Point-to-point reply to reviewers

Paper wes-2025-120 Title:

Large Eddy Simulation of the IEA 15-MW Wind Turbine Using a Two-Way Coupled Fluid-Structure Interaction Model

September 26, 2025

The authors wish to thank the reviewers for their comments and suggestions on the paper to enhance the manuscript. The paper has been revised accordingly. The revised parts have been highlighted in red in the updated manuscript. If mentioned, the page number refers to the revised paper. In the following we report point-to-point replies concerning the questions and comments raised by the reviewers.

Reviewer #1

Main Critique Points

Documenting the software and its validation status.

• As a reader, I found it a bit hard to trace how the different pieces of your in-house UTD-WF framework were developed across prior work, and what has been validated under which conditions. This is important to know that the in-house code you use - i.e., the foundation for all your work and insights - is credible and correct in the first place. Adding a short provenance/validation paragraph would strengthen the manuscript.

A paragraph about the provenance of the in-house code and the validation of its different version has been now added at the beginning of Section 2.1.1 (red paragraph on page 4).

- Clarifying which subsets constitute formal validation would help readers map prior evidence to your present setup. In that light, two clarifications would make your contribution easier to interpret:
 - 1. Scope of prior validation vs. present cases: Prior validations include uniform and ABL inflows for a 5 MW turbine; your study addresses the IEA-15 MW case for a sheared laminar inflow configuration. Since larger rotors can amplify aeroelastic effects, it would be helpful to note explicitly that the present application extends the validated setting and to discuss any implications or arising uncertainties.

We have now included a small paragraph discussing this important point in Section 2.1.1 (last lines of the red paragraph on page 4). In particular, the added lines are as follows: "Notice that prior validations by (Della Posta et al. 2022) of the CFD-CSD solver were made on a laminar uniform and a turbulent sheared inflows for a 5 MW NREL turbine, whereas our study extends the validated setting to the IEA-15 MW case for a sheared

laminar inflow configuration. However, as discussed in the framework of the IEA Wind TCP Task 47 (Cacciola et al., 2025), turbulent fluctuations appear to have a much stronger impact than shear on load response of aero-elastic numerical codes. Moreover, high-fidelity codes appear rather consistent in predicting loads, while engineering models tend to overpredict fatigue loads, particularly for large rotors".

2. Citations for solver provenance: Where you cite the solver's origin, consider also referencing Santoni et al. (2015) as the first UTD-WF publication, prior to Santoni et al. (2020). Further mentioning the following papers and validations that were added to Santoni et al. (2015) would help readers that are unfamiliar with the code's history. Just so they know that the inhouse code you use is validated within a certain range.

We have now used Santoni et al. (2015) as first reference to the in-house code.

Comparing BEM with CFD for aeroelastic simulations

- The conclusions drawn about the relative suitability of CFD-based versus BEM-based aeroelastic simulations are not entirely straightforward, because the setups being compared differ in more than one respect. In particular:
 - Case A (CFD-CSD) couples a finite-volume LES solver with ALM to a linear structural model (A.1: OV; A.2: TN).
 - Case B (OpenFAST with BeamDyn) uses BEM aerodynamics with a nonlinear structural solver.
 - Case C (OpenFAST with AeroDyn/ElastoDyn) combines BEM aerodynamics with a linear structural solver.

Because both the aerodynamic and structural solvers vary simultaneously, it is difficult to isolate whether observed differences stem from the flow solver or from the aeroelastic solver (or from their specific implementations). Any causal conclusions should therefore be presented with appropriate caution.

At the beginning of section 4.2, we added as a preliminary comment the following sentence: "It is important to note that the four solvers employed differ in both their aerodynamic and structural modeling approaches. As a result, it is not always possible to unambiguously determine whether the observed discrepancies in the results originate from the fluid-dynamic models or from the structural formulations."

Moreover, We have rephrased all along the paper and in the Conclusions section, several sentences providing causal conclusions drawn by the comparison between these codes.

• A related point concerns the comparison with Bernardi et al. (2023). That study focused on a different turbine (NREL 5 MW), under uniform inflow, and reports blade load distributions that do not match those of the present paper. Drawing direct inferences from those results to the IEA 15 MW case with sheared inflow is thus challenging, as multiple differences may drive the discrepancies. In addition, the current manuscript discusses the 5 MW results extensively without showing them, requiring the reader to switch between papers to follow the discussion. To strengthen this part, I would suggest either limiting the cross-paper comparison, or alternatively presenting a direct comparison in the present manuscript — for instance, by reproducing a nondimensionalized plot from Santoni et al. (2017) in a comparable format that allows readers to interpret the differences more clearly.

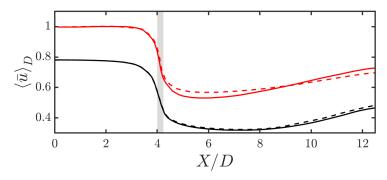


Figure 1: Rotor-averaged velocity along the streamwise direction normalized by the undisturbed velocity at the rotor height, namely, $U_{\infty} = 10 \ m/s$, for the present data (black curves) and the work of [1] (red curves). The grey region represents the area covered by the rotor. (RO ----, TN —).

As suggested by the reviewer, we have included in figure 4 of the revised paper, reported here for completeness, a reproduction of the nondimensionalized plot from Santoni et al. (2017) in a comparable format that allows the reader to interpret the differences more clearly. Moreover, we have eliminated some comparison with the 5MW turbine results in the conclusions.

Convergence study

• The grid convergence section currently relies on only two simulations. While this gives a first impression, two points are generally not sufficient to establish a clear convergence trend. I would therefore suggest either adding at least one additional grid resolution to demonstrate a systematic trend, or explicitly referring to convergence studies from previous publications with a closely similar setup.

Following the suggestion of this referee, we have added a computation with a coarser grid, consisting of 1.3×10^8 grid points. The outcome of the simulation in terms of angle of attack, forces and momentum is provided in Figure A.2 (page 25). All quantities are found to compare rather well, as discussed in the manuscript.

• In addition, the statement "the results obtained using the coarse and fine grids are extremely close ... the curves of the angle of attack are almost indistinguishable" comes across as rather qualitative. It would strengthen the section to include a more quantitative measure of convergence (e.g. RMS difference, maximum deviation along the span, or an error norm), so readers can assess the actual magnitude of the differences. Further, the figure of the angle-of-attack comparison in the grid comparison study would be much more clear if it would be scaled to include a maximum angle of 15 degrees. The angles of attack on the cylindrical root section are not of interest to the reader.

We have included in the discussion a quantitative measure of convergence, in particular the absolute and relative errors on the angle of attack at 80% of the span. Further, following the suggestion of the referee, the figure of the angle-of-attack comparison in the grid comparison study has been scaled to include a maximum angle of 15 degrees.

• Tip-loss models: I also noticed that different formulations of the tip-loss model are used across the compared solvers. Specifically: OpenFAST applies the classical Prandtl tip and root loss correction (line 222). The CFD-CSD solver employs the [2] correction (line 144). Since the Shen formulation is not equivalent to the standard Prandtl approach, the choice of model may

itself contribute to differences in the results. For the sake of a fair comparison, you could report clearly which correction is applied in detail in each case and provide the coefficients used in the Shen model. This would make the comparison more transparent to the reader.

Indeed OpenFast and the CFD-CSD code use two different tip-loss models, but we have used a cross-code calibration to set the coefficients of our model to match the forces close to the tip reported by OpenFAST, which uses the Prandtl model. Concerning the tip-loss model used for the CFD-CSD code, we have used the Shen model, whose coefficients c_1 and c_2 have been set in the following way. In particular, c_1 has been set to the value reported in the Shen 2005 paper ($c_1 = 0.125$), which is based on a comparison with experimental distributions of normal forces near the tip for the NREL rotor at a wind speed of $10 \, m/s$, and a tip speed ratio of 3.79. Whereas, the second coefficient has been increased with respect to the value reported by Shen (2005), after a calibration of the coefficient to match the forces close to the tip reported by OpenFAST for the same turbine and flow case, leading to the choice of $c_2 = 32$. A comment has been added to the manuscript reporting these details.

Detailed Critique Points

2 Methodologies

- 2.1 CFD-CSD Solver
 - L. 121: The subsection caption currently reads "2.1 CFD-CSD solver". From what I know, subsection titles should follow a consistent style. Please either use title case throughout (e.g., "2.1 CFD-CSD Solver") or sentence case consistently. At present, there is a mix (for example, "4 Results and Discussion" in title case versus "3 Flow and structural setup" in sentence case). Perhaps also check the WES journal guidelines, whether to use title or sentence case.

Looking at the journal guidelines, it is stated that "Titles and headings follow sentencestyle capitalization i.e. first word and proper nouns only". Thus, we now used the sentence style, not capitalizing the first letter of nouns. This has been now done throughout the paper, in a consistent way.

- L. 123-125: The text states: "The simulations of the flow around the wind turbine are carried out through Large-Eddy Simulations (LESs) of the incompressible, filtered, 3D Navier-Stokes equations, employing our in-house UTD-WF solver (Santoni et al., 2020)." To my understanding, the first introduction of the UTD-WF code was actually in Santoni et al. (2015), "Development of a high fidelity CFD code for wind farm control". The 2020 paper (Santoni et al., 2020) applies the solver at wind farm scale, but the code originates from the earlier work. Since UTD-WF is not as widely established as solvers like OpenFOAM, it would strengthen the methodology section if you also reference publications where the solver has been validated against either an established CFD solver of similar fidelity or experimental data.

We have now included more extensive comments concerning the validation of the code, both at the beginning of Section 2.1.1 and in the two validation Appendices (A.1 and A.2).

- L. 138: The manuscript currently cites Troldborg (2009) for the Actuator Line Method (ALM). A more appropriate primary reference would be Sørensen and Shen (2002), who first introduced the ALM. Thank you for the suggestion, now we have included Sørensen and Shen (2002) as primary reference.

- L. 144: You mention comparing the Shen tip-loss correction with the Prandtl tip-loss model. Could you please specify the chosen free parameters in the Shen model? It would also help to clarify how you ensured that both tip-loss approaches are consistent, so that observed differences in results are not simply due to discrepancies between the models themselves.

As reported above, the coefficient c_1 of the Shen model has been set to the value reported in the Shen 2005 paper ($c_1 = 0.125$), which is based on a comparison with experimental distributions of normal forces near the tip for the NREL rotor at a wind speed of 10m/s, and a tip speed ratio of 3.79. Whereas, the second coefficient has been increased with respect to the value reported by Shen (2005), after a calibration of the coefficient to match the forces close to the tip reported by OpenFAST for the same turbine and flow case, leading to the choice of $c_2 = 32$.

- L. 159-160: The structural model is attributed to Della Posta et al. (2022, 2023). To provide readers with a clearer overview of how the full solver framework was assembled, it would be useful to briefly note the sequence of developments: Santoni et al. (2015): introduction of the ALM-LES flow solver (UTD-WF), Santoni et al. (2017): tower-nacelle representation using the immersed boundary method, Della Posta et al. (2022): coupling of the aeroelastic solver, Della Posta et al. (2023): implementation of the unsteady aerodynamics model (Leishman-Beddoes dynamic stall). You might phrase it along the lines of: "The structural model used in the present study builds upon the UTD-WF framework progressively developed in Santoni et al. (2015, 2017) and further extended by Della Posta et al. (2022, 2023), where the aeroelastic solver and the Leishman-Beddoes dynamic stall model were implemented."

This suggestion has been implemented at the beginning of section 2.1.1 of the new version of the paper.

3 Flow and Structural Setup

• L. 235: The subsection caption currently reads "3 Flow and structural setup". For consistency with the other section titles, the first letter of nouns should be capitalized (e.g., "3 Flow and Structural Setup"). Please check the WES journal guidelines and apply the chosen style consistently throughout.

This has been now done throughout the paper, in a consistent way.

• L. 248-249: The text states: "The turbine location is 4 diameter units from the inlet and centered in the spanwise direction." Could you please elaborate on whether this positioning is sufficient to ensure that there is no unintended influence between the turbine and neighboring boundaries? It would be helpful to explain how these dimensions were chosen—either by referencing a small domain-geometry convergence study (perhaps in the appendix) or by citing relevant literature that uses a similar domain setup.

In the revised paper, we have discussed the choice of the layout with reference to the data available in the recent literature.

• L. 250: The manuscript notes: "Furthermore, we impose (...) a radiative outlet boundary condition." This boundary condition type is relatively uncommon in CFD literature. A short explanation of its formulation would therefore be valuable for readers. For instance, Santoni et al. (2017) also use this condition and explicitly provide the form of the equation: $\frac{\partial \tilde{U}_i}{\partial t} + C \frac{\partial \tilde{U}_i}{\partial n} = 0$. To my knowledge, this BC is commonly referred to as "convective boundary condition" If you wish to use the term "radiative boundary condition," it would be helpful to clarify this naming choice and cite Santoni et al. (2017) for context.

We have now explicitly reported the form of this boundary condition, and changed the name with "convective boundary condition".

4 Results and Discussion

• All captions of the subsections, similar to the caption of chapter three, should have the first letter of the nouns in capital letters. So instead of "4.1 Flow analysis" — > "4.1 Flow Analysis" and the same for 4.2, 4.3, and 4.4

Done (see previous questions).

• 4.1 Flow Analysis

- L. 280-283: The manuscript states: "Contrary to what Santoni et al. (2017) observed in their work on the 5MW reference turbine invested by a uniform inflow, the rotoraveraged velocity for the TN configuration in the wake remains slightly lower than for the OR case, indicating that wake recovery is slightly hindered by the presence of the tower." It is useful to compare with Santoni et al. (2017), but in order for readers to interpret the comparison correctly, it would be important to also highlight the notable differences between the setups (e.g., Santoni et al. (2017) used no-slip boundary conditions at all walls — top, bottom, and lateral — and neglected aeroelastic effects). Furthermore, I recommend caution in how the observed results are phrased. Since this finding is based on a single CFD-based aeroelastic solver, it would be safer to state that wake recovery appears to be hindered by tower presence, but that further validation is required as the result does not fully align with expected aerodynamics. In the following sentence, the text currently shifts from observation to causality: "The reason for this behavior can be found in the different aspect ratio of the tower for the present turbine." Here, I would suggest a more cautious phrasing such as: "One possible explanation for this unexpected trend could be differences in the tower-to-rotor aspect ratio."

We agree with the referee. We have now restated the comparison following the suggestions of the referee.

- L. 291: The sentence "Figure 5 represents the time-averaged TKE for both configurations on different planes." refers to a figure that is placed two pages later. This is not a critical issue, but if the layout allows, placing the figure closer to its first mention would improve readability.

Done.

- L. 296-297: The manuscript states: "This suggests that the tower does not increase the kinetic energy entrainment but it rather has a slight shielding effect on wake recovery." Similar to my earlier comment, I would recommend avoiding the phrasing "this suggests" here, as it conveys a level of certainty not yet supported by validation against other solvers or experimental data. A more neutral formulation (e.g., "This result may indicate ..." or "In this simulation, the tower effect appears to ...") would be more appropriate.

Done.

• 4.2 Aerodynamic loads on the blade

- Figure 7: It may improve clarity if the angle of attack (AoA) is shown in a zoomed-in range (e.g., [0°, 15°]), as otherwise it is difficult to interpret the details. The legend also appears to be missing for this plot, which makes comparison harder. In addition, the BeamDyn AoA and forces in the most outboard two blade sections seem to approach zero, which looks unexpected. It would be helpful to add a short explanation if there is a known reason for this, or otherwise acknowledge it as an open point.

Concerning the AoA, this is due to the fact that Prantl tip-loss correction used by OpenFAST is applied to the velocity, and not to the forces, leading to a zero angle of attack at the tip. Concerning the forces, both tip-loss correction models are constructed in order to lead to zero forces at the tip.

- L. 339-341: The sentence currently reads: "Indeed, the blade-tower interaction leads to an oscillations of the aerodynamic forces and of the incidence angle around $\theta = 180$, i.e., when the blade is pointing down." There is a grammar error here: it should read "leads to oscillations"

Done.

- Figure 8b: There appears to be a notable disagreement in F2 between CFD-CSD/OV and ElastoDyn, even though the two models agreed reasonably well on AoA. Moreover, given that CFD-CSD/OV predicts a lower AoA compared to ElastoDyn, one would expect a lower F2 compared to ElastoDyn, yet the opposite is observed. Could you please clarify this?

Here, F_2 is the flapwise force, the one perpendicular to the plane of rotation of the blades. Since F_2 depends on lift times the cosine of the flow angle, it should decrease when the AoA increases with a constant pitch and twist angle. Thus, we think that the trend observed in figure 8b is consistent with that of figure 8a. Concerning the error, since the relation between the AoA and the force is not linear, but it depends on the cosine of the flow angle, we think that the errors on these two variables are not supposed to scale linearly. In particular, on the AoA we observe an error of $\approx 4.5\%$, while on F_2 the error is $\approx 12\%$. Since the AoA is rather low in the considered plots, its cosine will be rather high, justifying the increased weight of the error on the flapwise force.

- L. 353-355: The manuscript states: "On the other hand, when torsional feedback is included, CFD-CSD/T and BeamDyn solvers agree rather well for all the quantities considered, regardless of the linearity or non-linearity of the models." I would suggest reconsidering this phrasing. In Figure 8a there are visible discrepancies across all azimuthal angles, and in Figure 8c there are large differences at both low and high azimuthal angles. Instead of stating "agree rather well for all quantities," it might be more precise to describe where the agreement is reasonable and where significant differences remain.

We have modified the paragraph, discussing in detail these differences (see lines 393-395).

- Figure 9: To improve readability, it would be helpful to use a consistent color scheme across the colormaps, so that interpretation of the results is more straightforward.

The colormaps in figure 9 have been unified.

- L. 374-377: The manuscript notes: "Although some mild differences can be observed in their amplitudes and phases, the frequency of these oscillations appears consistent between the two solvers and comparable with the natural frequency of the first torsional mode." Here I would recommend two adjustments:
 - 1. The differences in amplitude, especially for α and F3, are not "mild" but rather notable. In some cases (e.g., BeamDyn-TN), the qualitative shape also differs, showing more oscillations than CFD-CSD/T.
 - 2. Instead of subjective wording like "mild" or "strong," it would be clearer to describe the differences in quantitative or qualitative terms (e.g., "larger amplitude," "different oscillation patterns").

We have now described the differences in a quantitative way, reporting the approximate errors for all the curves (lines 416-418).

• 4.3 Power and Thrust coefficients

- L. 388-390: The manuscript states: "The results reflect the dependency of the power and thrust coefficients on the tangential aerodynamic force F2 and the normal aerodynamic force F3 at the 80 % of the blade, respectively." For clarity and consistency, please use a single naming convention throughout. At present, F2/F3 are sometimes referred to as tangential/normal, and in other places as edgewise/flapwise. Consistency will make it easier for readers to follow.

We have adopted the naming flapwise/edgewise throughout the revised paper.

- L. 391-392: The text notes: "Notice that, also here, we can observe that the drop in the Cp curve appears to be rather consistently predicted by BEM and CFD." I would recommend revising this statement. The qualitative shape of the drop differs between the two methods: the BEM prediction exhibits notable oscillations before and after the drop, whereas these are not present in the CFD results. Thus, describing the predictions as "consistently" aligned may be misleading.

We have now modified this sentence, following the comments of the referee (see lines 433-434).

- L. 395-399: The manuscript explains: "Indeed, the flow induced by a thinner tower (in diameter units), as in the case of the 15-MW wind turbine, might be better described by a potential flow solution compared to the one induced by a thicker tower, as in the case of the 5-MW wind turbine, and may thus lead to the observed improved agreement between BEM and CFD results." Since you make several direct comparisons with the results of 5MW turbine simulations, these comparisons become a central part of the discussion. To improve readability, I suggest including the relevant 5MW results directly in the figures,

rather than expecting readers to switch between different papers.

To follow this comment of the referee, we have now included a figure concerning the wake recovery data extracted by the paper of Santoni et al 2017 [1] (see reponses above).

- L. 407-408: The sentence "Overall, it can be said that the performance drop due to the passage in front of the tower is somewhat more limited for the 15MW NREL turbine than for the 5MW counterpart (...)" could be made more precise. The repeated references to the 5MW turbine again suggest that the corresponding results should be explicitly shown and discussed here. Also, the phrases "it can be said" and "somewhat" are too subjective. A more precise wording might be: "Results indicate that the performance drop relative to the corresponding average performance is smaller for the 15MW turbine than for the 5MW counterpart." Ideally, a quantified comparison (e.g., percentage reduction or absolute values) would make this statement more rigorous. Further, the 5MW simulations were performed with uniform inflow, while the 15 MW simulations are performed using a sheared inflow. The lower wind speed in the lower part of the rotor plane means that the bottom half of the rotor plane, where the tower is located, will produce less than half of the total power. This will inevitably cause the performance drop due to the tower to be smaller relative to the total produced power. Therefore the observed difference is not only due to the change in turbine size, but also due to the change in inflow conditions.

The sentence has been rephrased in the following way: "It can be concluded that the performance loss induced by the passage in front of the tower is less pronounced for the 15 MW NREL turbine ($\approx 5\%$) compared to the 5 MW turbine ($\approx 15\%$), with both BEM theory and CFD yielding similar predictions in the case of the 15 MW turbine." Of course, also the sheared inflow can have a non negligible effect, and this point is now clearly aknowledged at several points in the paper (see, for instance, lines 453-459).

- L. 410-411: The manuscript states: "Moreover, results seem to suggest that for very large rotors the presence of the tower may constitute a less critical issue for the blade deformations than for smaller rotors (...)". This phrasing is somewhat misleading. It is not possible to draw conclusions about "issues" such as fatigue without dedicated simulations or experiments. What is actually shown are differences in blade deformation predicted by aeroelastic simulations, which have not yet been validated for this case. I would therefore recommend rephrasing along the lines of: "Moreover, the present simulation results predict that for very large rotors the tower effect on blade deformations is less pronounced than for smaller rotors." At the same time, it would be important to acknowledge that this conclusion is based only on one 15MW sheared inflow simulation, where the tower is located in the part of the rotor plane where deflections are generally smaller, and one 5MW uniform inflow simulation, so broader generalizations are not yet possible.

The sentence has been changed according to the suggestion of the reviewer and reference to the different inlet condition has been added at lines 453-459.

• 4.4 Structural response

- L. 458-459: The manuscript states: "The amplitude of the deformation is however consistent with that obtained by Trigaux et al. (2024) using LES." The wording "consistent" is somewhat ambiguous here. It would strengthen the statement if you could clarify in which sense the amplitudes agree — e.g., whether they are similar in absolute magnitude,

in relative deviation from a reference case, or primarily in qualitative trend.

We have now reported quantitatively the values of the oscillations shown by Trigaux et al. (2024) in their figure 7b (see lines 511-512 of the present paper).

- L. 474-476: The text reads: "However, the gap between the BEM and the CFD-CSD/T curves is quite large. This can be attributed to the different aerodynamic and structural model used in BEM and LES."
 - 1. The expression "quite large" is subjective; it would be clearer to either quantify the gap (e.g., percentage difference, RMS error) or replace it with a more neutral term such as "substantial" or "noticeable."
 - 2. The phrase "this can be attributed to" presents speculation as a fact. Since both the aerodynamic solvers (BEM vs LES) and structural solvers (modal vs torsional models) differ, the discrepancies cannot be uniquely traced to one factor. A more balanced formulation would be: "These differences likely arise from the combined effects of both aerodynamic and structural modeling approaches."

We have now rephrased these sentences as suggested by the referee, also providing a quantitative estimate of the error (see lines 517-518).

- L. 491-493: "the second and third flapwise natural frequencies are indeed recovered by all the numerical models". These peaks are visible, because they are at the 13th and 26th multiple of the rotational frequency (13p and 26p). They are not visible because they are at the second and third flapwise mode, because flapwise modes have very large aerodynamic damping, which is also why the first flapwise mode is not visible.

We agree with the referee, although we haven't noticed that before. We have now changed the text according to this referee's comment (lines 543-546).

5 Conclusions

• L. 522-527: The manuscript states: "The entrainment of kinetic energy driven by the tower leads to higher turbulence levels in the near wake, but then result into a slightly decreased mixing behind the turbine, differently to what has been found for the NREL 5MW wind turbine, whose wake recovery was found to be promoted by the presence of the tower. This finding can have important implications for the aerodynamic loads on downstream turbines in wind farms and overall farm efficiency." This is a counter-intuitive result, as prior studies (e.g., the NREL 5MW turbine case) suggested the opposite effect. Since the observation is based on a single solver without confirmation from experiments or other CFD-based aeroelastic simulations, I recommend formulating this more cautiously. For example, instead of "this finding can have important implications", you could write that "this result requires further examination, as it appears counter-intuitive and has not yet been confirmed by other studies." This way, the uncertainty is acknowledged while still highlighting the potential significance.

Thank you for the suggestion, we have restated this sentence in the manuscript (lines 579-580).

• L. 551-553: The manuscript concludes that "CFD-CSD can capture complex aerodynamic loading and turbulent effects better than BEM." While this is likely true in general, the specific evidence presented here — larger amplitudes at lower frequencies — does not in itself

constitute proof of that statement. It would strengthen the conclusion to either rephrase more cautiously (e.g., "In this case, the CFD-CSD solver captured larger low-frequency fluctuations than BEM") or to provide additional evidence that directly supports the broader claim.

We have rephrased the sentence in a more cautiously way (see line 604-605).

• L. 562-563: The differences between CFD-CSD/T and BeamDyn are described in a way that attributes them to solver fidelity. However, since the two approaches differ in both aerodynamic fidelity (LES vs. BEM) and structural fidelity (torsional vs. modal models), it is not possible to unambiguously assign the discrepancies to one component. I recommend rephrasing along the lines of: "The observed differences likely stem from the combined effects of differences in aerodynamic and structural fidelity, and cannot be uniquely attributed to one component alone."

We have rephrased the sentence as suggested by the referee (see lines 617-619).

Appendix A Grid Convergence Study for the LES Simulation

• L. 573: To demonstrate a clear trend in grid convergence, more than two grid resolutions are typically required. With only coarse and fine grids, it is difficult to establish whether the solution is truly converging. One possible approach would be to use the finest grid as a reference and compute a root-mean-square (RMS) error relative to it. Plotting the RMS across multiple grid resolutions would then allow you to illustrate the convergence trend more quantitatively.

Done (see answers above).

• L. 579: The manuscript states: "The comparison in figure A1 shows that the results obtained using the coarse and fine grids are extremely close each other along the entire blade span." This phrasing is somewhat vague and subjective. To make the convergence assessment clearer, it would be better to quantify the agreement, for example by reporting RMS errors or percentage deviations. Also, there is a small grammar correction: it should read "close to each other" rather than "close each other."

The updated figure has now been discussed in much more detail. Also, the typo has been corrected.

Appendix B. Validation of the Structural model

• Caption: Please ensure consistent use of title case or sentence case across the entire manuscript. For example, the current caption "Appendix B. Validation of the Structural model" mixes styles. The WES journal guidelines specify which convention should be followed — it would be good to align with that.

Looking at the journal guidelines (Titles and headings follow sentence-style capitalization i.e. first word and proper nouns only), we now used the sentence style, not capitalizing the first letter of nouns. This has been now done throughout the paper, in a consistent way.

• L. 599-600: The manuscript states: "The computed values of the modal frequencies appear to be consistent with the other results, although some discrepancies in the higher-order modes

are observed." Since the 6th mode (corresponding to the first torsional mode) is likely the most relevant for the present study, it would strengthen the paper to explicitly address these discrepancies. Please clarify in which sense the results are "consistent" and provide more detail on how the 6th mode compares across solvers.

As now clearly reported in the paper, the structural model for the IEA 15MW wind turbine has been cross-validated with many other aeroelastic numerical codes within the framework of the International Energy Agency (IEA) Wind TCP Task 47 TURBINIA [3]. In this IEA Task, a consortium of research institutions and industrial partners benchmarked their own aeroelastic codes on the IEA 15 MW wind turbine [4]. Since we cannot report in this paper data from all these partners, we have provided here a comparison of literature data. Concerning the latter, we have now clarified the discrepancies and added more details about this comparison.

• Figure B2:

- From my understanding, the 6th mode (first torsional mode) should be central to your analysis. I would expect clustering of results for solvers without torsion degrees of freedom (e.g., purple, green) as distinct from those including torsion (e.g., red, blue, grey, black). However, this clustering is not clearly visible. Is it possible that there has been a mix-up between the 6th and 7th modes in Table B1? For instance, in the 7th mode the aeroelastic solvers without torsion do not appear, whereas they do for the 6th mode. Even if this is not the case, a short discussion of why this expected separation is not observed would improve clarity.

We thank the reviewer for the comment as it highlighted a mistake in the order of the modes from the literature.

Indeed, we confirm that our modal analysis provides a 6th mode with torsional nature. However, as noticed by the reviewer, some of the mentioned solvers do not include torsional degrees of freedom in their structural models. Hence, as the natural frequencies of the torsional modes are missing, there cannot be a perfect correspondence between the order of the modes of the various models. In particular, the frequencies erroneously indicated as 6th mode for ElastoDyn and H2-PTNT can only correspond to flexural modes.

According to these observations, we have corrected the figure and we have moved the natural frequencies of the former 6th mode of ElastoDyn and H2-PTNT to our 7th mode, which is instead an edgewise mode that can be captured by these models and has a similar frequency as well.

- There is also a large spread in the higher-order modes. It could be informative to explicitly separate the results into torsion and no-torsion degrees of freedom. For example, ElastoDyn does not include torsional degrees of freedom, so one would expect systematic differences relative to models that do. The same applies to H2-PTNT.

We thank the reviewer for the suggestions, and we trust that the previous answer clarified the separation between torsional and non-torsional modes.

Spread between the higher-order natural frequencies in the literature, instead, may reasonably stem from the differences in the models used. As higher frequencies are considered, we observe that coupling between the torsional, flapwise, and edgewise degrees of freedom arise, which may be potentially affected by the different modeling assumptions adopted in the definition of the mass and stiffness matrices, or even by differences in the material properties used. However, we believe that our results are within the tolerance observed in the literature and thus guarantee a proper validation of the structural model used in this work.

Sources

• The reference "Hansen, M. (2015). Aerodynamics of wind turbines. Routledge." should be adapted to match the citation style required by WES. At the moment, the publisher and format do not appear consistent with standard referencing. Please check the journal guidelines to ensure proper formatting. For example, depending on the required style, the same reference would look as follows:

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- Chicago Style: Hansen, Martin O. L. 2015. Aerodynamics of wind turbines. 3rd ed. London, UK: Earthscan.
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The revised manuscript with the highlighted changes mentioned in this point-to-point document is attached in the following pages.

Large Eddy Simulation of the IEA 15-MW Wind Turbine Using a Two-Way Coupled Fluid-Structure Interaction Model

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3 Abstract

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The aim of the work is studying the aeroelastic response of the 15 MW NREL-IEA largescale wind turbine using a high-fidelity fluid-structure interaction solver that combines large-eddy simulation with a modal computational structural dynamics solver through a two-way coupling. The fluid solver employs the actuator line model to simulate the interaction between the turbine blades and the fluid and the immersed boundary method to model the presence of the tower and nacelle. The results are compared with those obtained by the OpenFAST software, which is a well-known numerical tool for engineering predictions. A series of simulations have been performed with and without the presence of the tower and nacelle to better understand the effects of these components on flow structures and structural deformations. The largest discrepancies among the solvers have been observed in correspondence with the blade passage in front of the tower, which induces an abrupt alteration in the local incidence angle of the flow. Moreover, by comparing the outcomes of different structural approximations, it has been established that taking into account the torsional degree of freedom considerably affects the deformations, aerodynamic loads and power coefficient. Whereas, the nonlinearity of the solver appears to have a weak effect on the same quantities.

Meywords

Aeroelasticity, Large Eddy Simulation, Actuator Line Model, Fluid-Structure Interaction, Computational Fluid Dynamics, Computational Structural Dynamics, Blade Element Momentum, IEA-15MW Wind Turbine.

1 Introduction

Wind energy has become a crucial component of the global transition toward renewable energy sources. 35 The increasing demand for clean energy has led to the development of large-scale wind turbines, such 36 as the IEA 15-MW offshore wind turbine developed within IEA Wind Task 37 (Gaertner et al., 2020a). 37 This turbine, with a rotor diameter of 240 meters and blades measuring 117 meters in length, rep-38 resents a new frontier in wind energy technology (Gaertner et al., 2020b), and research is currently 39 pointing towards even larger rotors, reaching 22-MW of power production (Zahle et al., 2024). The 40 increasing scale and flexibility of such newly designed turbines present significant engineering chal-41 lenges, particularly in predicting their aeroelastic response (Burton et al., 2011; Zheng et al., 2023). 42 As turbines grow in size, their structural components, especially the blades, are subject to complex 43 aerodynamic forces that cause deformations, which in turn affect the aerodynamic loads. Understand-44 ing these interactions is essential to improve the performance, reliability, and longevity of large-scale 45 wind turbines (Manwell et al., 2010). In the worst cases, aeroelastic instabilities such as edgewise 46 instability and flutter might even lead to blade damage, as reported for the Lunderskov Mobelfabrik 47 19 m wind turbine blades (Moeller, 1997), with devastating effects on the turbine performance. 48 Aeroelasticity, the study of the interaction between aerodynamic, inertial and elastic forces due to the 49 deformation of the structure, is critical in the design and analysis of modern wind turbines. Aeroe-50 lastic phenomena such as dynamic stall, flutter, and fatigue can have significant effects on turbine 51 performance, particularly as the blade length increases (Hansen, 2007). These blades experience vary-52 ing aerodynamic forces along their span, which can lead to substantial deformations. When blades 53 deform, they alter the local flow field, which in turn modifies the aerodynamic loads acting on them. 54 This feedback loop between aerodynamic forces and structural deformation makes it very difficult 55 to predict modern large-scale turbine performance under real-world operating conditions (Vermeer 56 et al., 2003; Wang et al., 2016a). Accurate evaluation of these interactions is key for ensuring turbine 57 efficiency and structural integrity, especially in offshore environments where wind conditions are more 58 severe (Bayati et al., 2017). 59 The numerical modeling of the blades in most of the numerical aeroelastic codes used nowadays (Schep-60 ers et al., 2021) is accomplished by the blade element momentum (BEM) model, due to its robustness and low computational cost. However, BEM has several limitations, due to the strong assumptions 62 made on the impinging flow, requiring models of dynamic stall, dynamic inflow, yaw and tilt flows, 63 and corrections of the aerofoil data for taking into account three-dimensional effects and tip losses. 64 Unfortunately, more computationally expensive models, such as the free-wake panel and the actuator 65 disc methods, are not able to predict the dynamic loading much more accurately. Therefore, the application of computational fluid dynamics (CFD) to full-scale turbines is the most promising way 67 to drop those assumptions and describe the complex aerodynamics of the flow field more accurately

(Sørensen, 2011).

However, coupling three-dimensional CFD simulations with computational structural dynamics (CSD) 70 solvers taking into account the deformation of the blade is not trivial. Three-dimensional structural 71 finite-element models are in fact able to fully describe the complex shape of a wind turbine blade but, 72 although accurate, these models are computationally expensive and hard to implement, leading to 73 only a few examples of coupling with CFD codes (Bazilevs et al., 2011; Yu and Kwon, 2014). Since 74 wind turbine blades are slender structures, their structural modeling can be more easily achieved using 75 beam models, where the blade is approximated as a series of one-dimensional beam elements, each 76 characterised by a given cross-sectional stiffness and mass per unit length. One-dimensional beam 77 models can be either modal, since natural frequencies and mode shapes of a turbine are directly re-78 lated to the natural frequencies of its blades, or they can rely on the geometrically exact beam theory 79 including non-linear effects (Sabale and Gopal, 2019). 80

Due to their ability to provide a rapid evaluation of the turbine performance, numerical tools based 81 on the lifting-line approach equipped with aeroelastic modules based on one-dimensional beam mod-82 els, are currently widespread (Schepers et al., 2021). A notable example is OpenFAST, a numerical 83 code developed at NREL (Jonkman, 2013) and widely used for aeroelastic simulations, which employs 84 BEM theory for aerodynamic modeling and various structural solvers, such as ElastoDyn (Damiani 85 et al., 2015) and BeamDyn (Wang et al., 2016b), for structural deformation analysis. However, it is 86 still not clear whether the predictions of such lifting-line aeroelastic codes are sufficiently accurate for 87 large-scale turbines, in which the effect of shear and inflow turbulence can lead to complex inflows and 88 turbine aerodynamic responses. Comparing the predictions of OpenFAST with those of a Large-Eddy 89 Simulation (LES) equipped with a structural one-dimensional beam model has shown that, for an 90 NREL 5MW wind turbine, the passage in front of the tower leads to large deformations which are 91 largely underestimated by OpenFAST (Bernardi et al., 2023). 92

Concerning rotors of even larger size, such as the IEA 15-MW reference turbine, it is not yet known 93 whether these discrepancies in the predictions of lifting-line codes with respect to CFD are even more 94 consistent. Using the unsteady Reynolds-Averaged Navier-Stokes (URANS) equations coupled with 95 an aeroelastic module, as reported by Pagamonci et al. (2023), has shown that neglecting the flexibility 96 of the blades in numerical simulations leads to an underestimation of the rotor thrust of approximately 97 2.5% for the IEA 15-MW turbine, which is not observed for the smaller NREL 5MW rotor. More-98 over, this work also concluded that the deformation of long, slender blades may act as a filter for the high-frequency fluctuations arising from the flow field, proving that taking into account the blades' 100 aeroelasticity in the design process of these machines is key for the future upscaling of turbine rotors. 101 Furthermore, Trigaux et al. (2024) observed how the use of high-fidelity aerodynamic models is crucial 102 to predict the aeroelastic effects of large rotors. These results suggest the need to investigate this issue 103 resorting to LES, which is capable of describing the dynamics of the flow more accurately. 104

In this context, the present work aims at studying the aeroelastic response of a large-scale 15-MW wind turbine by means of LES, assessing the effect of the flexibility of the blades on the wake dynamics. The results are compared with those obtained by more simple and less computationally expensive models, such as the OpenFAST code. Computations are performed by an in-house LES code using the immersed boundary method to model the tower and nacelle and the Actuator Line Model (ALM) for blade modeling, coupled with a structural modal solver, originally developed by Della Posta et al.

111 (2022).

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The discussion of the results highlights the role of the tower and nacelle in the dynamics of the aerodynamical forces, thrust and power coefficients, as well as in the distribution of turbulent kinetic energy within the wake, which could have an impact on the aerodynamic loads of downstream turbines in wind farms. Moreover, the effect of the torsional degree of freedom has been investigated by comparing the outcomes of different structural approximations.

The work is structured as follows. In section 2, the aerodynamic and structural solvers of both CFD-CSD and OpenFAST codes are described in detail. In section 3, the numerical setup is presented. In section 4, relevant results are discussed, and conclusions are drawn in section 5.

120 Methodologies

2.1 CFD-CSD solver

122 **2.1.1** Flow solver

The simulations of the flow around the wind turbine are carried out through Large-Eddy Simulations 123 (LESs) of the incompressible, filtered, 3D Navier-Stokes equations, employing our in-house UTD-WF 124 solver introduced by Santoni et al. (2015). The UTD-WF framework has been progressively devel-125 oped by Santoni et al. (2017, 2020) and further extended by Della Posta et al. (2022, 2023), where the 126 aeroelastic solver and the Leishman-Beddoes dynamic stall model were implemented. The solver has 127 been validated in its non-aeroelastic version by Santoni et al. (2017) against wind-tunnel data repro-128 ducing the NTNU "Blind Test" and comparing simulations to Krogstad et al. (2015) measurements, 129 also considering the impact of tower and nacelle. Whereas, the recently developed version of the code 130 including the two-way FSI coupling Della Posta et al. (2023) has been validated through comparison 131 against reference datasets, including HAWC2-based results reported by Heinz (2013). The IEA 15MW 132 wind turbine configuration cosidered here has been cross-validated with many other aeroelastic nu-133 merical codes in the International Energy Agency (IEA) Wind TCP Task 47 (Cacciola et al., 2025), 134 also considering turbulent inflow conditions (Schepers et al., 2025). Notice that prior validations by 135 Della Posta et al. (2022) of the CFD-CSD solver were made on a laminar uniform and a turbulent 136 sheared inflows for a 5 MW NREL turbine, whereas our study extends the validated setting to the 137 IEA-15 MW case for a sheared laminar inflow configuration. However, as discussed in the framework 138 of the IEA Wind TCP Task 47 Schepers et al. (2025), turbulent fluctuations appear to have a much 139 stronger impact than shear on load response of aero-elastic numerical codes. Moreover, high-fidelity 140 codes appear rather consistent in predicting loads, while engineering models tend to overpredict fa-141 tigue loads, particularly for large rotors (Cacciola et al., 2025). 142 The code implements a second-order accurate centered finite difference scheme for the spatial dis-143 cretization on a staggered Cartesian grid. A hybrid low-storage third-order-accurate Runge-Kutta (RK) scheme is used for time integration of the non-linear terms (Orlandi, 2012), while the linear 145 terms are treated implicitly using a Crank-Nicolson scheme. The filtered governing equations are: 146

$$\frac{\partial u_i}{\partial t} + \frac{\partial u_i u_j}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \frac{1}{Re} \frac{\partial^2 u_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j} + \tilde{f}_i, \tag{1}$$

$$\frac{\partial u_i}{\partial x_i} = 0,$$

$$\frac{\partial u_i}{\partial x_i} = 0,\tag{2}$$

where $i, j \in \{1, 2, 3\}$ represent, in a Cartesian reference frame, the components along the streamwise (x), wall-normal (y), and spanwise (z) directions, respectively. The Reynolds number $Re = U_{\infty}D/\nu$ is defined by the undisturbed inlet velocity U_{∞} , the turbine diameter D, and the kinematic viscosity of the fluid ν . These quantities are used as reference values to make the equations non-dimensional. To solve the filtered equations, a Subgrid-Scale (SGS) stress model is needed. The latter describes the interaction between the large resolved and the sub-grid unresolved scales, as described by Pino Martín et al. (2000) and Santoni et al. (2017). Here, we employ the Smagorinsky model with constant $C_s = 0.09$ as discussed by Martinez-Tossas et al. (2018).

The effect of the blades on the flow is modeled by the Actuator Line Model (ALM) (Sorensen and Shen, 2002), by adding a forcing term to the Navier-Stokes equations, representing the force per unit volume exerted by the rotor on the fluid. By approximating the rotor blades as rigid straight lines discretized into segments, it is possible to estimate the lift and drag forces per unit length on a 2D plane as follows:

$$F_l = \frac{1}{2}\rho u_{rel}^2 C_l(\alpha) cF, \qquad F_d = \frac{1}{2}\rho u_{rel}^2 C_d(\alpha) cF, \tag{3}$$

where ρ is the air density, c is the local chord, u_{rel} is the relative incoming velocity, α is the angle of attack, and F represents the tip loss correction factor, which employs the tip-loss model proposed by Shen et al. (2005). The coefficients c_1 and c_2 of this model have been set in the following way: c_1 has been set to the value reported in the Shen et al. (2005) paper ($c_1 = 0.125$), whereas, c_2 has been chosen after a calibration with respect to the forces close to the tip reported by OpenFAST for the same turbine and flow case, leading to the choice of $c_2 = 32$. The forces are then projected on the flow employing a 2D Gaussian kernel, which spreads the lift and drag force vector, f^{aero} , in cylinders surrounding the actuator line,

$$\tilde{\mathbf{f}} = -\mathbf{f}^{aero} \frac{1}{\epsilon^2 \pi} exp \left[-\left(\frac{r_{\eta}}{\epsilon}\right)^2 \right],\tag{4}$$

where r_{η} is the radial distance of a generic point of the cylinder from the actuator line and ϵ is the spreading parameter, where $\epsilon/\Delta \geq 2$, with $\Delta = \sqrt{\Delta x^2 + \Delta y^2 + \Delta z^2}$, following Troldborg (2009). The tower and nacelle are modeled using the Immersed Boundary Method (IBM) following the approach described by Orlandi and Leonardi (2006).

2.1.2Structural solver

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From an aerodynamic standpoint, the rotor blades represent the most flexible components within a wind turbine. Several studies demonstrated that their modal properties have a significant impact on

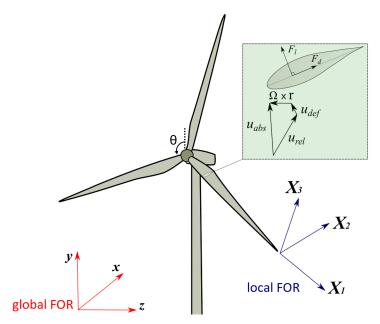


Figure 1: Sketch of the frames of reference used for the CFD and for the CSD simulations.

the dynamics of the entire structure (Damgaard et al., 2013; Dong et al., 2018). Moreover, an analysis

of the isolated blades is also sufficient to accurately estimate the aeroelastic properties of the entire structure, including the flutter speed (Abdel Hafeez and El-Badawy, 2018). Additionally, the tower and shaft exhibit minimal deflection due to their stiffness. In light of the above considerations, the aeroelastic model is constructed to encompass solely the structure of the blades.

The structural model used in the present study was previously presented by Della Posta et al. (2022, 2023). In order to model the working conditions, the blades are assumed to be rotating beams rigidly clamped at the hub (cantilever beams), under the assumption of small deformations with respect to a relative frame of reference (FOR). The direction of the pitching axis is denoted by X_1 . This coincides with the neutral axis of the blade, defined as passing through the quarter of the chord. The direction of the out-of-plane flapwise motion is indicated by X_2 and is oriented in the positive streamwise direction. The in-plane edgewise direction of X_3 is defined such that the FOR is oriented

as a right-handed coordinate system (Figure 1).
Under the assumption of linearity, the elastic generalised displacement d, which includes translational d_i and rotational θ_i degrees of freedom (DoFs), is decomposed along the coordinate X_1 on the neutral axis as:

$$d(X_1, t) = \sum_{m=1}^{M} q_m(t) \psi^m(X_1),$$
(5)

where $\psi^m(X_1)$ is the m-th elastic mode shape from the modal analysis of the structure, q_m is the corresponding modal coordinate, and M is the number of modes used. The general inertial coupling is included in a modal basis by means of the methodology introduced by Reschke (2005) and further

developed for the case of wind energy by Della Posta et al. (2022). In particular, the two-way coupling algorithm between rigid-body and structural dynamics does not take into account a modification of the rotor inertia caused by the deformation of the blades. Hence, the structural dynamics of the structure can be described by the following equation:

$$\boldsymbol{M}\ddot{\boldsymbol{q}} + [\boldsymbol{D} + \boldsymbol{D}^{Co}(\boldsymbol{\Omega})]\dot{\boldsymbol{q}} + [\boldsymbol{K} + \boldsymbol{K}^{c}(\boldsymbol{\Omega}) + \boldsymbol{K}^{Eu}(\dot{\boldsymbol{\Omega}})]\boldsymbol{q} = \boldsymbol{e} + \boldsymbol{e}^{c}(\boldsymbol{\Omega}) + \boldsymbol{e}^{Eu}(\dot{\boldsymbol{\Omega}}), \tag{6}$$

where M, D and K denote the modal structural mass, damping, and stiffness matrices, respectively, and e are the external loads expressed in modal basis. The remaining terms are inherently related to the various contributions to the acceleration in a moving FOR. Terms with the superscript Co, c and Eu are related to the Coriolis, centrifugal, and Euler accelerations, respectively. The discrete evaluation of the additional inertial terms in Equation (6) is expressed as a function only of the information known from the structural finite-element method (FEM) model and from the corresponding mode shapes, according to Saltari et al. (2017). For the modal analysis, we use a finite element model of the blade based on complete beam elements with 6 DoFs, with Euler-Bernoulli behavior for bending in directions X_2 and X_3 , and linear shape functions for axial and torsional deformations. The generalized- α method (Chung and Hulbert, 1993) is employed to advance the structural dynamic equation in time, which is unconditionally stable for linear problems, and second-order accurate. We assume a lumped-mass representation, and we take into account the local offset of the centers of mass with respect to X_1 . Finally, the structural matrices are assembled considering the local twist. Details about the modal analysis are provided in Appendix A.

2.1.3 Fluid-structure interaction model

The two-way coupling aeroelastic model employs the ALM sectional approach, whereby the angle of attack (AoA) and relative velocity are locally modified following the instantaneous blade motion provided by the structural dynamics. In particular, the distribution of the AoA along each blade is evaluated as a function of the velocity of the fluid, the angular velocity of the rotor, and the instantaneous elastic state of the blade. The latter is generally constructed from the deformation velocity $\mathbf{u}_{def} = \dot{\mathbf{d}}$ and the local vector of the deformation angles $\boldsymbol{\theta}$ (torsion and bendings) derived from the structural solver, which is forced by the updated aerodynamic loads. The algorithm restricts inter-field communications solely at the beginning of each RK substep, thereby ensuring optimal computational efficiency. The impact of torsional dynamics was deemed to be limited in light of the results obtained in previous studies on the effect of torsion for smaller wind turbines (Chen, 2017). In order to investigate this issue for the large rotor 15MW wind turbine, in this study we compare two different CSD models. In particular, we consider as a baseline a two-way coupling that includes the effect of blade deformation velocity as a sole variable (CFD-CSD/OV, for Only Velocity), and a more complete model including the torsional deformation in the coupling (CFD-CSD/T, for Torsional). In general, the relative velocity for a rotating blade can be defined with the following expression:

$$u_{rel} = u_{abs} - \Omega \times r_{OP} - u_{def}, \tag{7}$$

where u_{abs} is the filtered velocity from the fluid solver at the actuator line, r_{OP} is the general radial vector pointing to the considered section, Ω is the rotor rotational speed, and u_{def} is the deformation

velocity of the structure at the same position. As a result, the AoA used to determine the air load coefficients is defined as follows:

$$\alpha = \operatorname{atan}\left(\frac{\boldsymbol{u}_{rel} \cdot \boldsymbol{E}_2}{-\boldsymbol{u}_{rel} \cdot \boldsymbol{E}_3}\right) - \phi - \theta_{tors} = \operatorname{atan}\left[\frac{(\boldsymbol{u}_{abs} - \boldsymbol{u}_{def}) \cdot \boldsymbol{E}_2}{\Omega r - (\boldsymbol{u}_{abs} - \boldsymbol{u}_{def}) \cdot \boldsymbol{E}_3}\right] - \phi - \theta_{tors},\tag{8}$$

where ϕ is the local twist angle of the blade, θ_{tors} is the local torsional deformation, \mathbf{E}_i are the unit vectors of the relative FOR rotating with the structure, and hence, $v_2 = \mathbf{u}_{def} \cdot \mathbf{E}_2$ is the flapwise deformation velocity component, and $v_3 = \mathbf{u}_{def} \cdot \mathbf{E}_3$ is the edgewise deformation velocity component. The simplified coupling procedure benefits from the sectional one-dimensional formulation of the ALM, which avoids the complex treatment of the fluid-solid interface with the associated kinematic and traction conditions.

2.2 OpenFAST modules

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For comparison purposes, wind turbine simulations have been also conducted using the OpenFAST solver Release v3.2.0 (July 29, 2022). OpenFAST is a widely utilized open-source numerical code developed by the NREL that combines different specialized modules for simulating the coupled aerohydro-servo-elastic response of wind turbines. The aerodynamic computations are performed by the AeroDyn (Jonkman et al., 2015) module which is based on the BEM theory. A Prandtl loss model is applied to account for the tip and root effects. The structural module dedicated to the computation of the blade deformation is contained in the BeamDyn module, which relies on the geometrically exact beam theory and may resolve geometric non-linearities and large deflections (Wang et al., 2016b). BeamDyn has replaced the simplified ElastoDyn module, based on a modal approach and suitable for blade deformation dominated by bending. In order to compare the CFD-CSD results with a modal structural analysis, we also performed simulations using the standalone *ElastoDyn* module. It is worth to notice that the latter does not take into account the torsional degree of freedom, so it is to be directly compared to the CFD-CSD/OV model, which also does not account for the coupling between the torsional deformation and the angle of attack. As reported in the original manual of AeroDyn (Moriarty and Hansen, 2005), OpenFAST couples the fluid and structural solvers in a similar way to our CFD-CSD solvers. In particular, the local angle of attack is determined taking into account the local deformation velocities.

3 Flow and structural setup

In this work, we consider a stand-alone IEA 15-MW wind turbine (Gaertner et al., 2020b) in its monopile configuration. This wind turbine has a rotor diameter D=240 m with three blades of length L=117 m. Table 1 provides the main features of the turbine. The computational box has dimensions $12.5 \times 5 \times 3$ diameter units, as shown in Figure 2. The distance of the turbine from the inlet of the computational domain (equal to 4D) has been determined on the base of the reference data available in the literature, which vary in the range 2D-5D. Smaller distances from the inlet (2D) have been employed for experimental set-up (Bartl and Satran, 2017; Krogstad et al., 2015), whereas larger distances (in the range 2.7D-5D) are typical of numerical simulations

(Porte-Agel and Wu, 2011; Ciri et al., 2017; Allah and Sha ei Mayam, 2017; Stevens et al., 2018). 266 Moreover, we have verified numerically that pressure fluctuations do not generate spurious reflections 267 at the inlet section in our simulations. The spanwise length of the computational domain (equal 268 to 3D) is the same employed in previous numerical simulations (Ciri et al., 2017; Allah and Sha ei 269 Mayam, 2017). We have verified that, using periodic boundary conditions, the blockage effect on 270 the single turbine is negligible. Moreover, following the convergence study reported in the Appendix 271 A, the computational box has been discretized by a staggered grid composed of $2049 \times 513 \times 513$ 272 points in the streamwise, wall-normal, and spanwise directions, respectively. The orthogonal grid is 273 equally spaced in the streamwise and spanwise directions and is stretched vertically, with a gradually 274 wider spacing starting from the region above the rotor. The grid spacing described leads to an 275 actuator line discretized by 86 points per blade. The time resolution of the LES computation is tied 276 to the spatial resolution, as defined by the stability requirements of the numerical scheme adopted. 277 Simulations are carried out at a constant Courant-Friedrichs-Lewy (CFL) number (Courant et al., 278 1967) CFL = 0.65, which ensures an average time step $\overline{\Delta t} = 0.024s$. The turbine location is 4 279 diameter units from the inlet and centered in the spanwise direction. Furthermore, we impose a 280 sheared laminar inflow velocity profile, defined by a power law with the exponent $\alpha = 0.05$, and a 281 convective outlet boundary condition, i.e., $\frac{\partial u_i}{\partial t} + C \frac{\partial u_i}{\partial x} = 0$, with the constant C set to the average 282 value of the outflow velocity. In the spanwise direction, periodic boundary conditions are imposed. 283 Moreover, slip and no-slip conditions are enforced at the top and bottom boundaries, respectively. 284 The turbine is subjected to a flow with a Reynolds number $Re \approx 10^8$ and operates at its nominal tip 285 speed ratio (TSR) of $\lambda = 9$. The streamwise undisturbed velocity at the hub height is constant and 286 equal to $U_{\infty} = 10 \ m/s$. The simulations were conducted for a time interval of 300 s over the initial 287 transient, which corresponds to 35 revolutions of the rotor. 288 To identify the optimal configuration for the structural model, we conducted a preliminary sensitivity 289 analysis and then validated the structural eigenfrequencies with the results found in the literature. A 290 more detailed insight into this analysis is presented in Appendix B, where the structural properties 291 of this turbine are shown. Finally, a number of modes $M_s = 15$ and a structural discretization of the 292 blades given by N = 80 equally-spaced nodes were chosen. 293

4 Results and discussion

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This section presents the results of two set of simulations: one modeling a rotor-only configuration (RO) and the other including the tower and nacelle (TN). Furthermore, both configurations are subjected to comparative analysis using the OpenFAST submodules. Firstly, the near-wake aerodynamic characteristics and the wake recovery of both configurations determined by the CFD-CSD solvers are discussed. Then, the aerodynamic loads on the blades are analyzed and the outcomes from both solvers are compared. Finally, the overall turbine performance and the effects on the blade deformation are assessed.

| Parameter | Units | Value | |
|------------------------|-------|--------|--|
| Power rating | MW | 15 | |
| Rotor diameter (D) | m | 240 | |
| Rotor orientation | _ | Upwind | |
| Number of blades | _ | 3 | |
| Blade length (L) | m | 117 | |
| Hub height | m | 150 | |
| Hub radius (R_{hub}) | m | 3.97 | |
| Rated wind speed | m/s | 10.59 | |
| Design tip speed ratio | _ | 9 | |
| Maximum rotor speed | RPM | 7.56 | |

Table 1: IEA 15-MW (Gaertner et al., 2020b) wind turbine main features

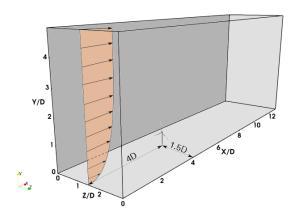


Figure 2: Sketch of the computational box where the incoming sheared flow and the position of the turbine are highlighted.

4.1 Flow analysis

As a first step, we analyze the flow field variables, as obtained using the CFD-CSD/T solver. Figure 3 illustrates the main coherent flow structures in the field by means of an instantaneous isosurface of the Q-criterion colored by the streamwise velocity for both cases. It is evident that the presence of the tower affects the vorticity intensity distribution along the vertical direction. In particular, the occurrence of a low-velocity recirculation zone at the tower height for the TN case can be identified, which is a result of the tower shadowing (see Figure 3b). Moreover, the TN case demonstrates a more rapid dissolution of the endogenous coherent hub vortex structures if compared to the RO case (see Figure 3a). On the other hand, the tip vortex structures appear to be minimally influenced by the presence of the tower. Figure 4 shows the rotor-averaged streamwise velocity along the flow direction, time-averaged over 30 revolutions of the rotor. Contrary to what Santoni et al. (2017) observed in

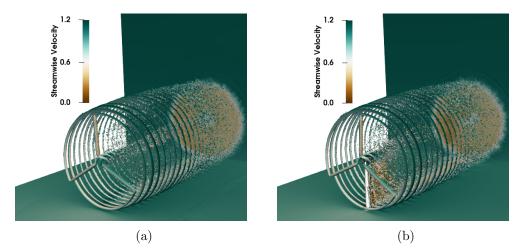


Figure 3: Q-criterion contour of the instantaneous velocity field colored by the streamwise velocity for the rotor-only case (RO) (a) and tower and nacelle (TN) (b).

their work on the 5MW reference turbine invested by a uniform inflow (see the red lines in figure 4), the rotor-averaged velocity for the TN configuration in the wake remains slightly lower than for the 314 OR case, indicating that wake recovery is slightly hindered by the presence of the tower. Although 315 further validation is required as the result does not fully align with this previous literature study, wake 316 recovery appears thus to be hindered by tower presence. One possible explanation for this behaviour 317 could be differences in the tower-to-rotor aspect ratio. In particular, for the NREL 5-MW turbine, 318 the ratio between the tower diameter and the rotor diameter is about equal to 0.047, whereas, for the 319 15MW turbine, it is only about 0.027 (the tower diameters being 6m and 6.5m, respectively). Thus, 320 the thinner shape (in terms of diameter units) of the tower, as well as the lower value of the incoming 321 velocity at the tower height due to the presence of shear at the inflow, result into a decreased mixing 322 behind the turbine which leads to a slower wake recovery. 323 From an energy perspective, the wake recovery process can be depicted by examining the Turbulent 324 Kinetic Energy (TKE) in the wake. Figure 5 represents the time-averaged TKE for both configurations 325 on different planes. The TN case exhibits high TKE values in the near wake, in the region just 326 downstream of the tower and nacelle. The top view of the TN case shows that the TKE in the wake 327 presents an asymmetric distribution as De Cillis et al. (2022) observed, among the others, in their 328 work. On the contrary, the RO configuration shows large TKE only in the far wake region, with large 329 values also in the region above hub height. This result may indicate that the tower does not increase 330 the kinetic energy entrainment but it rather has a slight shielding effect on wake recovery. Although 331 not favoring kinetic energy entrainment, the tower still plays a strong role in the wake dynamics, as 332 it can be visualized in figure 6, showing slices of instantaneous streamwise velocity at different tower 333 heights corresponding to 80% of the blade (top) and to the tip of the blade (bottom), when the blade 334 is in front of the tower, i.e. $\theta = 180^{\circ}$ (left), and when it is far from it (right). In particular, it can 335 be observed that the turbulent mixing right downstream of the tower is already very high in the near 336 wake compared to that close to the tip of the blades. Probably due to asymmetry induced by the 337

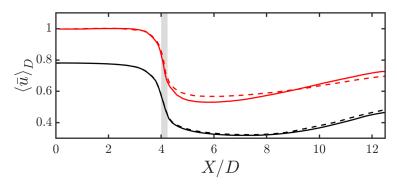


Figure 4: Rotor-averaged velocity along the streamwise direction normalized by the undisturbed velocity at the rotor height, namely, $U_{\infty} = 10 \ m/s$, for the present data (black curves) and the work of Santoni et al. (2017) (red curves). The grey region represents the area covered by the rotor. (RO ----, TN —).

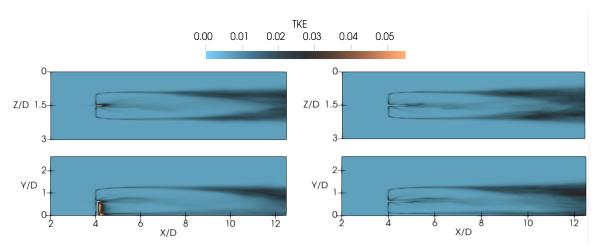


Figure 5: Top (upper slices) and lateral (lower slices) views of the time-averaged Turbulent Kinetic Energy on slices passing through the hub. TN (left), RO (right).

rotation of the blades, inside the rotor disk, it can be seen that the tower wake bends in the spanwise direction (Figure 6, top frames), whereas it is rather spanwise independent at a height corresponding to the blade's tip (bottom frames). Moreover, one can see that the passage of the blade in front of the tower (left frames) induces a strong perturbation in the flow field already upstream of the tower. In the following section, the effect of this perturbation on the phase oscillations of several relevant quantities (aerodynamic forces, power coefficient, etc.) will be discussed.

4.2 Aerodynamic loads on the blade

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The analysis of the aerodynamic loads on the blade has been conducted using the present CFD-CSD models and the engineering software OpenFAST. The same laminar sheared inflow is imposed for

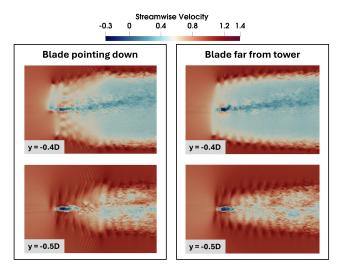


Figure 6: Instantaneous streamwise velocity on horizontal slices at different tower heights corresponding to 80% of the blade (top slices), and the tip of the blade (bottom slices). In the left configuration, the blade is in front of the tower ($\theta = 180^{\circ}$), while on the right the blade is far from the tower.

both solvers using a power law with the same exponent and reference streamwise velocity at the hub height. We have chosen not to impose a turbulent inflow to avoid differences in the definition of the turbulent inflow itself which might have hindered the comparison between the results of the two codes. It is important to note that the four solvers employed differ in both their aerodynamic and structural modeling approaches. As a result, it is not always possible to unambiguously determine whether the observed discrepancies in the results originate from the fluid-dynamic models or from the structural formulations.

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Figure 7 depicts the following time-averaged aerodynamic quantities along the span of the blade: the local angle of attack α (Figure 7a); the aerodynamic pitching moment per unit length M_{aero} (Figure 7b); the flapwise and edgewise components of the aerodynamic force per unit length F_2 (Figure 7c) and F_3 (Figure 7d), respectively. In particular, Figure 7a shows that a good agreement of the local incidence angle computed by both CFD-CSD models (solid lines) with that computed by ElastoDyn (circles) and BeamDyn (squares) is obtained from the 20% up to the 80% of the blade length. Indeed, the differences in the root area could ascribable to the presence of the hub which is modeled differently by the solvers. The discrepancy of the incidence angle observed towards the tip subsequently affects the aerodynamic loads. The F_2 force in Figure 7c shows a very good fit of the CFD-CSD/T results with that of the nonlinear solver BeamDyn, despite the linearity of our in-house CSD model. The strong discrepancies with respect to the values obtained by ElastoDyn can be ascribed to the absence of the torsional deformation in the latter solver. Indeed, the CFD-CDS/OV solver, which neglects the torsional feedback in the coupling, shows very similar results to the *ElastoDyn* solver. A similar effect can be observed by examining the reduction in F_3 towards the tip of the blade (see Figure 7d). The distribution of the aerodynamic pitching moment presents instead a maximum gap of about 8% from the BEM-based solvers.

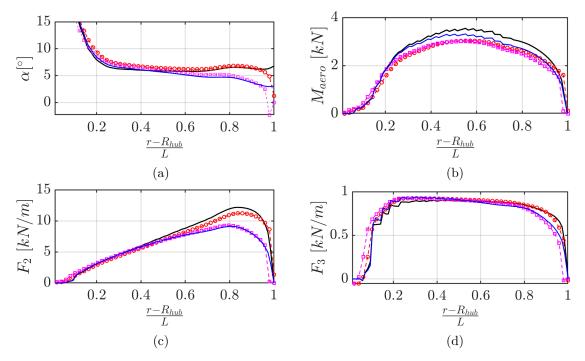


Figure 7: Average aerodynamic quantities along the blade compared between CFD-CSD/OV (black solid line), CFD-CSD/T (blue solid line), ElastoDyn (red rounded markers), BeamDyn (magenta squared markers). (a) Incidence angle, (b) Aerodynamic pitch moment, (c) flapwise aerodynamic force, (d) edgewise aerodynamic force.

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As demonstrated by Hansen (2015), the outer third of the blade span is the most critical region in terms of deflections and deformations due to the combination of higher aerodynamic loads and reduced structural stiffness. Therefore, a phase average of the aerodynamic quantities at the 80% of the blade has been performed. Figure 8 reports the evolution of the incidence angle and of the aerodynamic force components at $\frac{r-R_{hub}}{L} = 0.8$ (being R_{hub} the hub radius and L the blade length) versus the blade rotation angle θ . The dynamical behavior of the aerodynamic quantities in the presence (solid lines) or in the absence (dashed lines) of the tower underlines that the passage of the blade in front of the tower represents the main source of instability for the flow conditions considered. Indeed, the blade-tower interaction leads to oscillations of the aerodynamic forces and of the incidence angle around $\theta = 180^{\circ}$, i.e., when the blade is pointing down. However, unlike the case of the NREL 5-MW turbine (Bernardi et al., 2023), this effect appears to be stronger for the BEM computations than for the CFD-CSD solver. Concerning this point, we should recall that, as pointed out by Bernardi et al. (2023), the complex flow dynamics resulting from the interaction between the blade and the tower, shown in Figure 6, may not be well described by OpenFAST, which uses a simple potential flow model. It can be observed that, between the rotor and the tower, a region with low streamwise velocity is observed. We can expect that the passage of the blade in front of the tower thus induces an alteration of the aerodynamic forces on the blade due to the decrease/increase of the streamwise velocity. This issue

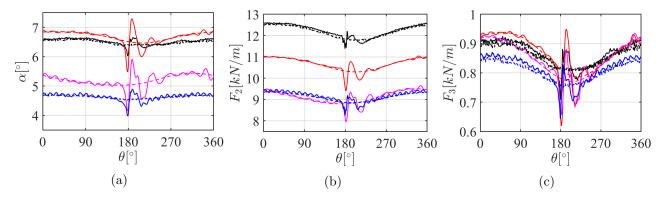


Figure 8: Phase-averaged values of: (a) the local incidence angle, (b) flapwise aerodynamic force, and (c) edgewise aerodynamic force at the 80% of the blade. CFD-CSD/OV: TN ——, RO ----. CFD-CSD/T: TN ——, RO ----. ElastoDyn: TN ——, RO ----. BeamDyn: TN ——, RO ----.

will be further discussed in the following, where a possible reason for the different behavior observed for the IEA 15-MW with respect to the NREL 5-MW turbine will be discussed.

Apart from the effect of the tower, one can observe a rather good match between the CFD-CSD/OV and ElastoDyn solvers for both the incidence angle and the edgewise component of the aerodynamic force, while the flapwise component presents some discrepancies. On the other hand, when torsional feedback is included, CFD-CSD/T and BeamDyn solvers, regardless of the linearity or non-linearity of the models, agree rather well on the aerodynamic forces, especially on the flapwise one, which shows an error $\approx 2\%$, while the edgewise force reaches a $\approx 5\%$ error at azimuthal angles close to $\theta = 0$. Whereas, the error between the two solvers on the angle of attack reaches 8%.

To better investigate the local response of the different models during the blade revolution, we conducted a comparative analysis of the aerodynamic loads, employing phase-averaged quantities over the span. Figure 9 illustrates the percentage difference of the phase-averaged aerodynamic quantities on the rotor plane of the ElastoDyn (BeamDyn) solver with respect to the CFD-CSD/OV (CFD-CSD/T) model, respectively. In particular, in comparison to ElastoDyn, a higher value of the absolute incidence angle in the range of $|\langle \Delta \alpha / \alpha^{CFD-CSD/OV} \rangle^{\%}| = [17\%, 25\%]$ is found in the zone after the tower (see Figure 9a). The difference with respect to the results obtained by BeamDyn tends to be higher moving from the root to the tip with a discontinuity in the tower area, spanning the range $|\langle \Delta \alpha / \alpha^{CFD} \rangle^{\%}| = [35\%, 60\%]$ in the last 20% of the blade span. Furthermore, the angle of attack distribution affects the components of the aerodynamic force. In fact, the distribution of the flapwise component of the force follows the same pattern of the incidence angle (see Figure 9b). On the other hand, for the edgewise component the major discrepancies are concentrated in the final radial sections of the blade toward the tip (see Figure 9c). In general, we can conclude that the most significant discrepancies are observed in the tip region where the three-dimensional effects are more relevant and where the complexity of the fluid flow is strongly affected by the presence of the tower.

Notably, similar discrepancies are observed when comparing the CFD-CSD/T solver with the Beam-Dyn solvers. However, in this case some high-frequency oscillations are observed for the three aerodynamic quantities. In fact, the same oscillations are observed in the phase averaged quantities at 80%

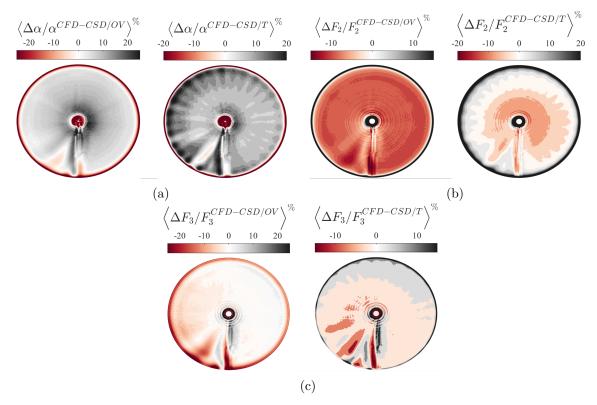


Figure 9: Phase-averaged contour plots of the percentual differences of the aerodynamic quantities between CFD-CSD/OV versus *ElastoDyn* (left), and CFD-CSD/T versus *BeamDyn* (right), respectively. (a) Incidence angle, (b) flapwise aerodynamic force, (c) edgewise aerodynamic force.

of the blade shown in Figure 9, for both the CFD-CSD/T solver and BeamDyn. The frequency of these oscillations computed by the two solvers appear very close and comparable with the natural frequency of the first torsional mode, although some differences can be observed in the amplitudes of the signals, especially concerning the angle of attack ($\approx 8\%$ of error) and the edgewise aerodynamic force at azimuthal angles close to zero ($\approx 6\%$ of error). Again, this observation indicates that including the torsional degree of freedom in the structural solver is crucial for describing accurately the amplitude and dynamical behaviour of the aerodynamic quantities.

4.3 Power and thrust coefficients

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The aerodynamic loads previously presented are also useful to evaluate the power and thrust coefficients, defined as follows:

$$C_p = \frac{P_d}{\frac{1}{2}\rho A U_\infty^3}, \quad C_t = \frac{T_{aero}}{\frac{1}{2}\rho A U_\infty^2}, \tag{9}$$

where $A = \pi D^2/4$ represents the rotor area, P_d is the aerodynamic power transferred to the rotor and T_{aero} is the overall aerodynamic thrust on the turbine.

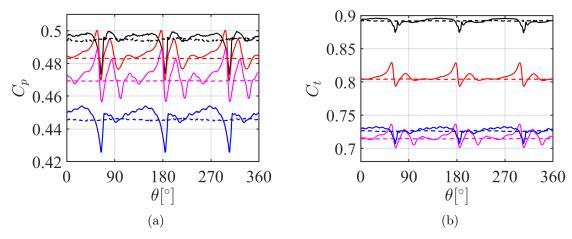


Figure 10: Phase-averaged power (a) and thrust (b) coefficients. CFD-CSD/OV: TN ——, RO ----. CFD-CSD/T: TN ——, RO ----. ElastoDyn: TN ——, RO ----. BeamDyn: TN ——, RO ----.

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Starting from the time history of C_p and C_t , we computed their phase-averaged evolution as reported in Figure 10. The periodic passage of the blades in front of the tower for the TN configuration produces a drop of the curves of about 10%. Eventually, the performance is restored to the value obtained in the RO case following the elastic dynamical behavior of the structure. The results reflect the dependency of the power and thrust coefficients on the edgewise aerodynamic force F_3 and the flapwise aerodynamic force F_2 at the 80% of the blade, respectively (see Figures 8c and 8b), which are strongly influenced by the presence of the tower. Notice that, also here, we can observe that the drop in the C_p curve appears to be rather similarly predicted by BEM and CFD, although the BEM prediction exhibits notable oscillations before and after the drop, whereas these are not present in the CFD results. A different behaviour was observed for the NREL 5-MW turbine (Bernardi et al., 2023), where this performance drop is considerably underestimated by the BEM computations. A possible factor that may contribute to this different behaviour may reside in the different relative geometry of the two wind turbines. Indeed, the flow induced by a thinner tower (in diameter units), as in the case of the 15-MW wind turbine, might be better described by a potential flow solution compared to the one induced by a thicker tower, as in the case of the 5-MW wind turbine, and may thus lead to the observed improved agreement between BEM and CFD results. Moreover, the differences in the flow impinging on the blade might also have an effect. In fact, in Bernardi et al. (2023) a uniform inflow was imposed. Whereas, in the present case, due to the shear imposed at the inflow and the limited distance from the ground of the tip of the blade (only $\approx 0.125D$ for the 15MW turbine), the blade is invested by a flow having a much smaller velocity compared to the given value of U_{∞} at hub height, further confirming the increased suitability of a potential flow solution upstream of the tower. Nevertheless, we should recall that this remains a very strong approximation, as also demonstrated by the differences in the forces and angles that have been observed in the previous section (see Figure 9, for instance).

It can be concluded that the performance loss induced by the passage in front of the tower is less pronounced for the 15 MW NREL turbine in the present configuration ($\approx 5\%$) compared to the 5

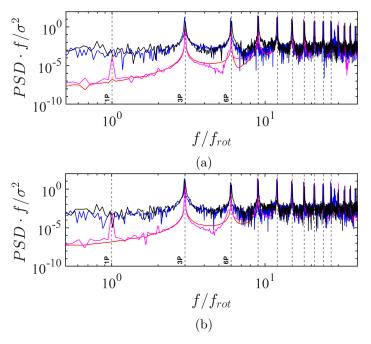


Figure 11: Power Spectral Density (PSD) of the power (a) and thrust (b) coefficients. The vertical dashed lines highlight the rotational frequency of the rotor $P = f_{rot}$ and the multiples of 3P, respectively. CFD-CSD/OV ——, CFD-CSD/T ——, ElastoDyn ——, BeamDyn

MW turbine in the configuration considered in Bernardi et al. $(2023)(\approx 15\%)$, with both BEM theory

452 and CFD yielding similar predictions in the case of the 15 MW turbine. However, it is worth recalling 453 again that Bernardi et al. (2023) considered a uniform inflow, whereas here the inflow is sheared. This 454 can be a possible reason for this different behaviour, since the lower wind speed in the lower part of 455 the rotor plane leads to a lower production in the bottom half of the rotor plane, where the tower is 456 located. This may cause a smaller performance drop due to the tower relative to the total produced 457 power. Therefore, the observed difference can be not only due to the change in turbine size, but also 458 due to the change in inflow conditions. 459 Moreover, the present results predict that, for very large rotors and a sheared inflow, the tower effect 460 on blade deformations is less pronounced than for smaller rotors, although it should yet be taken into 461 account for accurately describing the turbine's performance oscillations as it still represents a major 462 source of unsteadiness. 463 The average value of the power coefficient is much larger when the torsional deformation is neglected. 464 This feature is observed by both CFD and BEM approaches. However, one can observe that ElastoDyn 465 underestimates the value of C_p with respect to the corresponding non-torsional CFD model, while the 466 opposite is observed when comparing BeamDyn with the torsional CFD solver. This is probably due 467 to the fact that BeamDyn predicts higher values of the aerodynamic edgewise forces with respect to 468

the CFD-CSD/T approach, which are linked to a smaller torsional deformation as will be shown in

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figure 12f in the next section.

Figure 11 shows the premultiplied Power Spectral Density (PSD) of the power (Figure 11a) and thrust (Figure 11b) coefficients evolution. The PSD is normalized by the variance of each coefficient σ^2 and 472 plotted versus the frequency normalized by the rotational frequency of the rotor, f/f_{rot} . In both 473 cases, the CFD-CSD solvers seem to provide a richer representation of the aerodynamic coefficients, 474 capturing the full range of flow-structure interactions. Indeed, an examination of the low-frequency 475 behavior reveals that both quantities exhibit isolated low-frequency peaks when using the BEM-based 476 solvers, a phenomenon not observed with the CFD-CSD, where the low-frequency range is rather 477 broadband and does not present particular peaks. It is important to notice that the frequency 1P can 478 be directly linked to the frequency of the passage of the blade in front of the tower, but also to wind 479 shear loads on the blades. Concerning the first point, a potential flow solution as that used in the 480 BEM solver is keen to provide a simple, single-frequency response, whereas a complex, turbulent flow 481 is expected to result in a more broadband spectrum. Concerning the second point, we have to consider 482 that in LES, the power law profile is imposed at the inlet of the domain but it is free to evolve for 483 4 diameters before the wind turbine, altering in a non-trivial way the flow field and the consequent 484 frequency response of the blades. This outcome indicates that the BEM-based solvers tend to overcut 485 the power oscillations associated with low-frequencies that are not exactly equal to 1P or 2P. For all 486 solvers, however, the strongest PSD peaks are to be found at much larger frequencies (3P-6P-9P-12P), 487 as also observed by Pagamonci et al. (2023) by means of URANS aeroelastic simulations of the NREL 488 5-MW, the DTU 10-MW, and the IEA 15-MW turbines. One can also notice that the amplitude 489 associated with the 3P frequency appears to be consistently described by the two solvers, although 490 also in this range the BEM solver appears to overdamp the frequencies in between different peaks. 491 Moreover, a good agreement is evident between the two set of results concerning the value of the 492 frequencies and the level of the PSD for frequencies that are multiples of 3P. 493

4.4 Structural response

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This section presents the analysis of the structural dynamics. Figure 12 reports the phase-averaged dynamic response of the free extremity of the blade (left column) and the time-averaged deformation of the entire span (right column). Figure 12a shows how the out-of-plane deformation is mainly governed by the aerodynamic component of the force normal to the rotor plane and, hence, to the aerodynamic effects, heavily affected by the tower. In fact, it is visible how the tower placed at $\theta = 180^{\circ}$ produces a drop in the deformation, followed by an elastic dynamic response which restores the value far from the pointing-down position. The time-averaged maximum deformation predicted by the CFD-CSD/OV solver is 16% higher compared to the ElastoDyn module and 17% compared to BeamDyn (see Figure 12b). On the other hand, the same quantity predicted by the CFD-CSD/T solver is 17% lower compared to the ElastoDyn module and 13% compared to BeamDyn (see Figure 12b). This is consistent with the fact that including the torsional degree of freedom reduces the loads (see figure 8b) and the resulting deformation. Although the trend of deformation with respect to the blade span appears similar to previous predictions based on URANS (see Pagamonci et al. (2023)), the out-of-plane deformation is rather larger, reaching 16 m at the blade's tip. The amplitude of the deformation is however close to that obtained by Trigaux et al. (2024) using LES. Figure 12c depicts instead the in-plane deformation, which is mostly due to gravity. The results show that the shadowing effect of the tower does not influence this quantity. Furthermore, the discrepancies obtained

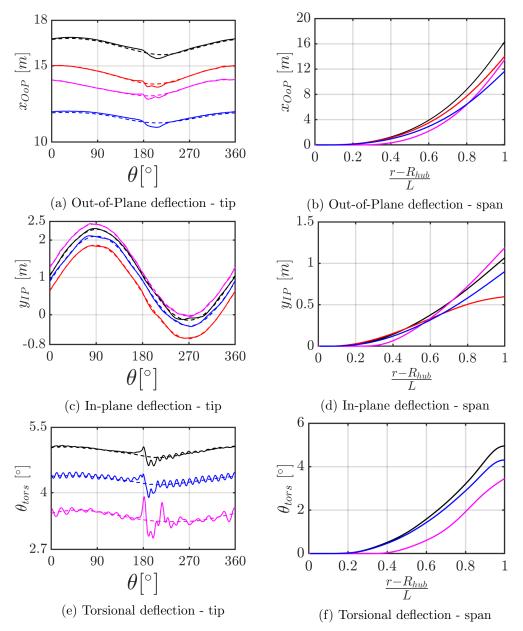


Figure 12: Phase-averaged deflections at the tip of the blade (left column) and time-averaged deflections along the blade span (right column). CFD-CSD/OV: TN ——, RO ----. CFD-CSD/T: TN ——, RO ----. ElastoDyn: TN ——, RO ----. RO ----.

between *ElastoDyn* and *BeamDyn* can be attributed to the lack of modes used by the former model to describe the translation in the edgewise direction (see Figure 12d). The discrepancy does not seem to be linked to the linearity of this model, as the result of the CFD-CSD/T solver, which is linear

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as well, is much closer to the BeamDyn results. Moreover, the results of the CFD-CSD/OV and the 515 CFD-CSD/T models are very close each other. It can be noticed that the amplitude of the oscillation 516 of the in-plane deflection is consistent with that reported by Trigaux et al. (2024) (see Figure 7b of 517 their paper, reporting an oscillation between ≈ -2.3 and ≈ 0.2), although the sign is opposite due to 518 the different frame of reference used. 519

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A further significant insight into the deformation phenomenon is provided by the torsional DoF. Figure 12e shows a comparison of the torsional angle at the tip with BeamDyn. Significant discrepancies can be observed between the LES and the BEM approaches, which cannot be reconducted to the different coupling procedures adopted by the models. On the one hand, BeamDyn and CFD-CSD/T both take into account the deformation angle in the coupling (Wang et al., 2016b), while in the CFD-CSD/OV solver the angle of attack depends only on the deformation velocity (see Equation 8). However, the gap between the BEM and the CFD-CSD/T curves is quite large, reaching approximatively 20% of the torsional deformation value. These differences likely arise from the combined effects of both aerodynamic and structural modeling approaches used in BEM and LES. This is confirmed by the time-averaged torsional deformation along the span reported in Figure 12f where the maximum percentual gap of BeamDyn reaches 29% for the CSD-CFD/OV, and 24% for the CFD-CSD/T. It is noteworthy that the lower torsional deformation resulting from BeamDyn leads to the higher aerodynamic loads observed in figure 8c. 532

Finally, figure 13 illustrates the Power Spectral Density (PSD) of the blade's tip deformation compo-533 nents for the TN configuration (which is characterized by more complex fluid-structure interactions). 534 The premultiplied PSD values are normalized by the variance of the signal, σ^2 , and plotted versus the 535 frequency normalized by the rotor frequency, f/f_{rot} . Spectral results have been corroborated through 536 use of the Welch and Lomb-Scargle PSD estimation algorithms. 537

Figure 13a shows the out-of-plane deformation, which we showed to be influenced mostly by the aerodynamic loading. The results indicate that, for all the numerical approaches used, the observed structural response does not exhibit a peak corresponding to the first flapwise natural frequency, suggesting that the intrinsic dynamics of the structure might play a less prominent role in the deformation process. A similar behavior is found in the results of Trigaux et al. (2024) (see figure 6 of the cited paper) for the same turbine and similar inflow conditions. Noticeably, all the numerical models recovered peaks at frequencies close to the (highly damped) second and third flapwise natural frequencies, but they appear to rather correspond to the 13^{th} and 26^{th} multiple of the rotational frequency (i.e., 13p and 26p). Both CFD-CSD solvers predict larger amplitude responses across a broad frequency range compared to OpenFAST, indicating a higher capability to capture complex flow interactions, including turbulence-induced vibrations. This effect is particularly pronounced at the lower frequencies, probably due to the large-scale three-dimensional structure of the flow impinging on the turbine, which is not captured by OpenFAST. These aspects seem to be under-represented in the ElastoDyn and BeamDyn solutions. Although the ElastoDyn curve aligns with both the CFD-CSD solvers at some key frequency peaks, it does not fully account for the fine-scale flow-structure interactions. On the other hand, the BeamDyn curve provides better agreement with the CFD-CSD solvers, especially at higher frequencies near the blade's natural modes, suggesting that BeamDyn captures more of the structural dynamics, particularly the aeroelastic response. Figure 13b shows the in-plane deformation, which is primarily influenced by gravity, centrifugal, and Coriolis forces acting on the blade. The

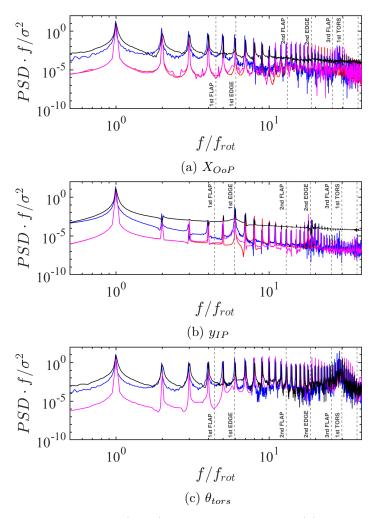


Figure 13: Power Spectral Density (PSD) of the out-of-plane (a), in-plane (b), and torsional (c) deformations of the blade. The vertical dashed lines represent the first 8 eigenfrequencies of the system. CFD-CSD/OV ——, CFD-CSD/T —— ElastoDyn ——, BeamDyn —

CFD-CSD solvers again demonstrate stronger low-frequency components.

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Figure 13c presents the torsional deformation for the CFD-CSD/T and BeamDyn solvers, excluding 558 ElastoDyn, which neglects the torsional DoF in the model. Additionally, also this quantity demonstrates that the CFD-CSD curves predict higher amplitudes at low frequencies. However, a good agreement between the two solvers is evident at higher frequencies, especially in the range around the first torsional eigenfrequency.

5 Conclusions

This study investigated the aeroelastic response of the IEA 15-MW wind turbine by employing a high-fidelity Computational Fluid Dynamics (CFD) solver that couples Large-Eddy Simulation (LES) with a Computational Structural Dynamics (CSD) solver. Two different CSD solvers are considered: the CFD-CSD/OV solver, in which the only structural quantity contributing to the definition of the angle of attack is the deformation velocity, and the CFD-CSD/T solver, in which the instantaneous torsional deformation is also considered when defining the local effective incidence. The results of the two CFD-CSD solvers are compared with those of traditional engineering solvers such as BeamDyn and ElastoDyn, both relying on Blade Element Momentum (BEM) theory. Two case studies were examined: a rotor-only configuration (RO) and one that included the tower and nacelle (TN). In the first instance, a flow analysis uncovered important considerations regarding wake entrainment. In particular, the study found that, for the considered turbine, impinged by a laminar sheared inflow, wake recovery is only slightly hindered by the presence of the tower. The entrainment of kinetic energy driven by the tower leads to higher turbulence levels in the near wake, but then result into a slightly decreased mixing behind the turbine, differently to what has been found for the NREL 5MW wind turbine, whose wake recovery was found to be promoted by the presence of the tower. This result requires further examination, as it appears counter-intuitive and has not yet been confirmed by other

In addition, the Power Spectral Density (PSD) of the power and thrust coefficients revealed that the CFD-CSD solver captures a broader range of flow-structure interactions, with a more broadband low-frequency response, compared to the BEM-based solvers. The isolated low-frequency peaks found in BeamDyn and ElastoDyn suggest that these solvers tend to over-simplify the aerodynamic fluctuations associated with phenomena such as wind shear and tower shadowing. For the large IEA 15-MW turbine, the performance drop caused by tower passage is not very pronounced and the resulting oscillations predicted by the BEM approach appear to be larger than the CFD-CSD solver.

Concerning the forces on the blade and the incidence angle, one can observe a rather good match between the CFD-CSD/OV solver and ElastoDyn, as well as between the CFD-CSD/T model and the BeamDyn solver. This is likely due to the presence – or not – of the torsional feedback, while non-linearities of the structural solver appear to have only a limited impact on the observed quantities. In agreement with previous studies, the results thus suggest that including the torsional degree of freedom in the structural solver is crucial for accurately describing the amplitude and dynamical behaviour of the aerodynamic quantities.

Moreover, it is observed that duly taking into account the torsional degree of freedom reduces the value of C_p . This feature is consistently observed by both CFD and BEM approaches. However, one can observe that BeamDyn predicts lower values of the torsional deformation and thus higher values of the aerodynamic edgewise forces with respect to the CFD-CSD/T approach, leading to a larger C_p value than that predicted by LES. All in all, it can be concluded that for the considered setup, the CFD-CSD solvers tend to exhibit larger amplitudes at lower frequencies with respect to BEM ones.

The structural response of the wind turbine blade has been assessed by comparing the out-of-plane, inplane, and torsional deformations obtained from the CFD-CSD solvers, *ElastoDyn*-based, and *Beam-*Dyn-based OpenFAST solver. In-plane deformation, influenced significantly by centrifugal forces, appears to be better captured by the CFD-CSD solvers, especially in the low-frequency range. Concerning the out-of plane deflection, large discrepancies are seen between the two CFD-CSD solvers, as well as between both BEM modules and the LES.

Our results underscore the importance of incorporating torsional deformation effects in the definition of the angle of attack and using high-fidelity aeroelastic models to ensure accurate predictions of wind turbine blade performance with a richer fluid dynamics. Whereas, the linearity of the structural model does not appear to have a strong effect on the aerodynamical quantities, deformations and loads. In general, the comparison of the results of the CFD-CSD solver with those of the engineering solver shows differences especially in the region behind the tower. The observed differences likely stem from the combined effects of differences in aerodynamic and structural fidelity, and cannot be uniquely attributed to one component alone.

Future work will explore the effect of turbulent fluctuations at the inlet to better investigate the impact of the atmospheric boundary layer on the aerodynamic forces, loads and deformations of the present turbine.

A Appendix A. Grid convergence study for LES

A grid convergence study was conducted to evaluate the sensitivity of the LES results to spatial and temporal resolution. Two further simulations were carried out using grids of different densities: a coarser mesh and a finer mesh, having approximately 40% less and more grid points than the former in each spatial direction, respectively. This allowed for a more detailed resolution of flow structures and aerodynamic quantities. Moreover, both simulations use the same CFL = 0.65 as the present grid. The average time step obtained and the other key parameters of different LES runs are summarized in Table A1.

| Parameter | Coarse Grid | Present Grid | Fine Grid |
|----------------------------|----------------------|----------------------|----------------------|
| Total number of cells | 1.31×10^{8} | 5.37×10^{8} | 1.36×10^{9} |
| Largest cell diagonal (m) | 8.1 | 5.0 | 3.5 |
| Smallest cell diagonal (m) | 3.9 | 2.5 | 1.7 |
| Actuator points per blade | 54 | 86 | 128 |
| Average time step (s) | 0.043 | 0.024 | 0.012 |
| Total number of threads | 320 | 512 | 768 |

Table A1: Comparison of the main parameters for different meshes.

The comparison in figure A2 shows that the results obtained using the coarse and fine grids are extremely close to each other along the entire blade span. In particular, the curves of the angle of attack are almost indistinguishable for the coarser and the reference grid, even in the outer portion of the blade, where stronger differences were expected due to tip effects and local three-dimensionality. Slightly larger differences are recovered between the reference and the finer grid, but only at low radius. In particular, for these two grids the maximum deviation of the incidence angle α between the two simulations at 80% of the span reaches a value of $\Delta \alpha_{max} \approx 0.2^{\circ}$, corresponding to a relative

difference of 1.6%. Whereas, the maximum deviation between the reference and the coarser grids at 80% of the blade span is $\Delta \alpha_{max} \approx 0.1^{\circ}$, corresponding to a relative difference of 1.5%. Similarly, the aerodynamic forces component distributions exhibit negligible variation between the reference and finer resolutions, and less than 1% relative variations between the reference and the coarser grids, confirming the overall consistency of the LES solution examined in the Sec. 4 with respect to mesh refinement.

These results indicate that the coarse grid already accurately captures the main aerodynamic features,

These results indicate that the coarse grid already accurately captures the main aerodynamic features, making the use of a finer mesh unjustified given its higher computational cost and minimal accuracy gain.

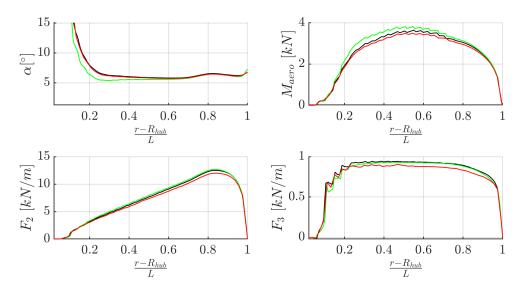


Figure A1

Figure A2: Average aerodynamic quantities along the blade obtained from the coarse grid (red line), the present grid (black line) and the finer grid (green line). (top left) Incidence angle, (top right) Aerodynamic pitch moment, (bottom left) flapwise aerodynamic force, (bottom right) edgewise aerodynamic force.

B Appendix B. Validation of the structural model

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The structural model for the IEA 15MW wind turbine has been cross-validated with many other aeroelastic numerical codes within the framework of the International Energy Agency (IEA) Wind TCP Task 47 TURBINIA (Schepers et al., 2025). In this IEA Task, a consortium of research institutions and industrial partners benchmarked their own aeroelastic codes on the IEA 15 MW wind turbine (Cacciola et al., 2025). Since we cannot report in this paper data from all these partners, we provide here a preliminary study was conducted to validate the structural model prior to coupling it with the CFD solver. Figure B1 shows the distributions of the structural and constructive properties along the

blade, which were utilized as input for the modal CSD analysis. A convergence study to determine the proper number of elements, N_e , (not reported here for brevity) was conducted, leading to the choice $N_e = 80$. Furthermore, the results of the present structural analysis were compared with those of five models including: the prismatic Timoshenko model without torsion (H2-PTNT); the Timoshenko model with a fully populated stiffness matrix (H2-FPM) from the study of Rinker et al. (2020); the 3D Finite Element Analysis (3D FEA) selected from Zhang et al. (2023); the ElastoDyn model; the BeamDyn model. Figure B2 shows the first 8 eigenfrequencies using the present method compared with the results of these models. The computed values of the modal frequencies appear to be consistent with the other results, although some discrepancies in the higher-order modes are observed. Moreover, an analysis of the most important modes was conducted: Table B1 provides the classification of the first 8 modes, whereas, Figures B3, B4, and B5 show the modal displacements for the first spanwise, edgewise, and torsional modes, respectively.

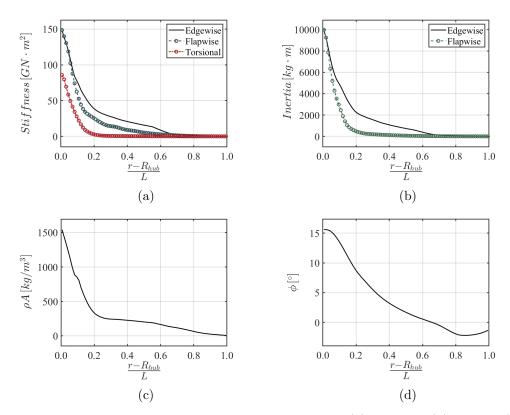


Figure B1: Structural properties of the blade along the span: (a) stiffness, (b) inertia, (c) density, (d) local twist angle.

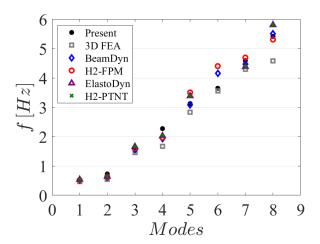


Figure B2: A comparison of the eigenfrequencies computed by different structural models.

| # | $f_n[Hz]$ | Mode |
|---|-----------|---------------|
| 1 | 0.5369 | 1st flapwise |
| 2 | 0.7267 | 1st edgewise |
| 3 | 1.577 | 2nd flapwise |
| 4 | 2.267 | 2nd edgewise |
| 5 | 3.113 | 3rd flapwise |
| 6 | 3.642 | 1st torsional |
| 7 | 4.571 | 3rd edgewise |
| 8 | 5.385 | 4th flapwise |

Table B1: Classification of the first 8 structural modes.

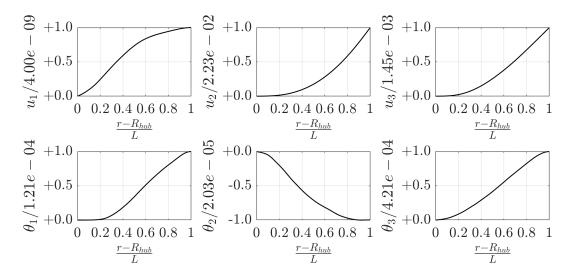


Figure B3: Mode 1 shape for all the DoFs.

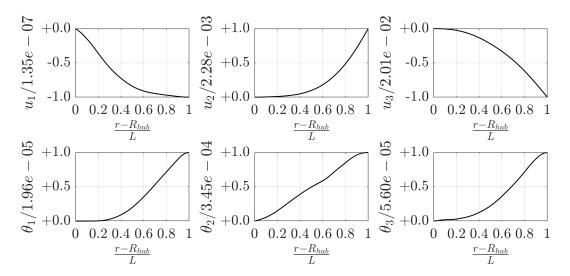


Figure B4: Mode 2 shape for all the DoFs.

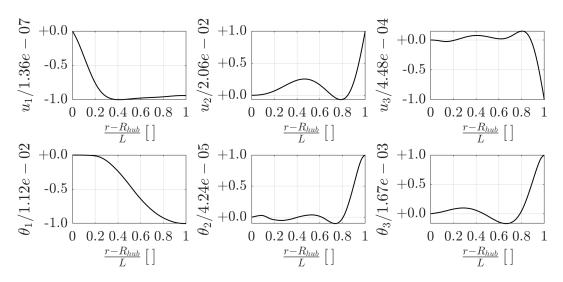


Figure B5: Mode 6 shape for all the DoFs.

- Author contribution. CB: Investigation, Writing Original draft, Formal analysis, Methodology, Software, Validation. SC: Conceptualization, Investigation, Writing Review & Editing, Supervision. FM:
 Methodology, Software, Validation. GDP: Formal analysis, Writing Review & Editing, Methodology, software. SL: Conceptualization, Software, Supervision. PDP: Conceptualization, Investigation,
 Writing Review & Editing, Supervision.
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