



**Figure 21.** Wind turbine power production from LES  $P$  and wake model  $\hat{P}$ .  $P_{1,baseline}$  is the LES power production for the leading upwind turbine from control update step 1 where the wind farm is operated with the greedy baseline control.  $\hat{P}_{baseline}$  is the wake model fit to  $P_{baseline}$  using EnKF estimation.  $P_{yaw}$  is the LES power production for control update step 2 with yaw misalignment incorporated.  $\hat{P}_{yaw}$  is the wake model prediction of  $P_{yaw}$  using  $k_w$  and  $\sigma_0$  fit based on control update step 1 and with the optimal yaw misalignment angles which were implemented by control update step 1. The wake model estimate for  $P_p$ , given by  $\hat{P}_p$ , is (a)  $\hat{P}_p = 2$ , (b)  $\hat{P}_p = 3$ , and (c)  $\hat{P}_p = 4$ . The error bars represent 1 standard deviation in the power data as a function of time. The subscript “f” denotes power predictions from the FLORIS wake model (Annoni et al., 2018) with the Gaussian wake model (Bastankhah and Porté-Agel, 2014) and model parameters prescribed by Niayifar and Porté-Agel (2016).