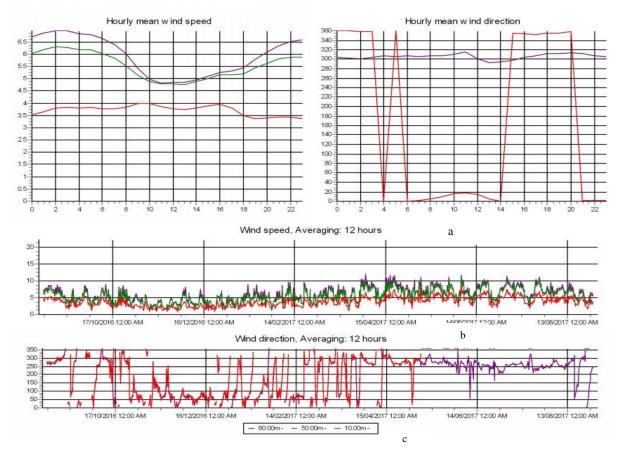
205 4. Result & Discussion

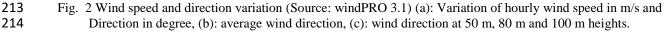
Annual mean wind speed and mean turbulence intensity is calculated at different heights from ground level. It is
 clear from Table 4 that the annual wind speed increase with respect to height, but mean turbulence intensity
 decreases. Due to more predominate viscous and obstruction effect near the ground level wind turbulence is more.
 Turbulence intensity seems to be decreases with the height due to decrease in surface shear stress.

210 Table 4 Wind characteristics

AMWS (Ar	nual Mean win	d speed) in m/s	3	Mean turbulence intensity (TU)			
100 m 80 m 50 m 10 m				100 m	80 m	50 m	10 m
6.32	5.93	5.53	3.71	0.124	0.143	0.150	0.24

211





- The hourly variation of wind speed and direction has been shown in Fig. 2 at 10 m, 50 m and 80 m height
- respectively. Blue shown in Fig. 2 signifies the wind speed and direction at 100 m hub heights. Weibull parameters
 have been divided into 12 sectors with the given direction and typically illustrated in Fig.3 and Fig. 4 respectively at
- 218 80 m and 10 m height respectively.

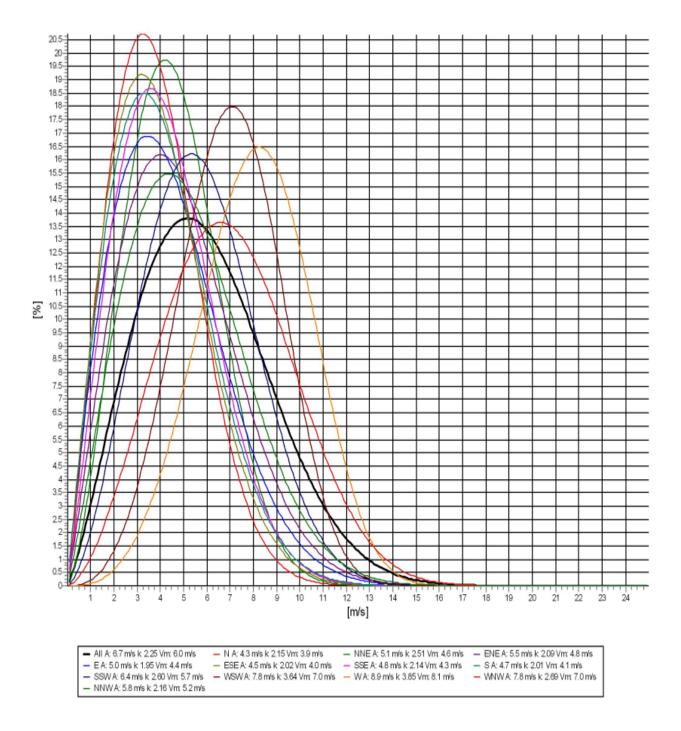
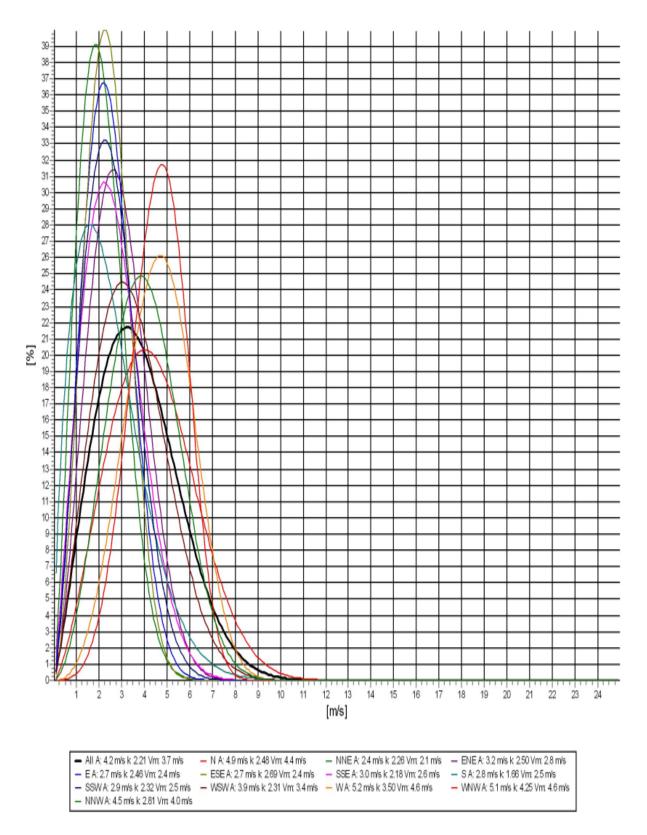




Fig. 3 Sector wise Weibull parameter distribution at 80m height a.g.l. (Source: windPRO 3.1)



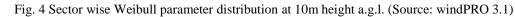


Fig.3 and Fig. 4 shows the sector wise distribution of Weibull parameter at 80m and 10m height respectively.



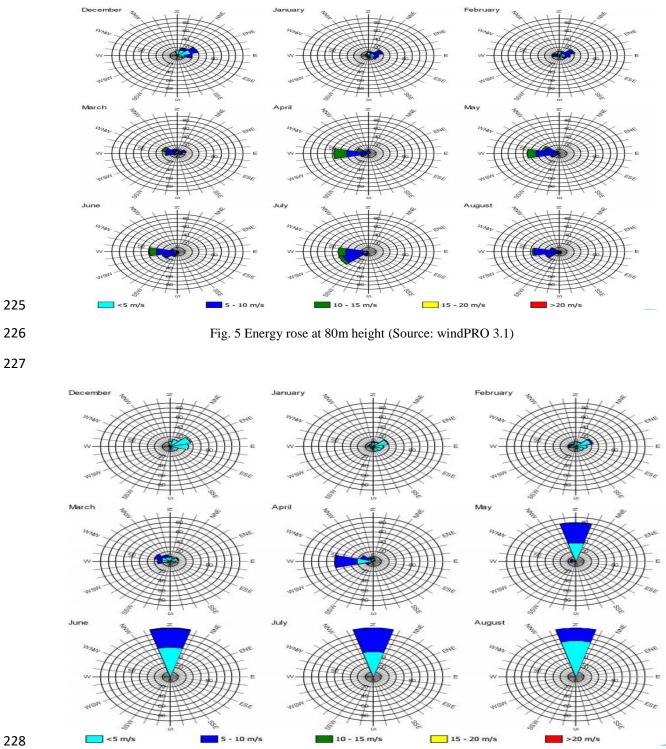




Fig. 6 Energy rose at 10m height (Source: windPRO 3.1)

- 230 In Fig. 5 (April month) upto 20m/s wind speed has been shown, which produces maximum power density at 80m
- height. While Fig. 6 indicates that the maximum wind speed can be utilized for the power production is 3 -5 m/s at
- 232 10m height. The measured wind speed at 10m a.g.l. can be taken as reference purpose. Further Wind speed has been
- extrapolated using the PL from 50m to 100m and 80m to 100m by $\alpha_{10.50} = 0.2483$ and $\alpha_{50.80} = 0.1474$ respectively.
- By taking the surface length of $z_0 0.3183$ m, von karman factor 0.4 and friction velocity u* 0.4316 m/s the wind
- speed can be found using the LogL at 100m a.g.l as 6.20m/s.

The Monin- Obukhuv Length similarity had been applied at Jamogadrani hills which predict that the atmosphere is
 strongly stable and wind speed using D&H model found to be 6.68m/s. The Richardson Number is 0.35614 which

- has been used to calculate Monin-Obukhuv scale.
- 239

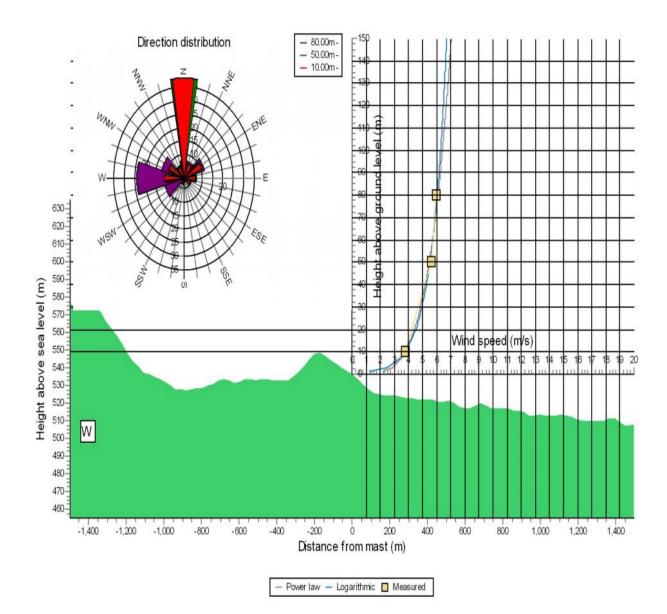




Fig. 7 Mean wind profile using power law and LogL respectively

242 Table 5 Comparative analysis between different models

Parameter/Results	Predicted by PL	Predicted by PL	LogL	D&H model
	$(\alpha_{10-50} = 0.2483)$	$(\alpha_{50-80} = 0.1474)$		
Wind speed in m/s	6.580	6.135	6.204	6.681
RMSE	0.26398	0.18085	0.111701	0.36485
NRMSE	0.04094	0.02905	0.017842	0.056139

243

It is clear from Table 5 that Log law fitted and best matches the wind profile. RMSE and NRMSE found to be least

in case of Log low in compare to PL and D&H model. The actual measured wind speed by wind anemometer is 6.32
m/s at 100m a.g.l. It can be seen from Fig. 7 that the accuracy of the LogL increases from the height above 80m
a.g.l.

249 5. Conclusion

To validate its reliability as a wind speed prediction extrapolations tool for addressing MW WTs, the PL, LogL and D&H model was assessed at hub heights at 10 m, 50 m, 80 m and 100 m. Based on a 2 year wind data of 10 min. observations including temperature and pressure data from the met mast of Jamgodrani hills, all models were compared. The application of models were required prior assessment of sites surface parameter such as α for power law, friction velocity and surface length for Log law and Coriolis factor, ABL height for D&H model. Though, D&H model was actually developed for strong wind conditions subjected to neutral conditions, it was forced to applied for all stability regions.

257 The RMSE and NRMSE were found to be least for the PL, the LogL, Deaves and Harris model upto height 80m

a.g.l. within the extrapolating range. The result seems to the LogL capability of best producing at higher level.

259 Since, this model has been found to be suitable for strong adiabatic conditions. However, the overall accuracy of

LogL model during these conditions should be chosen as a model's key factor. Practically, in Indian conditions the DH model could not fit appropriate due to two limitations: i) reliable friction observation ii) accurate site's surface

262 length assessment. Since, the value of Z_0 has the major effect on DH model.

263 Based on 10 min. wind speed, pressure and temperature data the minimum RMSE and NRMSE found to be 0.11 and

264 0.01 respectively. The PL exhibited the more accuracy across all extrapolations ranges and for all stability criteria,

which is used particularly in predicting wind speed profile variation. Currently, obtained results strongly encourage

- further uses of the PL, which would be deemed as a future research topic from a wind energy scenario. At
- 267 Jamgodrani hills, the LogL proved to be the finest in prediction the extrapolated wind speed, thus supporting its
- validity over the entire ABL.

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