

Assessing the Accuracy of a Three-Year High-Resolution Mesoscale Wind Farm Wake Simulation with Lidar and Satellite Radar Data

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Abstract. The rapid expansion of wind farm installations in the North Sea results in an increased need for understanding their influence on the local atmosphere, as well as the interactions between them. Wind farm operation and power production are affected by wakes produced both within the wind farm and by upwind wind turbines. ~~To accurately estimate wind power production, it is essential to quantify the effects behind these~~ Accurately estimating these impacts requires robust mesoscale atmospheric modeling capable of capturing extended wind speed deficits ~~using mesoscale atmospheric modelling and their dependence on atmospheric stability~~. This study presents a three-year-long mesoscale analysis using the Weather Research and Forecasting (WRF) model at a horizontal resolution of ~~1 kilometer~~ one kilometer, a comparatively long and high-resolution configuration within the context of offshore wake research. The simulations are evaluated against four lidars located in the Southern Bight of the North Sea in the vicinity of the ~~large 3.7 GW~~ Belgian-Dutch offshore wind farm cluster, ~~illustrating that the model performs adequately~~ providing an extensive observational basis that covers upstream, intra-farm, and downstream flow conditions. Coupling the mesoscale atmospheric model with the Fitch wind farm parameterization (WFP) scheme significantly improves simulation accuracy, particularly in regions frequently affected by wake effects. An ~~analysis of the model performance under evaluation across~~ different atmospheric boundary layer ~~(ABL) stratification conditions stability regimes~~ shows that the model performs ~~better~~ best under less extreme stability ~~cases~~, while a ~~complementary evaluation detailed~~ assessment of upstream, ~~intra-farm~~ intra-cluster, and downstream wake characteristics ~~further highlights the benefits of using~~ highlights the added value of the Fitch WFP scheme ~~in WRF. In addition for multi-year offshore applications. Finally,~~ synthetic aperture radar images ~~are compared to model outputs for specific wake events, indicating that the wind farm parameterization from selected wake events are compared with the model output, demonstrating that the WFP~~ scheme effectively captures the wake structures at the analyzed timestamps. Together, these results provide one comprehensive long-term evaluation of offshore wake behavior in a dense wind farm cluster, helping to address the current gap in mesoscale wake studies.

1 Introduction

In recent years, wind energy has become one of the most promising electricity generation technologies for a sustainable energy system. Especially offshore, wind farms are growing in size and number, resulting in gigawatt-scale clusters being installed in each other's vicinity. Therefore, it is important to quantify the effects of wind farms both in terms of how their interaction impacts the operation and energy production, as well as their local influence on the atmosphere. These effects vary based on the predominant atmospheric conditions and wind characteristics.

One of the most pertinent tasks is the understanding and quantification of wake effects produced by wind farms. Wakes exert a substantial influence on downwind wind turbines, as they lead to decreased wind speeds and increased turbulence that affect both the power production and the fatigue of the wind turbine (Stanley et al., 2022; Jézéquel et al., 2024). ~~Wakes~~ Crucially, wakes are the dominant driver for power losses in offshore wind farms, reducing power extraction in the order of 10% to 20% compared to lone-standing turbines (Lee and Fields, 2021). Furthermore, especially for large wind farms, individual turbine wakes merge into wind farm wakes that have been shown to persist several tens of kilometers downstream of the wind farm, depending on the atmospheric conditions (Ali et al., 2023). As a result, offshore wind farms are affected by current and future neighboring farms, and reducing uncertainties on these interactions is becoming increasingly important for the efficient development of offshore wind energy.

High-fidelity simulations like large-eddy simulations (LES) can provide useful insights on the interaction between wind turbines and the atmospheric boundary layer (ABL), with different approaches for wind turbine representation being developed (Sorensen and Shen, 2002; Stevens et al., 2018; Stipa et al., 2024). However, computational cost for high-resolution LES remains very high, rendering them impractical for simulating large wind farm clusters over long periods. ~~Furthermore~~ In addition, performing LES under real atmospheric conditions increases the computational cost further as proper coupling with a mesoscale model is required (Haupt et al., 2023; Muñoz-Esparza et al., 2014; Kale et al., 2023). As a result, mesoscale numerical weather prediction (NWP) models continue to be the most cost-effective state-of-the-art tool to assess atmospheric conditions spanning a wide geographic area and a prolonged period. NWP models typically operate on horizontal grid spacings of 1 to 3 km, necessitating the use of different parametrization schemes to capture the effect of subgrid-scale physics such as convection, hydrometeor microphysics, radiation, surface interactions, and turbulence. Over the past years, many NWP models have also included parametrization schemes to account for the influence of the wind turbines in the ABL. An extensive description of these wind farm parametrization (WFP) schemes in NWP models can be found in the work of Fischereit et al. (2022a). In particular, although several alternatives have been developed (Volker et al., 2015; Ma et al., 2022a), the most widely used WFP scheme in NWP models is the method proposed by Fitch et al. (2012). Even though the scheme has significant limitations, e.g. on the turbulence kinetic energy (TKE) representation (Archer et al., 2020), the freestream wind estimation (Vollmer et al., 2024), and the inclusion of subgrid-scale wakes (Ma et al., 2022b), the original implementation has been shown to agree reasonably well with high-fidelity simulations (Archer et al., 2020; Peña et al., 2022; García-Santiago et al., 2024; Fischereit et al., 2022b), field measurements (Larsén and Fischereit, 2021; Ali et al., 2023; Fischereit et al., 2024), and turbine production data (Lee and Lundquist, 2017; Santoni et al., 2020; Sengers et al., 2025). Nevertheless, further validation studies over ex-

55 tended time periods are needed to reduce uncertainties in quantifying wind farm wakes and the resulting inter-farm interactions (Fischereit et al., 2022a).

The vast majority of WFP studies utilize the Weather Research and Forecast (WRF) model (Skamarock et al., 2019). WRF is an open source and widely used NWP model able to simulate complex atmospheric phenomena and extreme events (Larsén et al., 2019; Müller et al., 2024; Shenoy et al., 2021). It has been used in a variety of studies that estimate the influence of wind farm effects (see, e.g., García-Santiago et al., 2023; Pryor et al., 2019, 2020). More specifically, studies estimating the wind farm effects under different ABL stability conditions (~~Rosencrans et al., 2024; Palatos-Plexidas et al., 2024~~) (Rosencrans et al., 2024; Palatos-Plexidas et al., 2024; Cañadillas et al., 2020) have been performed. In addition, specific events like extreme winds (Pryor and Barthelmie, 2021), storms (Ivanova et al., 2025), and low-level jets are well reproduced by WRF at different locations across the globe (~~Vanderwende et al., 2015; Quint et al., 2025~~) (Vanderwende et al., 2015; Quint et al., 2025; Olsen et al., 2025). Although there are a few studies that simulate the wind farm effects using mesoscale models at 1 km or sub-kilometer scales under real atmospheric conditions (Gomez et al., 2024), long-term high-resolution mesoscale simulations and validations remain largely absent from the literature.

The current work presents an assessment of model performance and analysis of wake effects from a ~~three-year-long~~ three-year-long high-resolution (1 km) WRF simulation of the Southern Bight of the North Sea, with a specific focus on the 3.7 GW Belgian-Dutch wind farm cluster. This cluster consists of several high-density wind farms installed next to each other, making it the largest offshore cluster operational today, hence resulting in a prime test case for studying wind farm wakes. Extending the analysis over a three-year period enables a comprehensive characterization of seasonal patterns and temporal variability.

The study is driven by two primary objectives ~~-.The first objective is that address notable gaps in current offshore wake research. The purpose of this study is not to validate the simulation-dataset-Fitch parameterization in isolation, but rather to assess the long-term predictive performance of the full WRF-Fitch modeling system for offshore wake dynamics in an operationally relevant environment. First, we assess the three-year WRF-Fitch simulation performance using lidar measurements in the vicinity of the wind farm cluster, with particular attention to positioned both within and around the Belgian-Dutch cluster, enabling an evaluation of model performance under varying ABL stability conditions. The analyzed lidar probes are strategically located and enable to evaluate the wind fields associated with varying wind directions inside and outside the cluster. The second objective is to evaluate model performance at selected timestamps by comparing simulation wind speeds with synthetic aperture radar (SAR) data. The assessment is conducted both qualitatively through analysis of the full two-dimensional wake structures and quantitatively, by examining the transect connecting the analyzed lidar locations. This approach enables a detailed evaluation of wind speed deficits regimes. This is particularly relevant given that long-term, wake validations at 1 km (assessed under different stability regimes) resolution remain rare, especially over multi-year periods and in densely built offshore environments. The strategic placement of the lidar probes allows us to assess how the model represents inflow conditions, intra-cluster wake dynamics, and downstream recovery for different wind directions and model accuracy relative to SAR imagery and available lidar measurements. wind speed regimes, and the availability of four lidars spanning upstream, downstream, and intra-farm positions provides a uniquely comprehensive observational basis for this~~

90 evaluation. Second, we evaluate the performance of WRF for a set of specific wake events by comparing the simulated wake signatures with satellite-retrieved wind fields. This dual comparison, quantitative through lidar transects and qualitative through two-dimensional SAR wake structures, provides a robust, multi-sensor estimation of wake deficits, blockage effects, and model skill. Together, these objectives provide a comprehensive long-term evaluation of offshore wake behavior in a high-density wind farm cluster.

95 The remainder of the study is structured as follows. Section 2 outlines the methodology, including the WRF model setup, ~~definitions of performance metrics, and the~~ classification of ABL stability. ~~Next, the measurement datasets used, and the definitions of performance metrics.~~ Section 3 highlights the simulation results, including the overall atmospheric conditions and model performance ~~assessment with~~ assessed against lidar data under varying ~~conditions of stability, seasonality, and wake loss intensity~~ stability conditions, wind speed magnitudes, and specific events. Finally, ~~Section~~ section 4 summarizes the

100 main findings of this study.

2 Methodology

This section outlines the methodology used to create and analyze the high-resolution dataset. First, the configuration of the WRF model is described. Next, the definition and the classification of atmospheric stability regimes is introduced. Finally, the lidar observations and the SAR images used for model performance assessment are presented, followed by the evaluation

105 metrics that are applied in this study.

2.1 WRF model setup

Simulations were performed with version 4.5.2 of the WRF model (Skamarock et al., 2019) over a period of three years: 2021, 2022, and 2023. The initial and boundary conditions are derived from 30 km spatial resolution ERA5 hourly reanalysis data (Hersbach et al., 2020). Three nested square domains are employed with grid resolutions of 9, 3, and 1 km, respectively, as depicted in Figure 1. Furthermore, one-way nesting is applied to prevent any potential noise generated within the innermost domain from propagating into the parent domains. In the vertical direction, 80 ~~levels were non-equidistant levels~~ are used up to 50 hPa, while the first 30 levels are densely distributed starting from approximately 5 meters up to 320 meters height, with an average vertical resolution of 11 m. Adaptive time stepping is used with a target ~~Courant-Friedrichs-Lewy~~ Courant-Friedrichs-Lewy number of 0.84 and 0.6 for the horizontal and vertical directions, respectively. In addition, vertical

115 velocity damping is enabled to ensure robustness and stability during the ~~year-long~~ multi-year runs using a Rayleigh damping layer with a depth equal to 5000 meters from the model top and a damping coefficient of 0.15 ms^{-2} . Results of the high-resolution domain ~~d03-D03~~ are processed every 10 minutes for comparison to lidar data. The model physics configuration is based on the New European Wind Atlas (NEWA) setup (Hahmann et al., 2020; Dörenkämper et al., 2020) and is presented in Table 1. The cumulus scheme is activated only at the outermost domain of 9 km resolution. Regarding the planetary boundary

120 layer (PBL) turbulence modelling, the MYNN (Nakanishi and Niino, 2006) scheme is used, as it is the only scheme available in WRF v4.5.2 capable of advecting the TKE produced by the WFP as explained below. Note that, rather than performing a

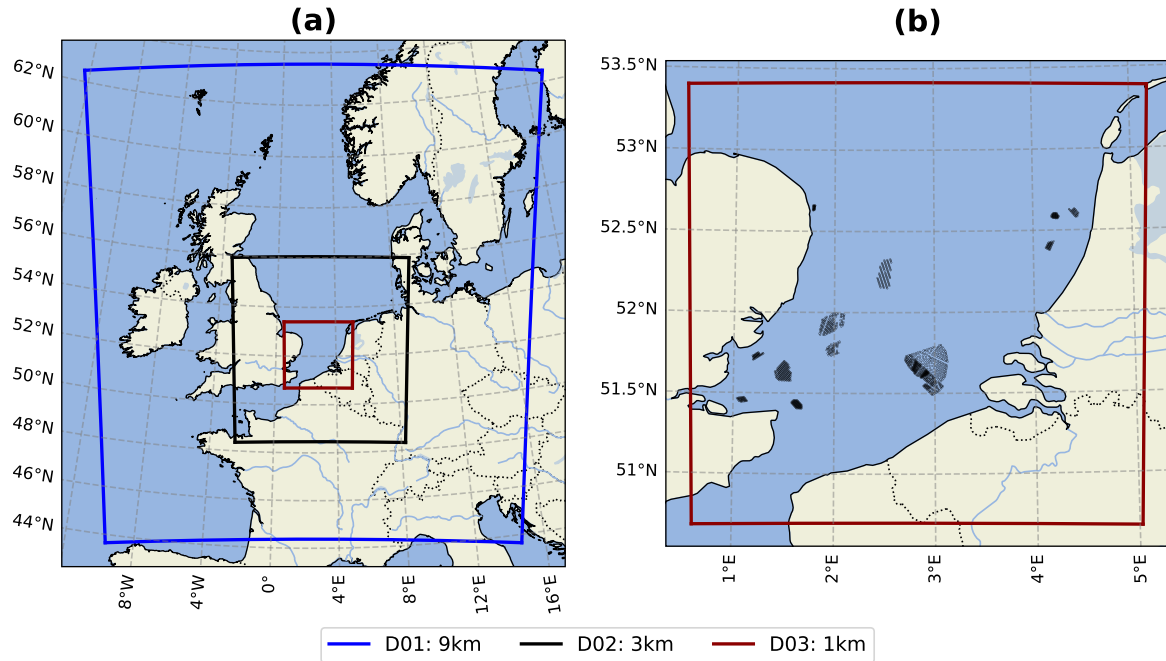


Figure 1. (a): Map of the three nested domains used for the WRF simulations, with a horizontal resolution of 9 km (D01, blue box), 3 km (D02, black box) and 1 km (D03, red box). (b): Zoom on the high-resolution innermost domain (D03), including the simulated wind turbines (black dots).

specific sensitivity study to optimize model performance for the location of interest, a single WRF configuration, close to the well-known NEWA setup, is chosen in order to evaluate typical out-of-the-box performance of the model against measurements.

Table 1. WRF physics parameterization schemes selected for this study, along with their associated references.

Parameterization	WRF Scheme	Reference
Planetary Boundary Layer (PBL)	MYNN 2.5 level	Nakanishi and Niino (2006)
Surface Layer Model	ETA Similarity	Monin and Obukhov (1954)
Land Surface Model	NOAH LSM	Mukul Tewari et al. (2004)
Cumulus	Kain-Fritsch	Kain (2004)
Microphysics	WSM5	Hong et al. (2004)
Radiation	RRTMG	Iacono et al. (2008)

2.1.1 Wind Farm Parametrization ~~farm parametrization~~

For this study, the WFP scheme proposed by Fitch et al. (2012) is used. The influence of turbines on the atmosphere is described by imposing a momentum sink in the mean flow, which enables the conversion of a fraction of the kinetic energy (KE) into electricity, while the remaining KE is transformed into TKE. The WRF model is executed with and without wind farm parameterization activated (hereafter WF and NWF, respectively) within a single model run, using two identical ~~d03-D03~~ domains, to isolate wake effects. The study focuses on the investigation of the Belgian-Dutch cluster, however, nearby offshore wind farms in the Southern Bight of the North Sea, i.e., in the United Kingdom and in the Netherlands, are included in the simulations. The locations of all the wind turbines included in the simulations are obtained from the study of Hoese et al. (2022). The wind farms are depicted in Figure ~~1(b)-1b~~, and they are exclusively simulated on the highest resolution domain. The principal equations for describing the ~~wind farms influence~~ influence of the wind farms on the mean flow in a discrete Cartesian computational cell i, j, k are defined as

$$\frac{\partial |V|_{ijk}}{\partial t} = - \frac{N_t^{ij} C_T \left(|V|_{ijk} \right) |V|_{ijk}^2 A_{ijk}}{2(z_{k+1} - z_k)} \underline{ec}, \quad (1)$$

$$\frac{\partial P_{ijk}}{\partial t} \underline{\frac{\partial TKE_{ijk}}{\partial t}} = \frac{N_t^{ij} C_P \left(|V|_{ijk} \right) |V|_{ijk}^3 A_{ijk}}{2(z_{k+1} - z_k)} \underline{\frac{N_t^{ij} C_{TKE} \left(|V|_{ijk} \right) |V|_{ijk}^3 A_{ijk}}{2(z_{k+1} - z_k)}} \underline{ec}, \quad (2)$$

$$\frac{\partial TKE_{ijk}}{\partial t} \underline{\frac{\partial P_{ijk}}{\partial t}} = \frac{N_t^{ij} C_{TKE} \left(|V|_{ijk} \right) |V|_{ijk}^3 A_{ijk}}{2(z_{k+1} - z_k)} \underline{\frac{N_t^{ij} C_P \left(|V|_{ijk} \right) |V|_{ijk}^3 A_{ijk}}{2(z_{k+1} - z_k)}}. \quad (3)$$

These equations describe the change in horizontal wind speed $|V|$, the wind power production P , and the turbulence enhancement TKE due to wind turbines, where z_k defines the height at model level k , and A_{ijk} is the cross-sectional rotor area of one wind turbine between the height levels k and $k + 1$. Furthermore, N_t^{ij} is the ~~amount~~ number of turbines located within cell (i, j) . The thrust coefficient C_T and power coefficient C_P depend on the wind turbine type and are obtained from a mix of public and confidential data. The TKE coefficient is defined as ~~$C_{TKE} = \alpha(C_T - C_P)$~~ $C_{TKE} = \alpha(C_T - C_P)$, with $\alpha = 1$ in the original Fitch implementation, driven by the idea that momentum lost by the mean flow, which is not converted to electrical power, is transformed into turbulence. However, it was found that this can lead to a significant overestimation of the TKE compared to high-fidelity simulations (Archer et al., 2020). ~~Though there is still significant debate on~~ Although there remains significant debate over the appropriate value ~~for~~ of α (Larsén and Fischereit, 2021; García-Santiago et al., 2024), this study uses the current default value in WRF, i.e., $\alpha = 0.25$. ~~Turbulence advection is activated in the high-resolution domains~~ Last, ec is the energy correction factor that ensures that the vertically distributed extraction matches the turbine power curve at hub height (adapted from the WRF source code). The wind speed deficit due to the wind turbine influence is defined as the normalized difference between the unperturbed and the ~~wind-farm-affected wind~~ wind farm-affected wind speed, i.e., $\Delta U_{wake} = U_{NWF} - U_{WF}$ $\Delta U_{wake} = (U_{NWF} - U_{WF}) / U_{NWF} \times 100$.

2.2 Atmospheric ~~Boundary Layer~~ boundary layer stability

155 The stability conditions in the lower layers of the ABL can be assessed by analyzing temperature, wind speed, and surface heat fluxes (Stull, 2015). These variables are closely associated with atmospheric turbulence and the resulting wake mixing. In this work, the atmospheric stability is characterized by the value of ~~Monin-Obukhov (MO)~~ Obukhov length L (Monin and Obukhov, 1954), as retrieved from the PBL scheme ~~in the inverse MO length via the inverse L~~ (RMOL) variable. ~~The MO~~ Obukhov length compares how shear and buoyancy contribute to the production and dissipation of TKE, i.e.,

$$160 \quad L = -\frac{u_*^3 \bar{\theta}_v}{\kappa g (\overline{w'\theta'_v})_s}, \quad (4)$$

where u_* is the friction velocity, $\bar{\theta}_v$ is the mean virtual potential temperature at the first model level above the surface (approximately at 5 m), $\kappa = 0.41$ is the von Kármán constant, g is the gravitational acceleration and $(\overline{w'\theta'_v})_s$ is the surface virtual potential heat flux. Stable conditions are present when $L > 0$, when shear production and buoyancy destruction counteract, leading to limited turbulence and intermittency. On the contrary, when $L < 0$, buoyancy enhances turbulence, resulting in
165 stronger vertical motion and mixing. In neutral conditions, when $|L| \rightarrow \infty$, buoyancy has a negligible effect and turbulence is driven solely by shear. Besides the main stable, unstable, and neutral conditions, four additional ABL stratification categories as defined in Table 2 are considered in the analysis, seeking to deliver a more comprehensive representation of the stability conditions. This approach is similar to the work of ~~Gryning et al. (Gryning et al., 2007)~~ Sathe et al. (2011), and has been implemented in the studies of ~~Olsen et al. (Olsen et al., 2022) and Palatos-Plexidas et al. (Palatos-Plexidas et al., 2024)~~.
170 Olsen et al. (2022) and Palatos-Plexidas et al. (2024).

Table 2. Atmospheric stability classes. ~~Monin-Obukhov~~ Obukhov length L values are ~~calculated in~~ assessed from WRF ~~using Equation simulations~~ (4) and seven classes are selected (~~Gryning et al., 2007~~), adapted from the work of Sathe et al. (2011).

Stability classes	Monin-Obukhov <u>Obukhov</u> length values (m)
Very stable	$0 < L \leq 50$
Stable	$50 < L \leq 200$
Stable-Neutral	$200 < L \leq 500$
Neutral	$ L > 500$
Unstable-Neutral	$-500 < L \leq -200$
Unstable	$-200 < L \leq -100$
Very unstable	$-100 < L \leq 0$

2.3 Offshore ~~Observations~~ observations

There are two ~~observations sources that are~~ sources of observations used in this work, and they are presented in this section. Initially, lidar profile measurements are employed to assess model performance throughout the entire analysis period. Subse-

175 quently, Synthetic Aperture Radar (SAR) data from the Southern Bight of the North Sea are utilized to compare and validate the model-assessed wakes at specific ~~timestamps~~events.

2.3.1 Lidars

Model performance is evaluated against ten-minute average wind speed and wind direction measurements from four vertical profiling lidars located in the Southern Bight of the North Sea, close to the Belgian-Dutch wind farms cluster. As discussed
180 below, considering the wind rose at this site, the locations of the lidars (see Figure 2) provide a unique opportunity for assessing wake effects. Details on their location and the operation period during the simulation time window are described in Table 3. The following lidars are considered:

- WHi: The Westhinder (WHi) lidar is a ZX 300M installed on the Westhinder (MP7) survey platform located approximately 40 km southwest of the Belgian-Dutch cluster, close to the French border in Belgium. The lidar was installed in
185 August 2021 and is operated by the von Karman Institute for Fluid Dynamics (Glabeke et al., 2023). In this study, we utilize data from the campaign between 4 August 2021 and 18 July 2022. The lidar measures at 11 different heights, i.e., 34.5, 44.5, 62.5, 79.5, 104.5, 124.5, 149.5, 174.5, 224.5, 274.5, and 324.5 mTAW. Measurement heights are in meters~~sa~~above the Tweede Algemene Waterpassing (mTAW), implying that the average sea level at low tide in Ostend (Belgium) is used as the zero level. This value lies 2.3 m below mean sea level.
- EPL and LEG: Northeast of the cluster, two more lidars are installed on the Europlatform (EPL) and Lichteiland Goeree (LEG) platforms, respectively. Data is provided by the Wind Energy Research Group of TNO, ~~who~~which operates the lidars (Verhoef et al., 2020; Bergman et al., 2022). LEG features a Leosphere WindCube lidar v2.1 providing measurements at eight heights, i.e., 62, 90, 115, 140, 165, 190, 215~~,~~, and 240 m above mean sea level. EPL is equipped with a ZX 300M lidar (Verhoef et al., 2020), with data provided at 63, 91, 116, 141, 166, 191, 216, 241, 266, and 291 m above
195 mean sea level.
- BSB: Inside the cluster, data from the ZX 300M lidar installed at the TenneT platform Borssele B (BSB) and operated by the KNMI is used (Knoop and de Jong, 2023), with measurements at 11 heights, i.e., 59, 83, 108, 117, 139, 164, 190, 201, 224, 244, and 294 m above mean sea level.

Considering the prevalence of southwesterly and, to a lesser extent, northeasterly wind directions at this site, the combination
200 of WHi, BSB, EPL, and LEG provides~~a~~a suitable alignment to include a freestream, intra-cluster wake, and far wake observation for these wind directions. All lidar observations come in the form of 10-minute averages. Both lidar measurements and model output are interpolated to a reference hub height of 107 ~~m-height~~meters above ground level, corresponding to the hub height of many wind turbines within the domain of interest.

Table 3. Description of the lidars used in this study. Data availability is expressed as the percentage of time each lidar was operational relative to the full simulation period (~~2021-2023~~2021-2023). Timestamps of missing data are also accounted for in the table.

<u>Lidar</u>	<u>Location</u>	<u>Operational period in WRF time window</u>	<u>Data-availab</u>
Wind-Wind-Speed-Direction -heightWesthinder (WHi)	51°23'18.74"N, 2°26'16.18"E	August 2021 - July 2022	
Borssele B (BSB)	51°43'34.90"N, 2°57'56.09"E	January 2021 - September 2023	
Europlatform (EPL)	51°59'52.51"N, 3°16'29.32"E	January 2021 - December 2023	
Lichteiland Goeree (LEG)	51°55'60.00"N, 3°40'00.00"E	January 2021 - December 2023	

^a Data availability refers to the timestamps for which wind speed and wind direction measurements overlap. The table also presents the final number of timestamps retained for analysis after applying the filtering procedure described in section 2.3.3.

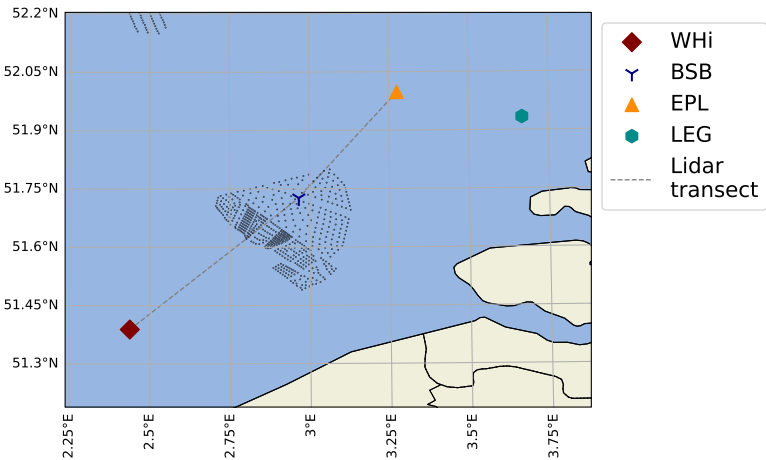


Figure 2. ~~Locations of~~Measurement locations in the domain of interest. Black dots indicate turbine locations included in the WRF simulations.

205 **2.3.2 SAR ~~Data~~data**

The SAR data used in this study ~~are were~~ retrieved by the Sentinel-1 European Space Agency (~~ESA~~) mission. More specifically, there are two satellites-, Sentinel-1A (~~2014-present~~2014-present) and Sentinel-1B (~~2016-2021~~-2016-2021), equipped with C-band Synthetic Aperture Radar (SAR) instruments operating at 5.405 GHz. ~~Both, and both~~ satellites follow a sun-synchronous polar orbit at an altitude of 693 ~~, with a repeat cycle of six days~~ (Hasager et al., 2024). ~~Over the km~~ (Hasager et al., 2024)

210 ~~. Focusing on the area of interest, including the Belgian-Dutch wind farms cluster in the~~ Southern Bight of the North Sea, ~~as well as additional upstream and downstream areas to study potential wake structures,~~ the analyzed time instances occur approximately at 06:00 UTC ~~and every twelve days, and at 17:40 UTC every six days, respectively~~ (Sentinel-1A, ~~respectively, SAR provides wind speed values at 2021-2023~~). The operation of Sentinel-1B during 2021 provided an additional set of ~~overpasses at around 17:32 UTC every six days. This corresponds to approximately 8 to 10 meter height and the pixel has~~

215 ~~a resolution of 500 meters~~SAR snapshots per month over the area of interest during the analyzed period. The wind speed is

calculated as a reflected signal, therefore it depends on the surface roughness variations and the terrain characteristics. The data are accessed through the [at 10-meter height is then estimated by applying the CMOD5N geophysical model function \(Hersbach et al., 2007\), as explained also in the work of Siedersleben et al. \(2020\). This indirect retrieval method assumes that radar backscatter from the sea surface, which reflects centimeter-scale waves generated by instantaneous wind stress, can be converted into wind speed at 10-meter height \(Ahsbals et al., 2017, 2018\). The wind fields are provided at a 500-meter pixel resolution through the Global Wind Atlas Science Portal of the Danish Technical University \(DTU\) Wind Energy Department \(<https://science.globalwindatlas.info/#/map/satwinds> last access: 30 July 2025\).](#)

2.3.3 Data Filtering

Two different types of filtering are used for the lidar measurements and the SAR data, respectively. For the lidars, we apply a threshold and discard wind speed values outside the range of $[0.5, 70] \text{ ms}^{-1}$. The lower bound was set to discard very low wind speeds in which the wind direction becomes ill-defined. A similar approach was taken by Pentikäinen et al. (2023). It was verified that this bound does not significantly impact wind speed validation results. The upper bound discards spuriously high measurements. The resulting interval retains relevant wind speed values for wind energy purposes, including wind speeds below cut-in and above cut-out. [The same thresholds are applied to the WRF wind speeds in both the NWF and WF simulations \(discarding approximately 0.3% of the WRF timestamps\). To avoid 180° wind direction ambiguity in the lidar data, we exclude instances exhibiting abrupt directional shifts greater than 120, as these are considered non-physical. Although such outliers could alternatively be corrected using nearby observational sources or WRF output, we opt to discard them entirely to ensure a more robust and reliable observational dataset.](#) This filtering results in an additional data removal of approximately of 1-2% of the total values presented in Table 3, depending on the location. ~~In parallel, the same filtering is applied to the WRF wind speeds in both the NWF and WF simulations (discarding approximately 0.3% of the WRF timestamps).~~ We then use the common timestamps of both filtered lidar and WRF datasets for evaluating both wind speed and wind direction.

The SAR data are polluted by wind turbines and ships in the area of interest, creating local outliers in the retrieved wind fields. In this case, we use a Hampel filter to detect the outlier values (Hampel, 1971). This method detects localized outliers of a series of data $x = \{x_1, x_2, \dots, x_n\}$ using the median absolute deviation (MAD) in a sliding window of size W_i . The median value m_i is computed across the sliding window and the MAD is defined as: $\text{MAD}_i = \text{median}(|x_j - m_i|)$, where x_j are the values in the sliding window W_i . The MAD is scaled to be comparable to the standard deviation for Gaussian data as: $\sigma_i = 1.4826 \cdot \text{MAD}_i$. A point x_i is considered as an outlier if $|x_i - m_i| > n_\sigma \cdot \sigma_i$. In this study, to detect the outliers, we use a sliding window $W_i = 3$ and set $n_\sigma = 3$ to prevent excessive outlier detection and ensure robustness without over-filtering the data.

2.3.4 Evaluation metrics

Different evaluation metrics are used to provide a comprehensive understanding of model performance. More specifically, the bias, the Centered Root Mean Squared Error (cRMSE), the Pearson correlation coefficient (r), and the Earth Mover's Distance (EMD) are computed for the wind speed and the wind direction. The mathematical definitions of these metrics are provided

in Appendix A1. The same metrics have been employed in several studies to evaluate model performance in calculating wind fields (Rosencrans et al., 2024; Olsen et al., 2025).

The bias score measures the systematic error between the simulations and the observations, indicating a consistent overestimation (positive bias) or underestimation (negative bias). The cRMSE is used to quantify the average error magnitude between the model and the lidars, emphasizing the variability around the mean value. The EMD evaluates the similarity between two distributions by calculating the minimum cost required to transform one distribution into another, thereby facilitating the comparison of the overall shape and distribution of predicted and observed wind speed and wind direction data. The Pearson correlation coefficient (r) measures the linear relationship between predicted and observed values. While bias, cRMSE, and EMD values closest to zero indicate better model performance, the Pearson correlation coefficient (r) ranges from -1 to 1, with values closer to 1 signifying a stronger direct linear relationship between the model and the lidar measurements.

To compute means ~~on~~of the wind direction, the circular ~~means-are-mean is~~ applied (Mardia and Jupp, 2009). The cRMSE equation for circular variables (A6) has been adopted from the study of Rosencrans et al. 2024. Instead of the Pearson correlation for linear values, the circular-circular correlation ρ is used (Mardia and Jupp, 2009). All metrics are computed using the built-in functions of the NumPy (Harris et al., 2020) and SciPy (Virtanen et al., 2020) Python packages. Furthermore, the ~~wasserstein-circle function-by~~ wasserstein_circle function from the Python Optimal Transport (Flamary et al., 2021) package is used to calculate the EMD for the wind direction.

Last, for the SAR transects, we compute the mean absolute error, $MAE = \sum_1^n |U_{SAR} - U_{WRF}|$, where n is the number of points across the upstream, intra-farm, and downstream regions of each transect (70 points in total after regridding the SAR and WRF data). In addition, for the same time instances, we evaluate the point-wise absolute error, $AE = |U_{lidar} - U_{WRF}|$, using the lidar observations as reference.

3 Results

This section discusses the simulation results and compares them to observations. First, ~~Section~~section 3.1 investigates the atmospheric conditions during the simulation period, focusing on dominant stability regimes and wind roses. Next, ~~Section~~section 3.2 compares model results to lidar observations. In addition to the validation of the full three-year dataset, the impact of stability on model performance is quantified. Further, wind fields along the lidar transect (see Figure 2) are analyzed to focus more specifically on wake-wind speed deficits (Section 3.2.3) and blockage (Section 3.2.4). Finally, ~~Section~~section 3.3 presents a comparison ~~of simulation results to SAR observations~~between WRF and SAR data for four specific events.

3.1 Atmospheric ~~Conditions~~conditions

Two main atmospheric characteristics are considered for the investigation, the ~~MO-stability~~Obukhov length (Equation (4), and Table 2) and the wind fields presented as wind roses, assessed ~~in-at~~ the four lidar locations. All results presented in this study use wind speed and direction rotated to Earth-fixed coordinates. Furthermore, only the horizontal wind speeds (hereafter referred to as wind speeds) are analyzed both in the measurements and the models. Figure 3 illustrates the monthly-averaged ~~MO-L~~

distributions for the years 2021 (a), 2022 (b), and 2023 (c). The ~~MO-values~~ values of L are calculated using WRF at the BSB lidar probe ~~both in, for both~~ the NWF (left bars indicated with 'o') and WF (right bars indicated with 'x') simulations. Despite the intra-annual variability in ABL stratification, the monthly ~~MO- L~~ distributions indicate that very unstable conditions prevail over the ~~three-year-long~~ three-year-long analysis. Peaks of the very unstable atmospheric conditions predominantly occur in
285 January, as well as during late summer and autumn.

Stable and very stable atmospheric conditions are primarily observed from late winter through early summer, while their occurrence is significantly reduced during autumn. Specifically, June 2021, May 2022, and June 2023 exhibit notably high frequencies of stable and very stable atmospheric conditions. Furthermore, a significant number of neutral cases is also observed. The frequency of neutral or near-neutral conditions is associated with strong winds, which enhances the importance of
290 shear effects over buoyancy. For example, in February 2022, severe storms occurred (Ivanova et al., 2025), resulting in a higher frequency of neutral events over the Southern Bight of the North Sea.

Overall, the predominance of unstable to very unstable events has ~~also been highlighted in various studies in the last decade.~~ several studies over the past decade. For example, Archer et al. (2016) demonstrated that the marine ABL ~~is mostly unstable in along~~ the U.S. northeastern coast was mostly unstable during a 2003-2011 measurements campaign. Similar ~~conditions have been mentioned in the work of Rosencrans et al. (2024) analyzing the ABL stratification on the Rhode Island-Massachusetts area in a WRF execution from September 2019 to September 2020.~~ conclusions for the North Sea have been reported in recent WRF-based studies (Porchetta et al., 2024; Palatos-Plexidas et al., 2024). However, it is important to ~~highlight that the intra-annual MO length distributions differ, as ABL stability conditions are highly dependent on the area~~ note that ABL stability strongly depends on the region and period of interest. ~~Last, focusing on the North Sea, analogous conclusions have been reached in the North Sea using WRF simulations in recent works (Porchetta et al., 2024; Palatos-Plexidas et al., 2024).~~ For instance, Rosencrans et al. (2024) found an almost equal mix of unstable and stable conditions, with relatively few neutral cases, in the Rhode Island-Massachusetts area based on WRF simulations from September 2019 to September 2020.
295
300

In addition to the intra-annual stability distributions in the BSB location, the influence of the wind turbines on the ABL stratification should be addressed. The inclusion of wind turbines affects the intra-farm ABL stratification, resulting in an
305 increase of 5 to 15% of the very unstable events during the three-year period. In addition, an increase in very stable instances is observed, while neutral and close-to-neutral cases are slightly reduced. The increase in very unstable and very stable cases may be attributed to the wind farm-induced wake, which leads to lower wind speeds and, consequently, reduced friction velocity magnitudes u^* .

Figure 4 illustrates the wind roses from the WF simulations (top), as well as the lidar-derived wind roses (bottom) at the
310 analyzed locations. The investigation over the three-year period indicates that the predominant wind direction at all locations is consistently from the southwest. At the WHi location, WRF provides a slight shift to westerly wind direction compared to the lidar observations. A similar trend is noticed in the cases of LEG and EPL locations, where events between southwest to west wind directions are more prevalent in the model. Similar behavior in WRF has been reported in the work of Kalverla et al. (2019), where winds were 10° clockwise-biased. At the BSB probe, the wind rose trends align between the model and
315 the measurements, offering a highly accurate comparison with the lidar data.

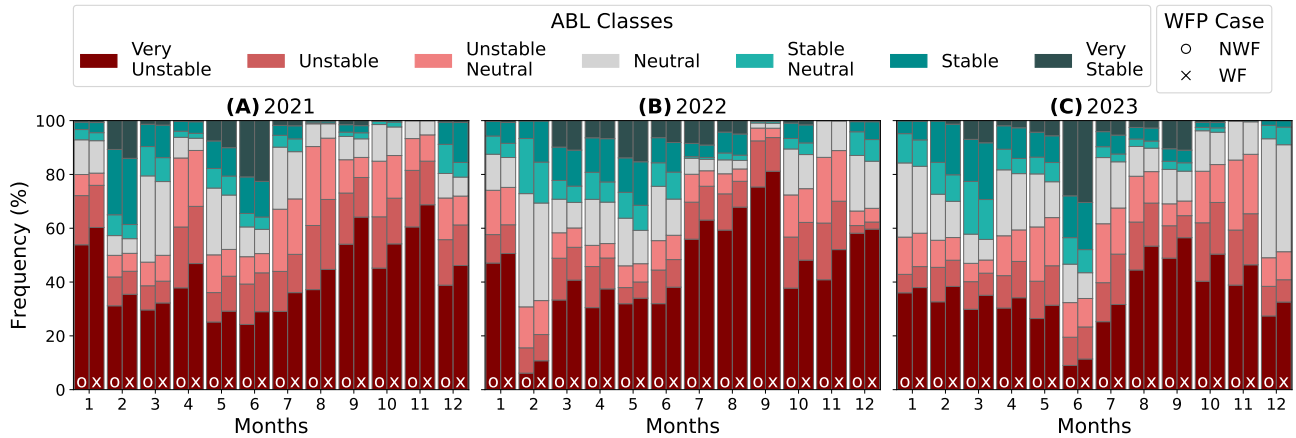


Figure 3. ABL classification based on [the](#) WRF-estimated [MO-length- \$L\$ values](#) at BSB location over the three-year simulation period. The stability classes are described in Table 2. On the y-axis, the frequency of each ABL condition is depicted, and on the x-axis, the months of each year, from 1 (January) to 12 (December). Bars marked with 'o' and 'x' correspond to [the](#) NWF and WF [cases](#) [simulations](#), respectively.

3.2 Model [Validation-validation](#) with lidar observations

3.2.1 [Full-Three-Years-Analysis](#) [Three-year evaluation](#)

[Figure-5](#) depicts

[Figure 5](#) presents wind speed metrics [calculated for the WRF simulations against the lidar measurements over the full](#)
 320 [three-year-long period. Furthermore, the for the three-year WRF simulations compared with lidar observations.](#) ERA5 data [are](#)
[extracted from the nearest grid point and interpolated to the hub height, serving are also shown as a baseline.](#) Specifically,
[Although WRF and lidar time series have a native 10-minute resolution, for the aggregated analysis in this section, we](#)
[upscale the datasets \(WRF and lidars\) to hourly averages to match the temporal resolution of ERA5. This hourly-averaged](#)
[representation ensures a consistent and fair comparison of WRF and ERA5 with the lidar observations. The bias score \(Figure](#)
 325 [5A\) shows that both ERA5 and the bias score in Figure 5\(A\) highlights that the NWF simulation as well as the exhibit a](#)
[consistent negative bias at all sites except BSB, a consequence of the inherent ERA5 have a negative bias for all locations other](#)
[than BSB. Since the WRF model is initialized with ERA5 data, this negative bias may propagate into the WRF simulations.](#)
[The underestimation that propagates into WRF. The additional wind speed reduction imposed introduced by the Fitch WFP](#)
 leads to a slightly worse bias for the WF simulations than the NWF runs. In both NWF and WF cases, WRF demonstrates
 330 [enhanced consistency with the observations, while more negative bias in the WF run, although WRF generally aligns better](#)
[with the lidar observations than ERA5 exhibits greater deviations. At the BSB location, model-estimated wind speeds show a](#)
[unique positive bias in both the NWF scenario and the comparison with ERA5 data. Taking into account that the prevailing](#)
[wind direction during the analysis period is southwesterly. Part of the improved bias in the near wake produced by the Belgian](#)
[cluster and assessed at the BSB location is more accurately represented by the WF simulations compared to NWF runs likely](#)

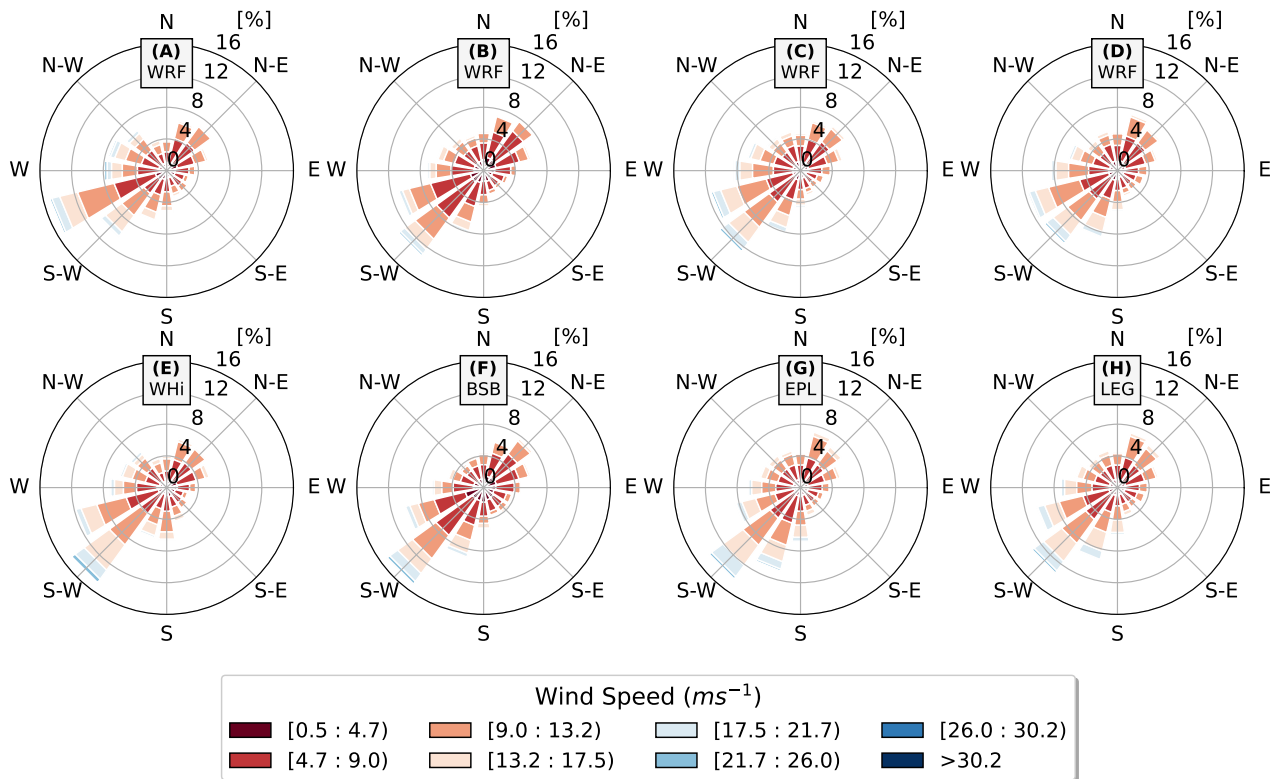


Figure 4. Top: Wind roses calculated at WHi (A), BSB (B), EPL (C), and LEG (D) probe locations using the ~~WRF model including the WFP scheme in the model~~ WF simulations. Bottom: Wind roses ~~calculated~~ extracted from the lidar measurements at WHi (E), BSB (F), EPL (G), and LEG (H) ~~using the lidar measurements~~. Both the lidar measurements and the model output are interpolated at the hub height.

335 results from an error-cancellation effect with the negatively biased ERA5 input, whereas in the WF simulations, these errors become slightly amplified due to wake-induced deficits, but remain lower than those in ERA5. At BSB, both ERA5 and the NWF runs ,resulting in a lower and negative bias, show a positive bias, while the WF simulation produces a smaller negative bias, corresponding to an improvement of about 82% over NWF and 73% over ERA5 in the near-wake under the predominant southwesterly flow.

340 In contrast to the bias score, ~~the cRMSE of ERA5 indicates a slightly more accurate estimation of wind speed compared to the NWF and WF simulations. However, among the two WRF cases, WF configuration outperforms the NWF runs. shows a lower cRMSE than both WRF configurations, indicating that it captures the temporal variability more consistently, whereas WRF exhibits a smaller bias due to a more accurate representation of the mean flow.~~ The EMD scores (Figure 5(C)) ~~shows that WF-C) further suggest that the WF configuration achieves the best fit against BSB observations, while exhibiting slightly~~
 345 ~~weaker agreement with the other lidars compared to the NWF simulations. Last, in Figure 5(D) agreement at BSB, the Pearson correlation shows that the wind speeds among WF, NWF, and ERA5 are highly correlated with the lidars observations, with~~

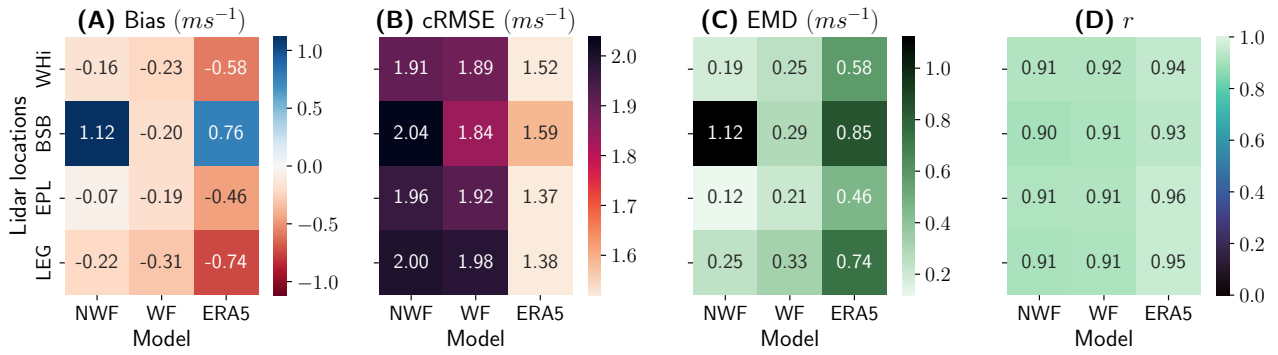


Figure 5. Evaluation metrics for wind speeds against lidar data, interpolated to hub-height at the four lidar locations: Bias (A), cRMSE (B), EMD (C), and r (D) scores. All values are interpolated to hub height. Darker colors signify poorer alignment with the observations.

a minimum r -value equal to with reductions of approximately 74% over NWF and 65% over ERA5. The Pearson correlation (Figure 5D) remains high across all datasets, with minimum values of 0.90 for the WRF model, NWF, 0.91 for WF, and 0.93 for the ERA5 data. In summary, a consistent negative bias is observed in Overall, both WRF and ERA5 datasets across all locations, except for BSB. This bias is likely exhibit a domain-wide negative wind speed bias, except at BSB, largely driven by the inherent underestimation in the underestimation in ERA5 data, which serve as input for the WRF simulations. Consequently, aggregated over the full three-year simulation period, wind speed is slightly underestimated within the analysis domain in both wind speeds remain slightly underestimated in both the NWF and WF simulations over the full three-year period.

Figure 6 presents bias (A), cRMSE (B), EMD (C), and circular correlation ρ (D) for wind directions, validating the WF, NWF, and ERA5 cases against the lidar observations. Wind Both wind speed and wind direction evaluations vary across metrics vary across the analyzed locations, with wind direction showing greater variability overall. First, it is important to highlight that the WF case yields more accurate wind direction estimates than the NWF simulations across all locations. Focusing on the BSB location, the wind speed metrics show a reduction of about 36% in bias and EMD, while an improvement of 4% in cRMSE is also observed in the WF simulations. Furthermore, when WPF is activated, wind direction bias at BSB is reduced by 65%, with improvements of 8% and 15% in cRMSE and EMD, respectively. However, ERA5 outperforms the WRF model in wind direction validation 51%. At WHi, all models exhibit a consistent bias of approximately 6.5 to 7.1°, while at EPL the models show a larger bias of about 11 to 12°. The cRMSE, EMD, and ρ at BSB indicate less consistent wind direction alignment with the lidars compared to the other locations. The increased discrepancies between WRF and lidar measurements Overall, ERA5 outperforms the WRF model in wind direction validation at the analyzed locations. The larger cRMSE in WRF compared to ERA5 data can be attributed to a few reasons. The coarse resolution of is expected because the coarser ERA5 can effectively average out spatial variability and reduce noise. Furthermore, the PBL physics schemes that are used in WRF may introduce uncertainty in near-surface turbulent mixing. Specifically, slightly higher cRMSE values in WRF, compared to fields do not resolve kilometer-scale wind speed fluctuations, resulting in a smoother signal and lower instantaneous error. In contrast, the higher spatial and temporal variability represented in WRF leads to phase mismatches between simulated and actual wind

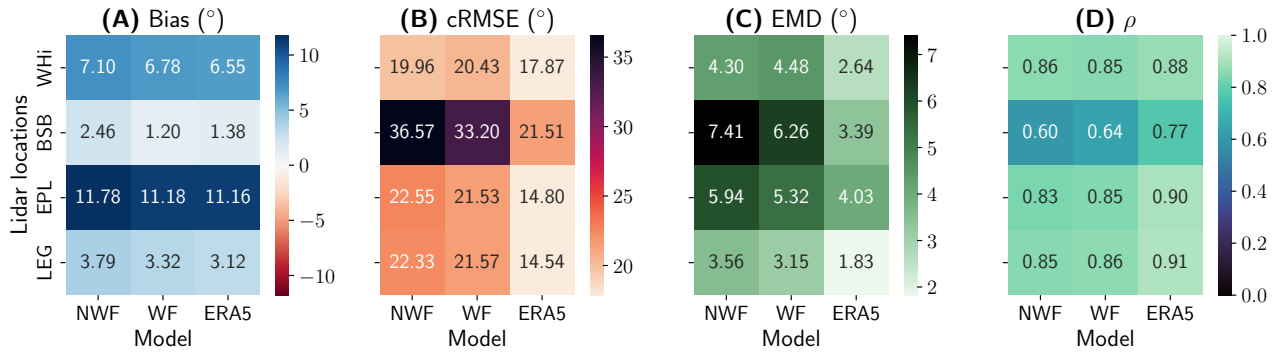


Figure 6. Evaluation metrics for wind directions against lidar data: Bias (A), cRMSE (B), EMD (C), and ρ (D) scores. All values are interpolated to hub height. Darker colors signify poorer alignment with the observations.

fluctuations, producing larger instantaneous discrepancies that manifest as higher cRMSE. The study of (Pronk et al., 2022) shows that ERA5 have been observed in the literature (Pronk et al., 2022). In that work, the authors emphasize that ERA5 can outperform downscaled WRF simulations in certain cases. outperforms WRF simulations in terms of cRMSE and correlation coefficient, both on land and offshore, under different stability conditions. Additionally, they report a consistent negative bias in wind speed. a consistent negative bias in wind speed is reported. These findings align with the WRF sensitivity analysis of Olsen et al. (2025) in the North and Baltic Seas, indicating that ERA5 outperforms the various WRF configurations in terms of cRMSE and correlation.

In Figure 7, the wind speed bias for each wind direction at each location is depicted, allowing a clearer assessment of the bias sources. Colored lines represent NWF, WF, and ERA5 datasets, and the dashed lines indicate zero bias. At WHi, EPL, and LEG where wakes due to the existence of the Belgian-Dutch cluster are observed, the NWF and WF simulations generally show similar distributions, except along the principal wake directions, where NWF performs slightly better. More specifically, at WHi the dominant wake influence arrives from the northeast, and around 45° the NWF bias is closer to zero. A similar pattern appears at EPL, and LEG, where NWF bias is closer to zero around 225° and 255° , respectively. Especially at EPL, the bias is close to zero between 190° and 225° in the NWF simulations. In all three cases, both WRF configurations reduce the negative bias found in the ERA5 data, highlighting that the Fitch scheme introduces an additional bias downstream of wind farm regions. Conversely, in the intra-farm region at BSB, the Fitch scheme provides a more accurate wind speed distribution across all wind directions, underscoring its importance in strongly waked environments. This behavior of the Fitch scheme, showing prolonged wakes and enhanced wind speed deficits at locations farther downstream and more accurate wind speed distributions closer to the turbines, has also been reported in previous studies (García-Santiago et al., 2024; Ali et al., 2023).

Similar to the wind speed bias per wind direction, Figure 8 presents the wind direction bias. Although the mean bias in Figure 6A suggests a closer agreement between the lidars and ERA5, WRF provides a better representation of the wind directions when the wind originates from the north to south-southeast (0 to 180°). Conversely, for westerly wind directions between 180

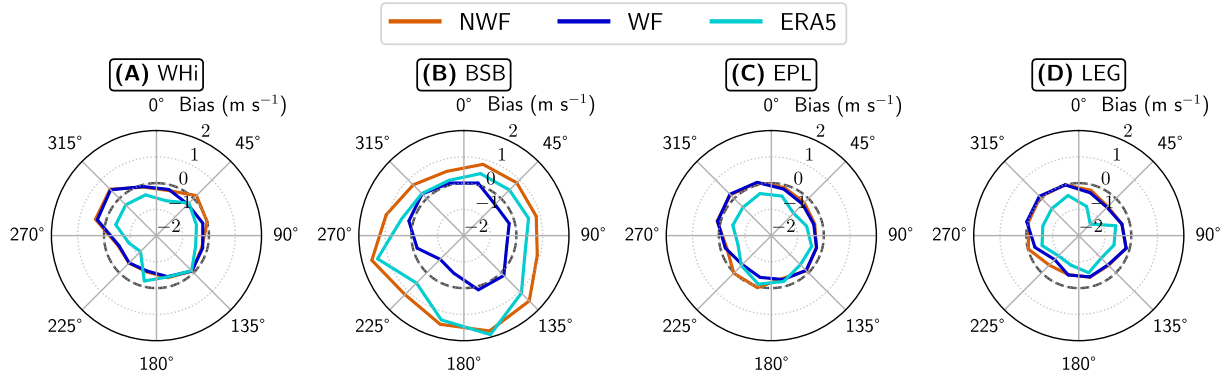


Figure 7. Evaluation metrics for Wind speed bias under different wind directions-direction sectors, evaluated against lidar data, observations. All values are interpolated to hub-height at the four lidar locations: Bias (A), eRMSE (B), EMD (C), and r (D)-scoreshub height. Darker colors signify poorer alignment. The deviation from the black dashed line indicates the degree of misalignment with the observations.

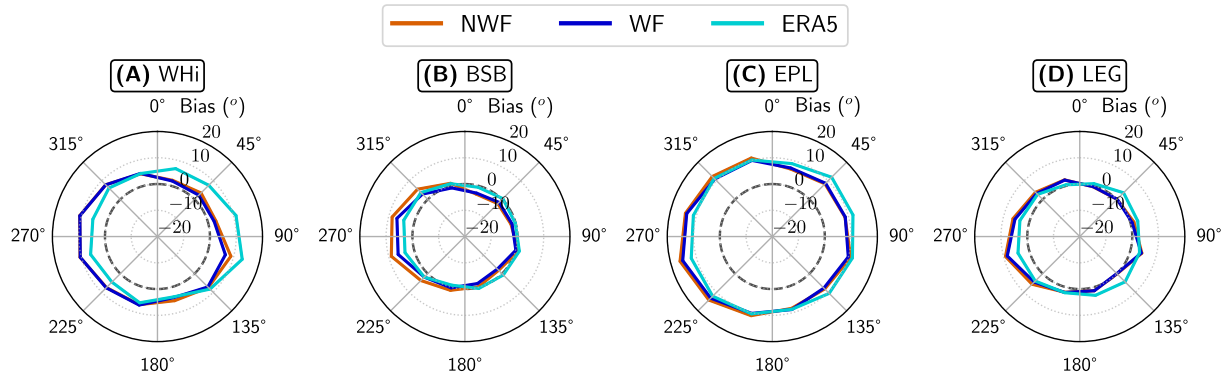


Figure 8. Wind direction bias under different wind direction sectors, evaluated against lidar observations. All values are interpolated to hub height. The deviation from the black dashed line indicates the degree of misalignment with the observations.

and 360° ERA5 performs better. At BSB, the mean bias is nearly identical between the WF runs and ERA5, but ERA5 shows a slightly closer agreement with the lidar measurements across all wind directions.

3.2.2 Impact of ABL Stability-stability on Model-Performancemodel performance

395 ABL stability conditions have been shown to play a significant role in influencing wind shear, buoyancy, and turbulence production, which in turn affect the width and length of downwind wind farm wakes (Rosencrans et al., 2024; Palatos-Plexidas et al., 2024). Therefore, it is essential to quantify these effects and assess the performance of WRF under varying ABL stratification.

Figure 9 depicts the wind speed scores estimated at the hub height. The ABL stability classes are determined at the BSB location using the MO-Obukhov length derived from the NWF simulations. The black dashed lines at each plot characterizes the ideal score values, while the colored solid and dashed lines represent the NWF and WF simulations at each location, respectively.

400

tively. EPL and LEG locations exhibit comparable patterns, with slightly greater wind speed underestimation at LEG during weakly stable to very stable conditions. In contrast, the wind speed assessed at BSB shows larger discrepancies. ~~In addition, at this location~~ At this location, the influence of wind turbines in the WF simulation is more evident, where a negative bias due to the wake is always observed (wind speed is underestimated). At WHi, the WF case provides a very accurate match ~~and especially in neutral, and stable cases~~, especially under neutral and stable conditions where the bias is close to zero. Similar trends are also ~~indicated~~ shown in the EMD scores, where reduced distribution-matching appears at BSB, and a closer match to observations is noticed at WHi, EPL, and LEG. ~~Across very unstable to neutral conditions, activating the WFP scheme in the model leads to a marked improvement in accuracy, especially in regions that are mostly affected by wind farm wakes, as evidenced by reductions in bias and EMD scores.~~

405 The cRMSE is around 2-1.8 to 2.5 ms^{-1} for all the cases, while there are subtle differences across the domain under different ABL conditions. Specifically, during very unstable to close-to-neutral conditions WHi, BSB, and EPL generate a reduced cRMSE, while LEG provides the best cRMSE during stable-neutral conditions. Furthermore, the cRMSE at BSB under very stable conditions remains close to 2 ms^{-1} in the WRF runs. Last, correlation r is higher than 0.80 when stability conditions are near-neutral and stable, while during more extreme ABL stratification, correlation values are lower and vary from ~~0.7 to 0.80~~ 0.69

415 to 0.77. The increase in cRMSE under very stable conditions is also reflected in the Pearson correlation, which decreases when transitioning from stable-neutral to very stable regimes. At BSB, all wind speed metrics improve in the WF simulations relative to the NWF runs across the different stability regimes, even under very stable conditions that are known to be associated with enhanced wakes (Rosencrans et al., 2024; Ali et al., 2023; Siedersleben et al., 2020). These findings align with the correlation analysis between WRF and sonic anemometer measurements in the Horns Rev wind farm (Peña and Hahmann, 2012), which

420 shows that model uncertainty increases as atmospheric stability deviates from neutral, i.e., under very stable or very unstable conditions. Although the Obukhov length diagnosed by the PBL scheme becomes uncertain under strongly stable conditions when Monin-Obukhov similarity theory is known to break down (Stiperski and Calaf, 2023; Optis et al., 2016) due to weak or intermittent turbulence, it remains a fundamental and practical metric for characterizing ABL stability in mesoscale models. Despite its limitations, many studies use Obukhov length, as it provides a consistent, physically based framework for classifying

425 stability regimes and interpreting wake behaviour (Rosencrans et al., 2024; Quint et al., 2025).

Wind direction scores presented in Figure 10 indicate different trends compared to the wind speed metrics above. Focusing on the bias score, the best alignment is observed at BSB, and specifically when the ABL conditions vary from very unstable to stable-neutral. The cRMSE reaches its highest values during periods of extreme ABL stratification, ~~both very stable and very unstable conditions~~, across all locations, with particularly pronounced misalignment observed at BSB and WHi during very

430 unstable events. Furthermore, cRMSE underscores the difficulty in accurately capturing wind direction, particularly at the BSB location under unstable-neutral stratification. At BSB, EMD suggests that during very unstable to unstable-neutral conditions, there is a discrepancy of around ~~7° to 10°~~ 7.5° to 10° in the wind direction distributions, which reduces when transitioning to neutral and stable stratification. On the other hand, higher discrepancies occur during weakly stable to very stable conditions at ~~EPL and WHi locations. In the case of wind direction, circular~~ WHi and EPL locations. Circular correlation ρ provides

435 comparable results to cRMSE, where the model performs less accurately during very unstable and very stable conditions,

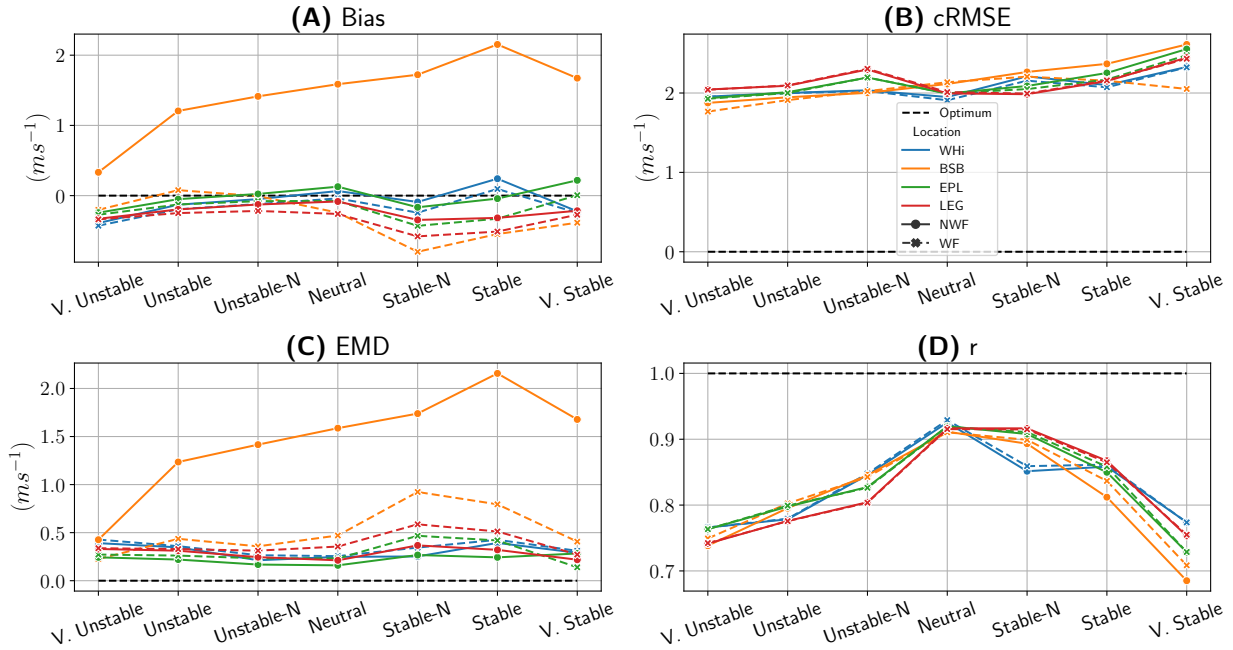


Figure 9. Comparison of WRF-assessed hub-height wind speed values against lidar metrics under different stability conditions: Bias (A), cRMSE (B), EMD (C), and r (D) scores. ABL classes are evaluated at BSB using the NWF simulations. Solid lines represent denote the NWF runs, while dashed lines correspond to WF simulations. The distance deviation from the black dashed line indicates the degree of misalignment with the observations.

and the best matching is when ABL stratification is near-neutral. More precisely, during very unstable events, ρ drops down to approximately 0.63 and 0.61 at WHi and BSB locations, respectively, indicating limited consistency in directional variability during these conditions. The high cRMSE, and the low circular correlation observed at BSB, and WHi locations during very unstable events may be attributed to lower winds and enhanced turbulence. Especially at BSB there is an important influence of the wind turbines in the flow, impacting the overall cRMSE and ρ . The applied cut-in threshold in wind speed (see Section 2.3.3), results in a significant improvement on the wind direction cRMSE and ρ scores during very unstable events (Figure ??), while wind speed metrics remain unaffected (Figure ??).

The validation analysis under different stability conditions reveals differences in model performance across the various locations. We should highlight that overall the WF simulation performs better across the locations. However, in addition to the analysis aggregated over the full three-year simulation period presented here, specific interest also lies in analyzing wind speeds across different magnitudes and specific wind directions to focus more on wake effects, as discussed in the next section.

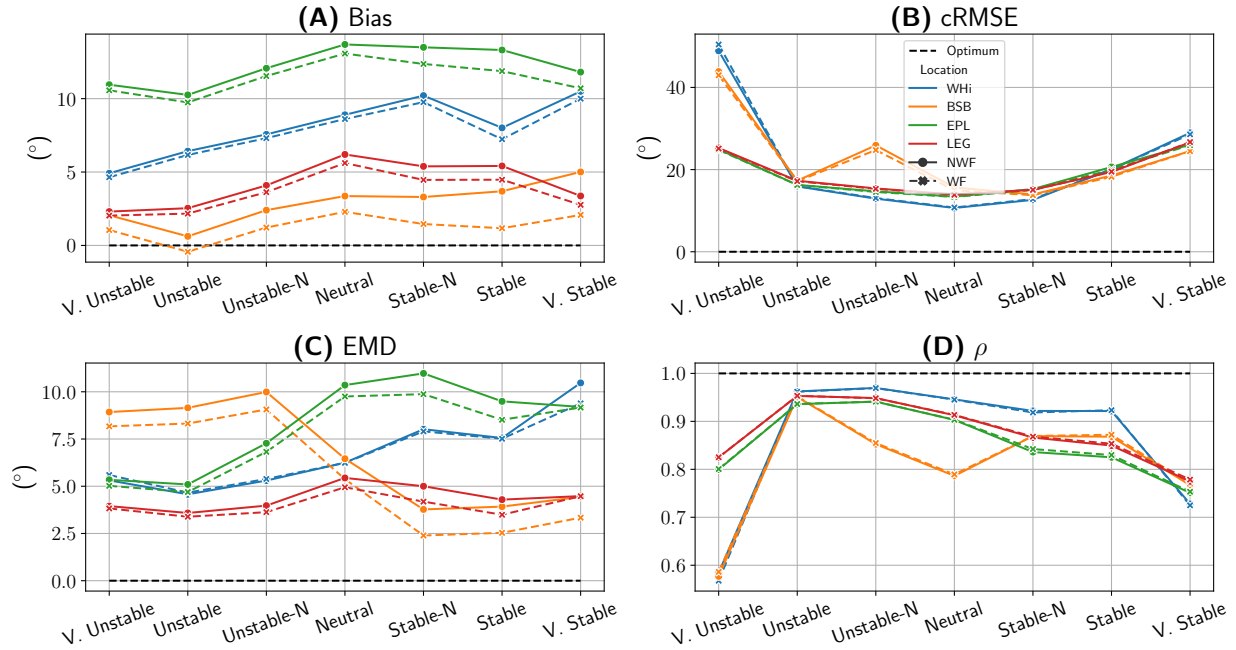


Figure 10. Comparison of WRF-assessed hub-height wind direction values against lidar metrics under different stability conditions: Bias (A), cRMSE (B), EMD (C), and ρ (D) scores. ABL classes are evaluated-assessed at BSB using in the NWF simulations. Solid lines represent-denote the NWF runs, while dashed lines correspond to WF simulations. The distance-deviation from the black dashed line indicates the degree of misalignment with the observations.

3.2.3 Assessment of Wind-Speeds Along wind speeds along the Transecttransect

In this section, we describe the influence of the wind speed magnitude on the intra-cluster and downstream wind speed deficits by comparing both the NWF and WF simulations with lidars across the transect that connects WHi, BSB, and EPL locations, with an almost perfect collinear alignment of these lidars (see Figure 2). The analysis is based on timestamps where lidar measurements are commonly available, representing about 21.724.4% of the total time instances. The limitation is primarily due to the availability of WHi measurements (see Table 3). The study focuses on two predominant wind direction categories: southwest (SW) and northeast (NE), and the frequency of each wind speed class is depicted in Figure 11. This configuration allows both SW and NE wind directions to effectively characterize the wind fields upstream and downstream the Belgian-Dutch cluster. Both wind direction and wind speed classification is based on the average values across the three locations.

Figure 12 depicts wind-speed Figures 12 and 13 depict the wind speeds along the transect connecting WHi, BSB, and EPL under-for the four different wind speed classes and-SW-wind-direction under SW and NE wind directions, respectively. The distributions at each location are clipped at the 1st and 99th percentiles solely for illustrative purposes, without affecting

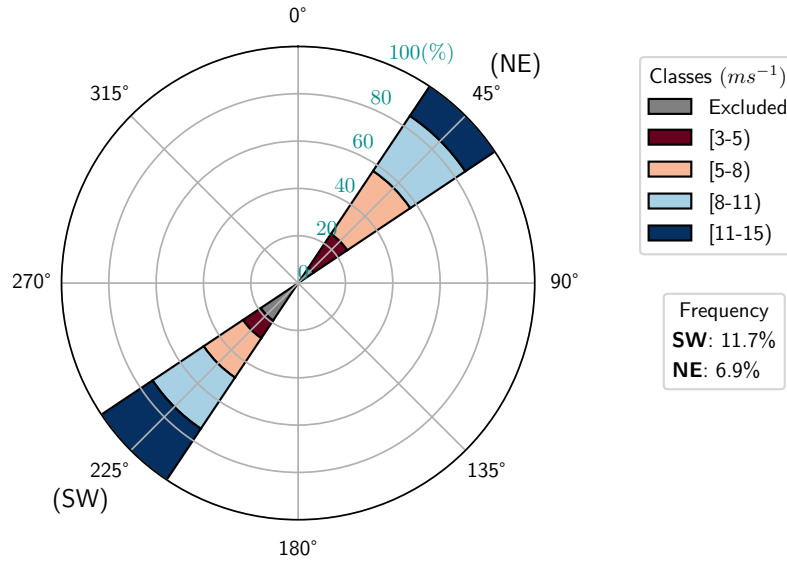


Figure 11. Wind-Frequency of the wind speed classes frequency when wind direction is under SW (41.9%) or NE (6.9%) wind directions, respectively. The frequency is based-calculated on the common timestamps of the lidars and not over the full period of analysis.

460 the presented statistics. Overall, the WF simulations slightly underestimate the wind speed, and this is corroborated by the bias scores in the full-period-heatmaps full-period heatmaps presented in Figure 5(A)A. More precisely, under SW winds, the model underestimates wind speeds in the at the upstream location of WHi across all the wind speed classes. Especially, when the wind speed is between $[3, 5) \text{ ms}^{-1}$ range, particularly at WHi and EPL, with discrepancies exceeding 1 or above 8 ms^{-1} . In contrast, wind speeds in the, the produced wind speed deficit of the Fitch model is overestimated. On the other hand, the

465 model provides a more accurate wake pattern when wind speed belongs to $[5, 8) \text{ ms}^{-1}$ and $[8, 11) \text{ ms}^{-1}$ ranges show strong agreement, although a slight underestimation, around 1 persists at BSB classes. These wind-speed ranges usually correspond to the power ramp-up region of a wind turbine, where power output exhibits strong sensitivity to wind-speed variations. Under northeasterly winds (see Figure 13), the model underestimates wind speeds in both the $[3, 5)$ ranges across all locations, while performance improves markedly when wind speed varies between from 5 to $8-11 \text{ ms}^{-1}$. At higher wind speeds (In both wind

470 direction cases, the WF simulations overestimate the intra-farm wind speed deficit when wind speed is above $11-15)$, the model performs well at WHi and EPL but there is limited accuracy at BSB, suggesting intensified wake effects within the wind farm. Wake formation under SW winds is mostly observed in the dense zone of the Belgian wind farms and remains relatively constant downstream the Borssele wind farm ms^{-1} .

In Figure 13, under northeasterly winds, the model underestimates wind speeds in both the $[3, 5)$ and $[5, 8)$ Table 4 summarizes the wind speed bias and cRMSE across the wind speed classes for the SW wind direction, highlighting how model performance varies in upstream, intra-farm, and downstream locations. Under SW winds, where the flow progresses from WHi (upstream) $\Gamma \hat{a} \hat{E}$ BSB (intra-farm) $\Gamma \hat{a} \hat{E}$ EPL (downstream), the largest errors occur upstream at WHi in the $3-5 \text{ ms}^{-1}$ ranges across

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WRF-assessed Hub-Height Wind speed validated across the WHi, BSB, and EPL transect. Wind direction is SW and it is assessed as the average across the three lidar locations. The vertical lines indicate the Belgian-Dutch cluster (black) and the Belgian-only (red) wind farm areas. The wind speed range on the y-axis varies across classes, aiming to highlight the distribution specific to each class:

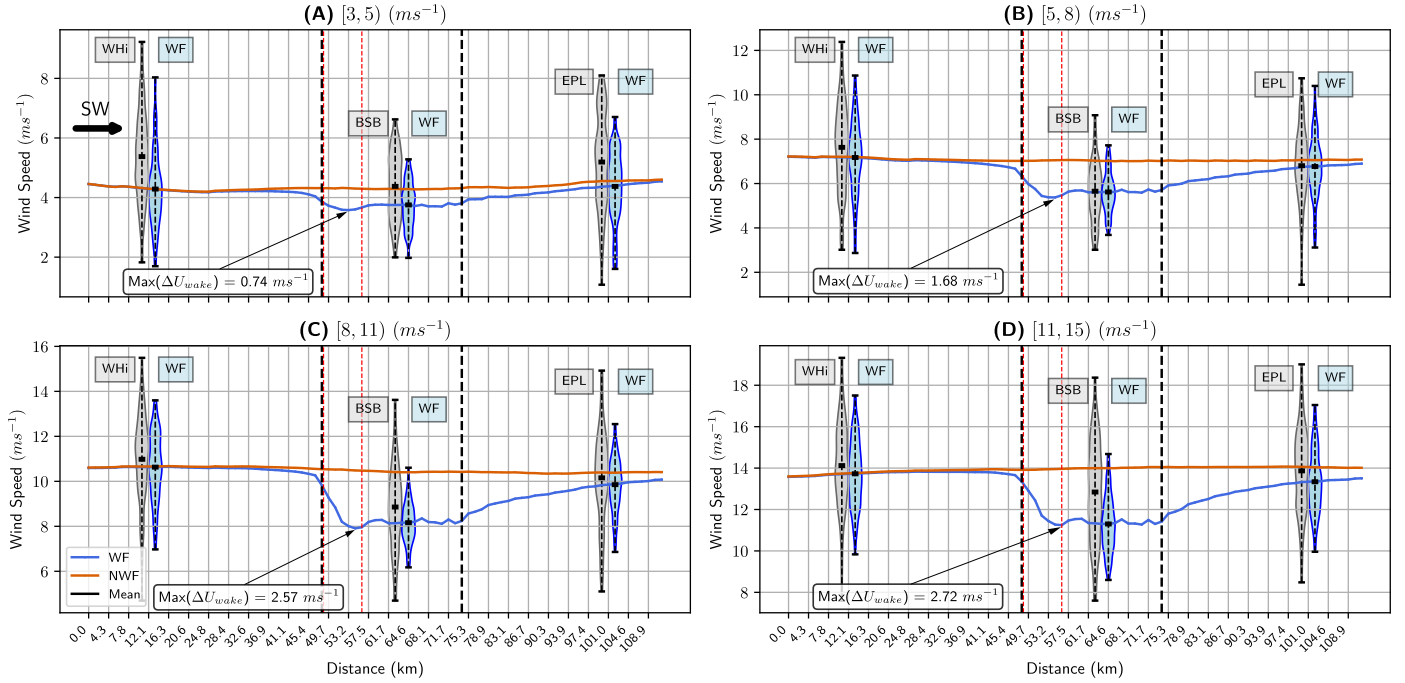


Figure 12. WRF-assessed hub-height wind speed along the WHi, BSB, and EPL transect for SW wind directions, with wind direction calculated as the mean across the three lidar sites. Vertical lines mark the Belgian-Dutch cluster (black) and the Belgian-only wind-farm areas (red). The wind speed range on the y-axis varies across classes to highlight class-specific distributions, and the maximum wind speed deficit value within the Belgian-Dutch zone is depicted.

all locations, while performance improves markedly when wind speed varies from 8 to 15 class (bias=-1.09 ms^{-1} , and cRMSE=1.56 ms^{-1} , with a modest underestimation of about 0.5 which are very similar to WF and NWF runs), reflecting that small inflow uncertainties propagate strongly before the flow encounters the farm. As the flow moves into and through the farm, the bias systematically decreases, reaching nearly zero at BSB and EPL in the 5-8 ms^{-1} at BSB. Notably, class in the WF simulations. The cRMSE increases with the wind speed magnitude, indicating that although the mean wind speed is well captured, the variability associated with wake turbulence and flow transitions is still not well reproduced. Overall, the cRMSE in the WF simulations is comparable to, or slightly lower than, that in the NWF simulations across all locations and wind speed regimes.

Under NE winds, where the flow reverses (EPL $\rightarrow$ BSB $\rightarrow$ WHi), a similar pattern emerges as presented in Table 5. The upstream location (now EPL) shows a reduced bias at low wind speeds (about -0.50 ms^{-1} in both NWF and WF) but a higher cRMSE (1.8 to 1.95 ms^{-1}). Within the farm (BSB), bias remains modest across most wind speed classes, while cRMSE stays

elevated. When wind speed is in the $8-11 \text{ ms}^{-1}$ class, WF provides an almost negligible bias both at EPL and BSB. At higher wind speeds (above 11 ms^{-1}), both bias and cRMSE increase, especially at BSB. The improved bias in the NWF simulations and under specific wind speed magnitudes can be associated with error-cancellation of the already biased ERA5 data (see section 3.2.1). The differences in bias and cRMSE scores between the NWF and WF simulations at the upstream locations (WHi under SW wind directions, and EPL when wind comes from NE) are related to the fact that the flow can already be slightly affected by the UK wind farms on the west and the Dutch cluster on the NE, as presented in Figure 1b.

Although Figures 12 and 13 present transects under different wind speed magnitudes for the SW and NE wind directions, transect-based analyses of instantaneous wake events have also been reported using flight measurements (Ali et al., 2023; Fischereit et al., 2023). Those studies showed that the Fitch WFP in WRF can reproduce the wake features and reduce wind speed biases along transects. The transects in Figures 13 and 14 extend this type of analysis but rely on lidar observations rather than flight data, allowing for a comparison of more events and analyzing upstream, intra-farm, and downstream wake characteristics.

Notably, distinct intra-cluster wake behavior differs under NE winds patterns emerge under SW and NE wind conditions. Under SW winds, the strongest wind speed deficit originates within the Belgian wind farm cluster and remains nearly unchanged as the flow proceeds across the Borssele zone. In contrast, under NE winds, the wind speed decreases progressively throughout the entire wind farm region, with a continuous reduction in wind speed observed throughout the wind farm, beginning in the Borssele zone and intensifying through the cluster and intensifying as the flow enters the denser Belgian wind farms. Furthermore, the wake recovery rate is less smooth at high wind speed magnitudes. These findings highlight the directional dependence of wake dynamics and underscore the need for improved model representation of low-speed flows and intra-cluster wake effects. The More specifically, the maximum wind speed deficits over the Southern Bight of the North Sea are illustrated in Figure 15. Following the transect plots in Figures 12 and 13, greater wind speed magnitudes are associated with more pronounced downstream wind speed deficits increase with wind speed magnitude. At wind speeds above 11 ms^{-1} , the difference between SW and NE conditions becomes substantial: under SW winds, the maximum deficit reaches approximately 2.72 ms^{-1} , whereas under NE winds it increases to about 4.19 ms^{-1} . At lower wind speeds (below 8 ms^{-1}), the largest deficits in both SW and NE regimes occur near the center of the densely built Belgian wind farm zone. At higher wind speeds, however, the location of the maximum deficit shifts. Under SW winds, the strongest deficit moves toward the northeastern boundary of the Belgian zone, near the interface with the Dutch Borssele cluster. Conversely, under NE winds, the maximum deficit appears at the downstream exit of the Belgian wind farm cluster. These contrasting behaviors between the wake trends under SW and NE wind directions arise from the strong dependence of wake evolution on turbine spacing. The averaged density of the Belgian wind farms that the analyzed transect crosses is about 10 to 12 MW/km^2 , while the Borssele cluster has a density of about 4 to 5 MW/km^2 . Therefore, the dense Belgian cluster produces rapid wake merging and a deeper cumulative deficit, whereas the more widely spaced Borssele layout allows partial recovery before wakes redevelop downstream. As a result, SW winds encounter an already merged wake that weakens over the coarse Borssele area, while NE winds first traverse the coarse Borssele layout, where deficits remain modest, and then intensify sharply upon entering the dense Belgian cluster.

~~WRF-assessed Hub-Height Wind speed validated across the WHi, BSB, and EPL transect. Wind direction is NE and it is assessed as the average across the three lidar locations. The vertical lines indicate the Belgian-Dutch cluster (black) and~~

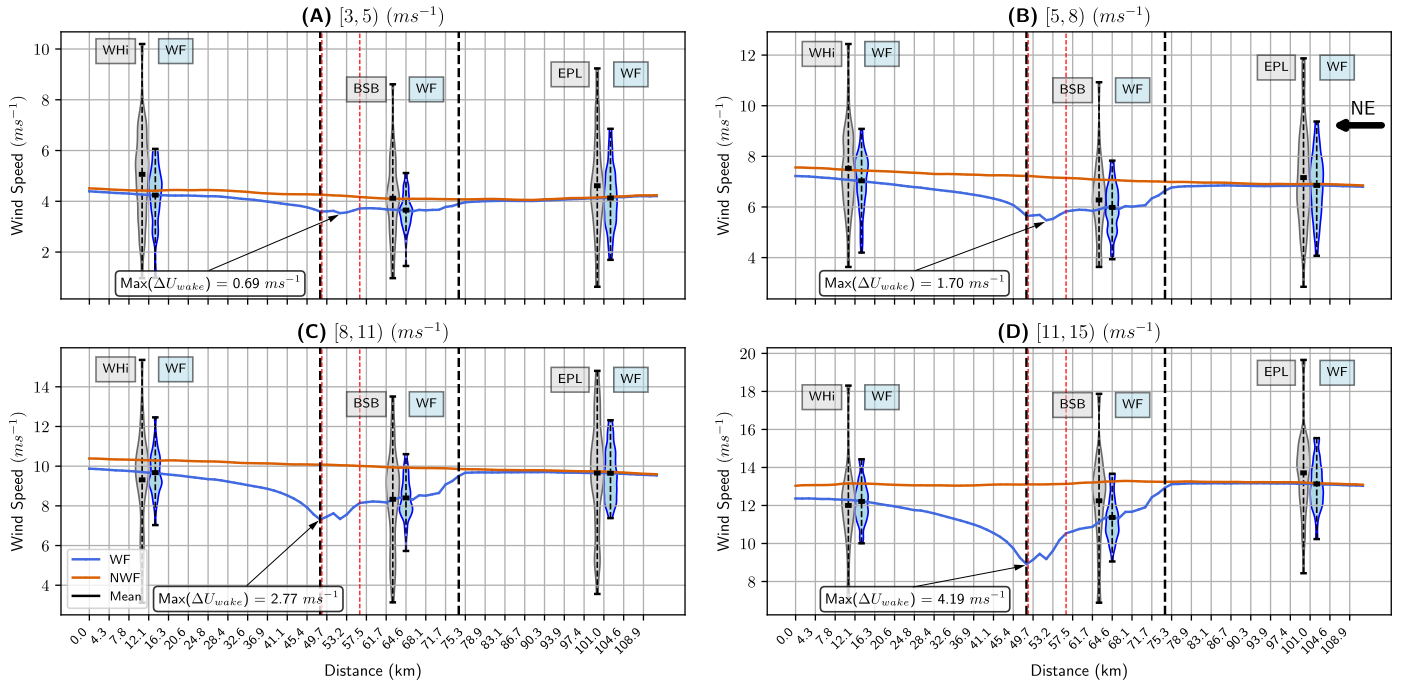


Figure 13. Wind speed deficits calculated at the WRF-assessed hub-height, for four wind speed classes. The red dashed line indicates along the WHi, BSB, and EPL transect. Subscript 1 indicates that for NE wind directions, with wind direction is SW calculated as the mean across the three lidar sites. Vertical lines mark the Belgian-Dutch cluster (top black), and subscript 2 presents the NE-Belgian-only wind direction cases farm areas (bottom red). The wind speed deficits are averaged range on the y-axis varies across classes to highlight class-specific distributions, and the occurrences that describe each case maximum wind speed deficit value within the Belgian-Dutch zone is depicted.

the Belgian-only (red) wind farm areas. The wind speed range on the y-axis varies across classes, aiming to highlight the distribution specific to each class.

Figure 14 presents

Figures 14A, and B present the frequency of the ABL stability conditions at each wind direction case and under the different wind speed range ranges, for SW and NE wind directions, respectively. The ABL stability classification is based on Obukhov length, averaged across the three lidar probes in the NWF simulations. Under low wind speed conditions, very unstable and unstable events tend to dominate. Conversely, a transition toward near-neutral ABL stratification under high wind speeds is evident in Figure 14 also evident. Previous studies (Rosencrans et al., 2024; Palatos-Plexidas et al., 2024; Porchetta et al., 2024) have demonstrated the dependence of wake propagation and wind speed losses on ABL stability, showing that transitioning from neutral to stable and very stable stratification, wakes tend to extend further downstream of wind farms. Similarly, we underscore the relation between wind speed magnitude, ABL stratification, and wake propagation, where during high wind

Table 4. Performance metrics under the different wind speed classes for SW wind direction.

<u>Metric</u>	<u>Location</u>	<u>[3-5) ms⁻¹</u>		<u>[5-8) ms⁻¹</u>		<u>[8-11) ms⁻¹</u>		<u>[11-15) ms⁻¹</u>	
		<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>
Bias (ms ⁻¹)	<u>WHi</u>	<u>-1.08</u>	<u>-1.09</u>	<u>-0.43</u>	<u>-0.46</u>	<u>-0.33</u>	<u>-0.35</u>	<u>-0.37</u>	<u>-0.39</u>
	<u>BSB</u>	<u>-0.09</u>	<u>-0.62</u>	<u>1.38</u>	<u>-0.02</u>	<u>1.56</u>	<u>-0.68</u>	<u>1.16</u>	<u>-1.53</u>
	<u>EPL</u>	<u>-0.63</u>	<u>-0.81</u>	<u>0.25</u>	<u>-0.04</u>	<u>0.23</u>	<u>-0.31</u>	<u>0.18</u>	<u>-0.53</u>
cRMSE (ms ⁻¹)	<u>WHi</u>	<u>1.55</u>	<u>1.56</u>	<u>1.76</u>	<u>1.77</u>	<u>1.89</u>	<u>1.89</u>	<u>1.92</u>	<u>1.93</u>
	<u>BSB</u>	<u>1.42</u>	<u>1.17</u>	<u>1.50</u>	<u>1.30</u>	<u>1.92</u>	<u>1.81</u>	<u>2.34</u>	<u>2.23</u>
	<u>EPL</u>	<u>1.62</u>	<u>1.48</u>	<u>1.60</u>	<u>1.56</u>	<u>1.90</u>	<u>1.83</u>	<u>1.89</u>	<u>1.88</u>

Table 5. Performance metrics under the different wind speed classes for NE wind direction.

<u>Metric</u>	<u>Location</u>	<u>[3-5) ms⁻¹</u>		<u>[5-8) ms⁻¹</u>		<u>[8-11) ms⁻¹</u>		<u>[11-15) ms⁻¹</u>	
		<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>
Bias (ms ⁻¹)	<u>WHi</u>	<u>-0.68</u>	<u>-0.85</u>	<u>-0.13</u>	<u>-0.54</u>	<u>0.89</u>	<u>0.26</u>	<u>0.95</u>	<u>0.05</u>
	<u>BSB</u>	<u>-0.08</u>	<u>-0.53</u>	<u>0.76</u>	<u>-0.32</u>	<u>1.48</u>	<u>-0.04</u>	<u>0.82</u>	<u>-1.07</u>
	<u>EPL</u>	<u>-0.48</u>	<u>-0.52</u>	<u>-0.29</u>	<u>-0.35</u>	<u>0.01</u>	<u>-0.07</u>	<u>-0.69</u>	<u>-0.74</u>
cRMSE (ms ⁻¹)	<u>WHi</u>	<u>1.90</u>	<u>1.81</u>	<u>1.80</u>	<u>1.71</u>	<u>3.02</u>	<u>3.00</u>	<u>2.72</u>	<u>2.66</u>
	<u>BSB</u>	<u>1.93</u>	<u>1.90</u>	<u>1.94</u>	<u>1.78</u>	<u>2.89</u>	<u>2.79</u>	<u>3.18</u>	<u>3.13</u>
	<u>EPL</u>	<u>1.95</u>	<u>1.92</u>	<u>1.95</u>	<u>1.94</u>	<u>2.80</u>	<u>2.80</u>	<u>2.83</u>	<u>2.84</u>

535 speeds, the frequency of neutral events is enhanced and wakes propagate a few tens of kilometers downstream of the Belgian-Dutch cluster.

In addition to the frequency of the stability regimes, in Figures 14C and D, the magnitude of the average normalized wind speed deficit is presented under the different stability conditions. The wind speed deficits are estimated as the average across the three analyzed lidar locations. It is observed that under very unstable and unstable occurrences, the wake magnitude is relatively lower (varying from 4 to 8%). When ABL stratification is near neutral, higher wake magnitudes are also observed. Following the patterns presented in studies (Rosencrans et al., 2024; Palatos-Plexidas et al., 2024; Porchetta et al., 2024), moving from unstable to neutral and stable stratification results in higher wind speed deficits. However, this should be interpreted together with the frequency of events in each wind speed class, which shows that the number of very stable cases, where wake effects

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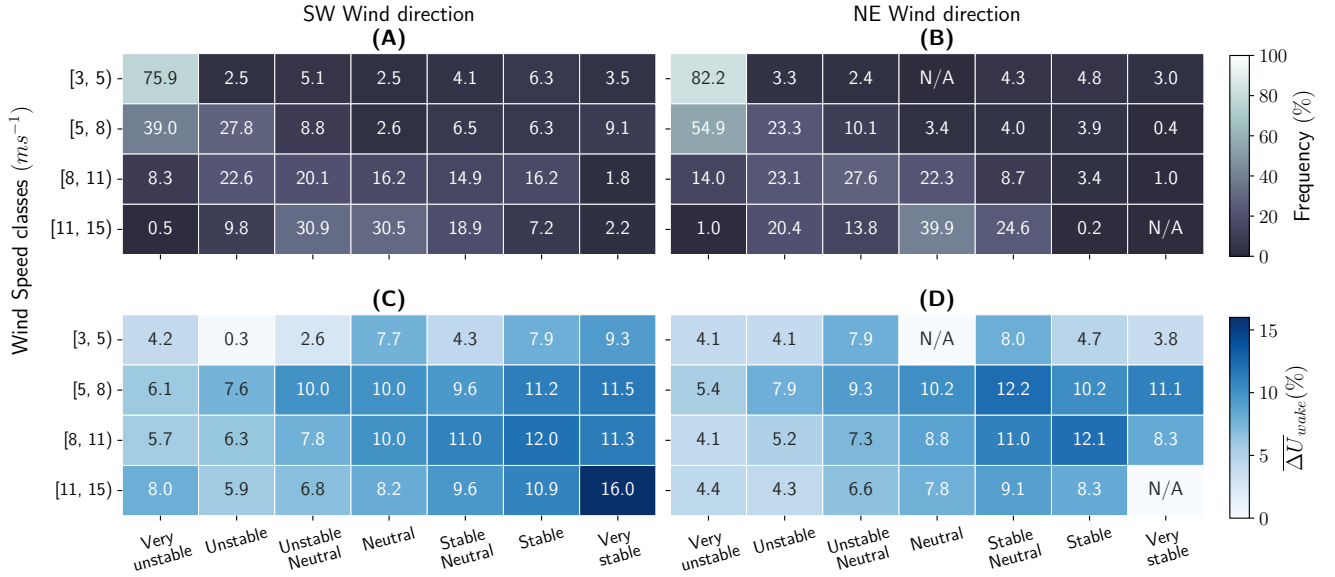


Figure 14. Frequency of the ABL stability frequency (%) conditions for each wind speed class regime, based on the two analyzed wind directions, under SW (top A), and NE (bottom B) wind directions. Lighter colors suggest higher frequency of Averaged wake magnitude under the stability class different ABL conditions and wind speed classes for SW (C) and NE (D) wind directions.

are relatively strong, is not particularly large. On the other hand, the wind speed deficits during very unstable and unstable events that occur more frequently (especially when wind speeds are below 8 ms^{-1}) are significantly lower. Near neutral conditions occur more frequently when wind speed is above 8 ms^{-1} in both SW and NE wind direction, and the wake magnitude in those cases ranges from about 7 to 12%. Greater wind speed magnitudes are associated with more pronounced downstream wind speed deficits (see Figures 12 and 13), as higher wind speeds in this region occur more frequently under neutral to stable conditions. Under these regimes, particularly during stable conditions, reduced turbulent mixing limits wake recovery, leading to enhanced and more persistent wakes (Rosencrans et al., 2024; Ali et al., 2023; Siedersleben et al., 2020). The transition toward neutral and stable ABL conditions with the increasing wind speed may contribute to the higher cRMSE values observed in Tables 4 and 5, as these regimes are associated with enhanced shear.

3.2.4 Blockage-Wake characteristics and blockage effects in the Belgian-Dutch cluster

The analysis presented in the previous section, based on SW and NE wind directions, supports the investigation of the two-dimensional wake characteristics and blockage effects within the Belgian-Dutch wind farm cluster. A reduction in wind speed upstream of the wind farms is evident both in the transects (Figures 12 and 13) and in the wake maps shown in Figure 15 under SW and NE wind directions. In the case of transect under SW winds (Figure 12), a noticeable wind speed deficit begins approximately 8 km upstream of the wind farm. This reduction is present across the different wind speed magnitudes, but becomes more pronounced and rapid around 4 to 5 km upstream, particularly when wind speeds

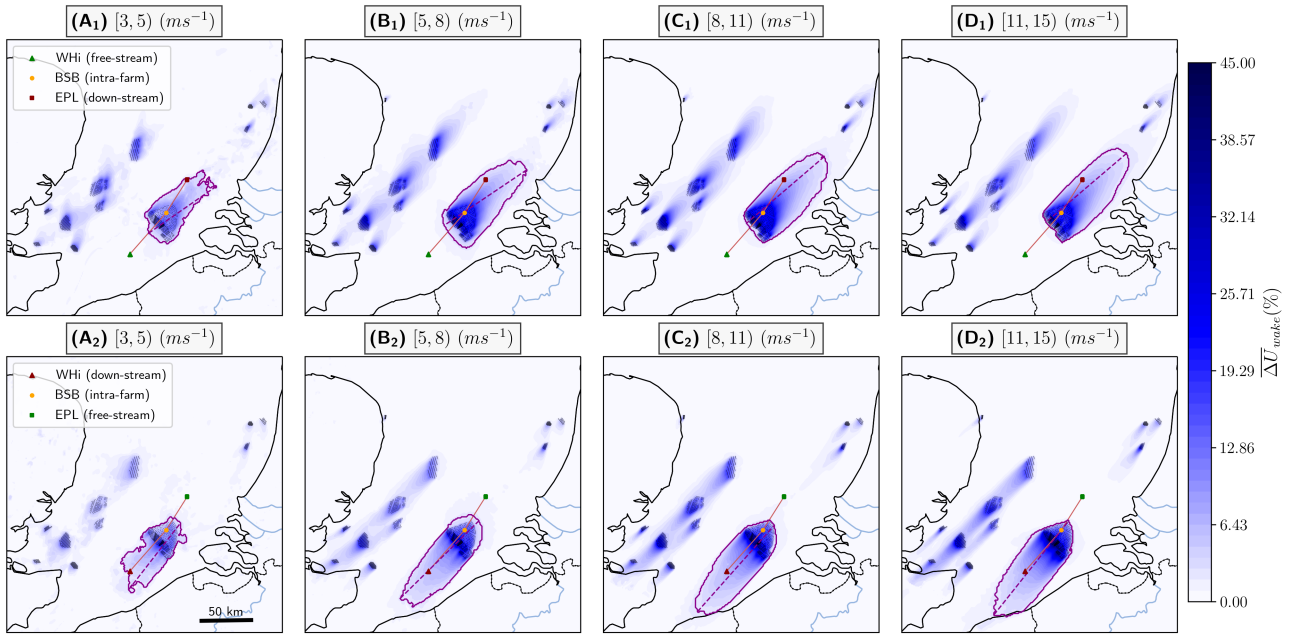


Figure 15. Wind speed deficits calculated at the hub height under the four wind speed regimes. The red dashed line illustrates the WHi, BSB, and EPL transect. Subscript 1 indicates that wind direction is SW (top), and subscript 2 denotes NE wind direction conditions (bottom). Wind speed deficits are averaged across each wind speed class. Solid purple lines depict the 95% wake recovery area, and dashed purple lines the maximum wake length within this area.

560 exceed 5 ms^{-1} . For NE wind directions (Figure 13), the blockage effect is also visible, though it is confined to a smaller region—approximately 2 to 3 km upstream of the Borssele wind farm, and occurs when wind speeds range between 5 and 15.

The full

The wake maps in Figure 15 further confirm the presence of blockage effects under both SW and NE wind conditions. 565 Notably, when wind speeds exceed 5 ms^{-1} , the solid purple lines indicate the 95% wake recovery area, while the dashed purple lines represent the maximum wake length within this area for each wind speed regime and wind direction. The wake structures become less coherent at wind speeds below 5 ms^{-1} , the upstream wind speed deficit extends over a broad area. Additionally, the geometric configuration of the cluster leads to distinct blockage zones depending on the wind direction. Speedup zones (i.e., negative wind speed deficits) are also observed between the Belgian-Dutch cluster and the UK wind farms, while an induction zone defined by the 95% wake recovery area is observed in low wind speeds. More precisely, the maximum blockage distance from the front row of the wind turbines appears around 10 km under SW wind direction (Figure 15A₁), whereas around 5 km in the NE wind direction regime (Figure 15A₂). In addition, Table 6 presents the values of the 95% wake recovery area and the maximum wake length within this area. The largest coherent wake region is extracted using connected-component labeling. Its perimeter is obtained from the contour of the binary mask, and the maximum extent is computed as the convex-hull diameter

Table 6. Wake characteristics under the different wind directions and wind speed classes.

Wind direction	[3-5] ms ⁻¹		[5-8] ms ⁻¹		[8-11] ms ⁻¹		[11-15] ms ⁻¹	
	Wake area (km ²)	Wake length (km)	Wake area (km ²)	Wake length (km)	Wake area (km ²)	Wake length (km)	Wake area (km ²)	Wake length (km)
Southwest	3317	119.9	5261	144.9	5587	144.8	5739	149.7
Northeast	3329	108.8	4988	147.2	5472	147.2	5819	148.9

of the perimeter points. The estimation of both the 95% wake recovery area and the maximum wake length near SW or NE wind directions is performed using the SciPy Python package (Virtanen et al., 2020). The values under the different wind speed regimes in Table 6 are comparable for both SW and NE wind directions.

When the flow transitions to higher wind speeds (above 5 ms⁻¹), the wake structures become more coherent, with more pronounced wake recovery areas, leading to overall longer wake lengths (see Table 6). In the 5-8 ms⁻¹ class, a blockage region forms upstream of the turbines, extending approximately 8 to 9 km from the first row under both SW and NE conditions. At higher wind speeds, this blockage pattern becomes negligible, and the flow tends to deflect around the cluster and propagate farther downstream.

3.3 Comparison of Wake Events with SAR Data

In this section, we focus on a one-by-one comparison of the WRF model output with SAR data. SAR images are retrieved from Sentinel 1A and 1B satellites as explained in Section 2.3.2, and they provide wind speed fields at 10-meter height. Four discrete timestamps have been selected to analyze the wind speed patterns derived from SAR and WRF data, as well as to validate the model performance across the transect that connects the WHi, BSB, and EPL lidars (see Figure 2). These timestamps were selected manually based on the visual appearance of wind farm wakes in the SAR images. Although an average of 8 to 10 snapshots per month (see section 2.3.2) covers the analyzed region, the focus on wake events affecting the WHi, BSB, and EPL lidar sites under SW and NE wind directions resulted in a further reduction of the available snapshots. Therefore, an additional event from September 2020, outside the defined three-year simulation period, has been deliberately included for analysis. The exact datetimes and the ABL stratification conditions are described derived from the NWF simulations, based on the Obukhov length and the planetary boundary layer height (PBLH), are provided in Table 7. Although this study uses only four specific SAR scenes and does not explicitly evaluate SAR data reliability, previous validation works provide strong evidence supporting the accuracy of SAR-retrieved winds. For example, Hasager et al. (2011b) compared SAR-derived wind speeds with meteorological mast measurements in the Baltic Sea and reported a small bias of -0.25 ms⁻¹ and a correlation coefficient of $R^2 = 0.783$ across 900 images. Similarly, de Montera et al. (2020) assessed 1544 SAR Level-2

Ocean product instances against four offshore buoys and three coastal weather stations around Ireland, finding an average bias of -0.4 ms^{-1} .

Table 7. Description of the atmospheric conditions on the SAR-WRF comparison timestamps. ~~MOL~~Obukhov length L and ~~planetary boundary-layer-height (PBLH)~~ are estimated in the NWF simulations.

Case / Datetime	WHi			BSB			EPL		
	L (m)	PBLH (m)	Stability	L (m)	PBLH (m)	Stability	L (m)	PBLH (m)	Stability
A: 2020-09-19 17:40:00	259.5	291.9	Stable-neutral	355.0	264.6	Stable-neutral	1000	326.2	Neutral
B: 2021-10-08 17:40:00	-38.7	688.8	Very unstable	-27.2	729.9	Very unstable	-29.9	715.9	Very unstable
C: 2022-03-25 17:40:00	-450.9	297.6	Unstable-neutral	-296.1	317.1	Unstable-neutral	-410.8	317.6	Unstable-neutral
D: 2023-08-20 06:10:00	-51.1	249.3	Very unstable	-98.8	338.9	Very unstable	-61.3	357.7	Very unstable

600 Figure 16 presents the comparison of SAR and WRF wind fields at 10-meter height. The left column shows the SAR-derived wind speeds, denoted by the subscript 1. The middle column depicts the WF wind speeds, indicated by a subscript 2, and in the right column, the reference NWF wind speeds are illustrated, and denoted with a subscript 3, as a reference case. In case A, higher wind speeds are also related to stable-neutral conditions and a shallow boundary layer (see Table 7). The wake structure of the Belgian-Dutch wind farm cluster is well captured by the WF simulation. However, a slight deviation in wind direction is observed in WRF, exhibiting a positive bias toward more westerly flow. Similar bias has also

605 been highlighted in the wind roses (Figure 4) and in the wind direction validation heatmap in Figure 6(A). ~~In case B-A.~~ The prolonged wake extending more than 50km downstream under stable-neutral stratification agrees with the findings of Cañadillas et al. (2020) and Platis et al. (2018), who also report that wake structures are more pronounced and longer during stable conditions. Furthermore, Siedersleben et al. (2020) examined a stable event simulated with the Fitch scheme in WRF

610 (version 3.8.1), comparing the original formulation ($a = 1$) with a variant excluding the added TKE term, and showed that including the added TKE source under stable stratification results in a more realistic representation of the prolonged wake of a SAR-retrieved 10-meter wind speed pattern. In our study, although we use a finer grid spacing (1km instead of 1.67km) and a reduced TKE coefficient ($a = 0.25$), which limits the influence of the added TKE term, we observe a very good agreement between the SAR image and the WF simulations during stable conditions. Furthermore, Ali et al. (2023) evaluated several

615 WFP schemes to characterize the wake of a specific event using 10 m SAR data. Their results show that, when comparing the Fitch model with $a = 1$ and $a = 0.25$, the latter produces a longer wake downstream of the wind farms, similar to the behavior observed in case A analyzed in the present study.

In case B, the wake is weaker, but still detectable both in SAR image and in the WF simulation. In this case, stability conditions are very unstable, and the PBLH is around 700 meters, explaining the attenuated wake pattern. Case C is characterized by higher wind speeds, ~~MO-length- L~~ varies from -300 to -450 m, and PBLH is approximately 300 m across the three locations, resulting in a more unstable-neutral stratification profile, resulting in the observed downstream wake of about 40 to 50km. Similar wake patterns but slightly shorter, about 25 to 35km have been observed during neutral stratification in the study of Platis et al. (2018). Last, in case D, very unstable ABL conditions prevail, and the PBLH varies between 250 meters upstream at the WHi location to 358 meters downstream at the EPL area. This is the only SAR image with clear wakes for SW wind conditions. Overall, the patterns of the wakes are accurately represented by the WF simulations, highlighting the importance of using the Fitch WFP scheme in WRF. Although SAR assumes neutral stability to compute the 10-meter wind speed, there are discrepancies with the WRF model, especially in cases B and D, where very unstable stratification dominates based on the values of Obukhov length. Uncertainty exists regarding the assumption of SAR image neutrality used to calculate wind fields, an issue that has also been reported in previous studies across different applications Hasager et al. (2011a); Ahsbabs et al. (2017). Furthermore, there is uncertainty in the estimation of L within WRF, as it strongly depends on the PBL and surface schemes applied in each configuration.

In addition to the wind speed deficit maps, Figure 17 presents the transects that connect WHi, BSB, and EPL. The green line illustrates the ~~SAR~~-10-meter height SAR wind speeds, while the ~~blue-purple~~ and orange lines correspond to the WF and NWF simulation outputs, respectively. Although a Hampel filter (see ~~Section~~ section 2.3.3) has been applied to the transect of the SAR data, we can still observe a few outlier values, especially in the intra-farm area. The wind turbines generate spikes in the wind fields due to strong radar reflection (Hasager et al., 2015; Ahsbabs et al., 2020). Therefore, to further evaluate the performance of the WRF model, hub height-lidar measurements are incorporated when available, depicted as gray scatter points in Figure 17. In addition to the qualitative assessment of the wind speeds in Figure 17, Table 8 presents the MAE across the upstream, intra-farm, and downstream transect regions, as well as the point-wise AE, when lidar measurements are available, and the evaluation methodology is described in section 2.3.4. In cases A, B, and C (NE wind flow), the transect follows the direction EPL (upstream) $\rightarrow$ BSB (intra-farm) $\rightarrow$ WHi (downstream), whereas case D corresponds to a SW flow event, where the sequence reverses.

Case A shows good agreement in the representation of the transect wake. Specifically, while the WF simulation tends to underestimate wind speeds upstream and within the Borssele zone, it accurately captures the wind speed deficit in the Belgian wind farms and downstream of the wind farm cluster. This is also reflected in Table 8, where only in the upstream region WF generates a slightly higher $MAE = 0.49 \text{ ms}^{-1}$, compared to $MAE=0.37 \text{ ms}^{-1}$ in the NWF simulation. However, the improvement between the WF against the NWF simulations in MAE in the intra-farm region and downstream is 81% and 85%, respectively. Similarly, in Case B, both the intra-farm and downstream wind speed patterns are well represented by the WF simulation, ~~whereas the NWF case fails to capture the wind speed deficit.~~ Although the overall trend is accurately reproduced, the WF simulation tends to overestimate the wind speeds ~~downstream-upstream and downstream of~~ the wind farms. Additionally, a flow acceleration is observed as the wind exits the Belgian-Dutch cluster. This ~~can be attributed to a misalignment in wind direction, with the simulated flow being closer to westerly (see Figure 16, B), causing the transect~~

points to shift toward the southern edge of the wake and partially escape the waked region pattern is consistent with the broader flow conditions downstream of the Belgian-Dutch cluster, since a similar acceleration is evident in the SAR observations and in both the WF and NWF simulations. Both the lidar measurements and the WF simulation effectively capture the intra-farm wind speed deficit and the downstream flow acceleration. A maximum positive bias of approximately 1 is observed at EPL. Although the averaged stability trends shown in Figure 9 (A) appear to contradict this positive bias, it is important to note that Case B represents a discrete timestamp and therefore cannot be considered representative of the average ABL conditions. Furthermore, in Table 8, MAE and AE are better in the WF than NWF simulation across the full transect regions.

Case C also features NE incoming wind conditions. Similar to the previous cases, the WF simulation successfully captures the wind speed deficit trends both within the intra-cluster zone and in the downstream wake recovery region. The WF simulation shows noticeable discrepancies. Both the NWF and WF simulations show noticeable discrepancies upstream at EPL compared to lidar observations, particularly with an AE reaching above 3 ms^{-1} . This is significantly improved both at BSB and EPL, where negative biases of approximately 1.7, and 3, respectively are observed. MO length is relatively large downstream at WHi, where WF simulations outperform the NWF runs both in terms of MAE across the transect regions and AE against the lidar measurements. During this event, the Obukhov length at EPL is relatively high and negative, indicating unstable to near-neutral conditions. This may be attributed to elevated less negligible shear, which can contribute to increased deviations from the lidar measurements. In contrast, at BSB, the NWF simulation exhibits a significantly lower but positive bias. However, in this case, it produces an unrealistic and nearly linear increase linearly increasing pattern in wind speed of approximately 0.5 ms^{-1} between EPL and WHi is observed. Case D is the only selected timestamp with a SW wind direction. Although the SAR data exhibit considerable noise, particularly within the intra-farm region, the WF simulation is still able to reproduce the wind speed deficit and the downstream recovery trends wake-recovery trend. In this case, only EPL lidar measurements are available, which show good agreement with the WF simulation, with a slightly improved AE compared to the NWF run. Furthermore, the MAE provides a more accurate matching with the 10-meter SAR wind speeds across the three transect regions in the WF simulations.

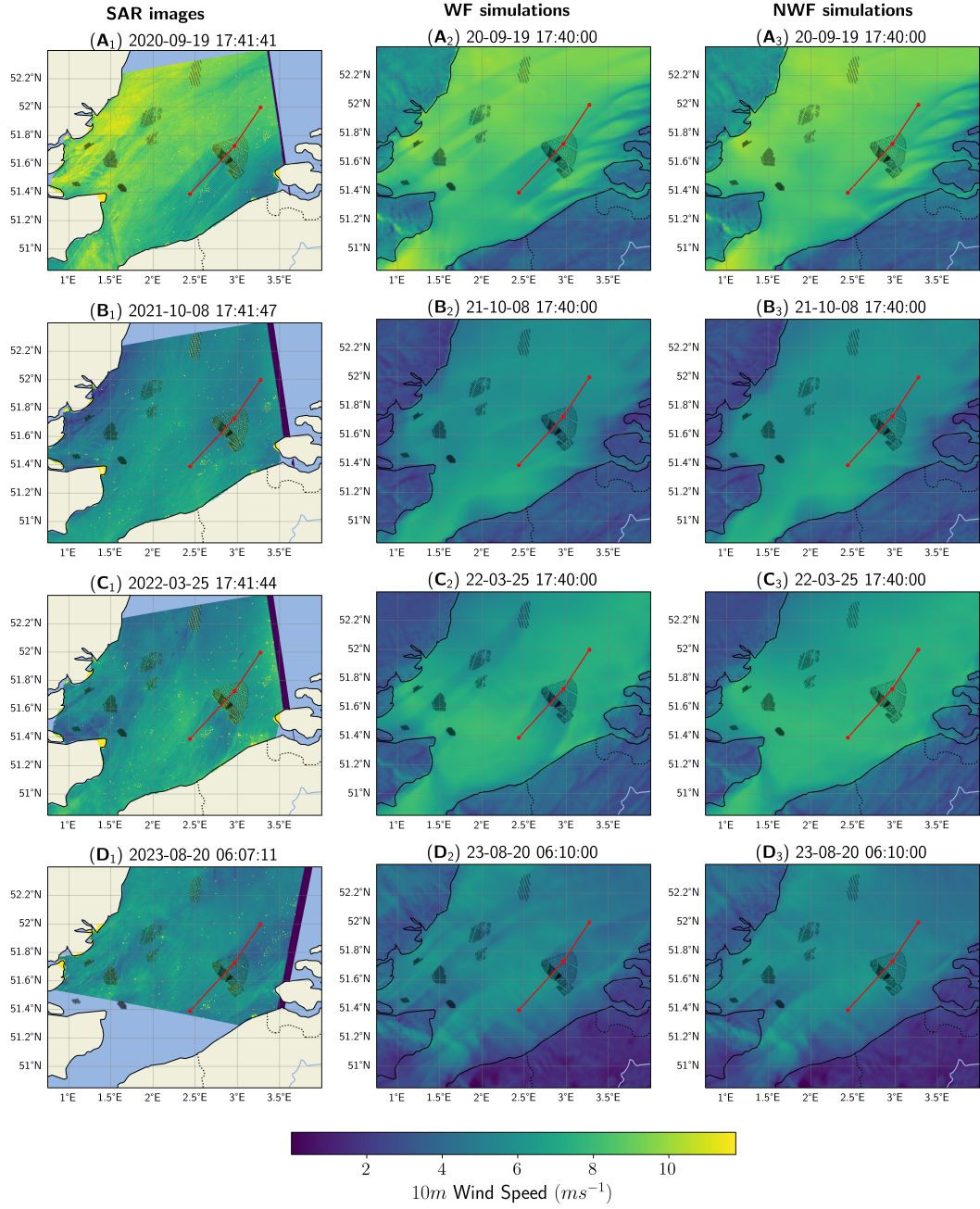


Figure 16. ~~10-meter height~~ Two-dimensional wind speeds at 10-meter height: SAR images (left, subscript 1), WF simulations (middle, subscript 2), and NWF simulations (right, subscript 3). Four ~~discrete timestamps~~ snapshots are compared where the wind farm-produced wake is present ~~in both cases~~. The red line depicts the transect ~~among~~ connecting the WHi, BSB, and EPL locations.

Table 8. Mean Absolute Error (MAE) and point-wise lidar absolute error (AE) for the NWF and WF simulations. MAE is computed across the upstream, intra-farm, and downstream regions of the transects shown in Figure 17. The intra-farm region corresponds to the full Belgian-Dutch cluster, delineated by the two vertical dashed black lines.

Case	<u>WHi</u>				<u>BSB</u>				<u>EPL</u>			
	<u>SAR MAE</u> (ms ⁻¹)		<u>Lidar AE</u> (ms ⁻¹)		<u>SAR MAE</u> (ms ⁻¹)		<u>Lidar AE</u> (ms ⁻¹)		<u>SAR MAE</u> (ms ⁻¹)		<u>Lidar AE</u> (ms ⁻¹)	
	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>	<u>NWF</u>	<u>WF</u>
<u>A</u> ^a	<u>1.38</u>	<u>0.20</u>	<u>N/A</u>	<u>N/A</u>	<u>1.08</u>	<u>0.20</u>	<u>N/A</u>	<u>N/A</u>	<u>0.37</u>	<u>0.49</u>	<u>N/A</u>	<u>N/A</u>
<u>B</u> ^a	<u>1.10</u>	<u>0.62</u>	<u>1.18</u>	<u>0.86</u>	<u>1.07</u>	<u>0.22</u>	<u>1.26</u>	<u>0.77</u>	<u>0.58</u>	<u>0.43</u>	<u>1.16</u>	<u>1.10</u>
<u>C</u> ^a	<u>1.33</u>	<u>0.66</u>	<u>0.98</u>	<u>0.56</u>	<u>1.43</u>	<u>0.66</u>	<u>1.46</u>	<u>0.54</u>	<u>1.04</u>	<u>0.75</u>	<u>3.04</u>	<u>3.06</u>
<u>D</u> ^b	<u>0.30</u>	<u>0.29</u>	<u>N/A</u>	<u>N/A</u>	<u>0.51</u>	<u>0.29</u>	<u>N/A</u>	<u>N/A</u>	<u>0.67</u>	<u>0.59</u>	<u>0.22</u>	<u>0.20</u>

^a WHi is downstream and EPL upstream ^b WHi is upstream and EPL downstream

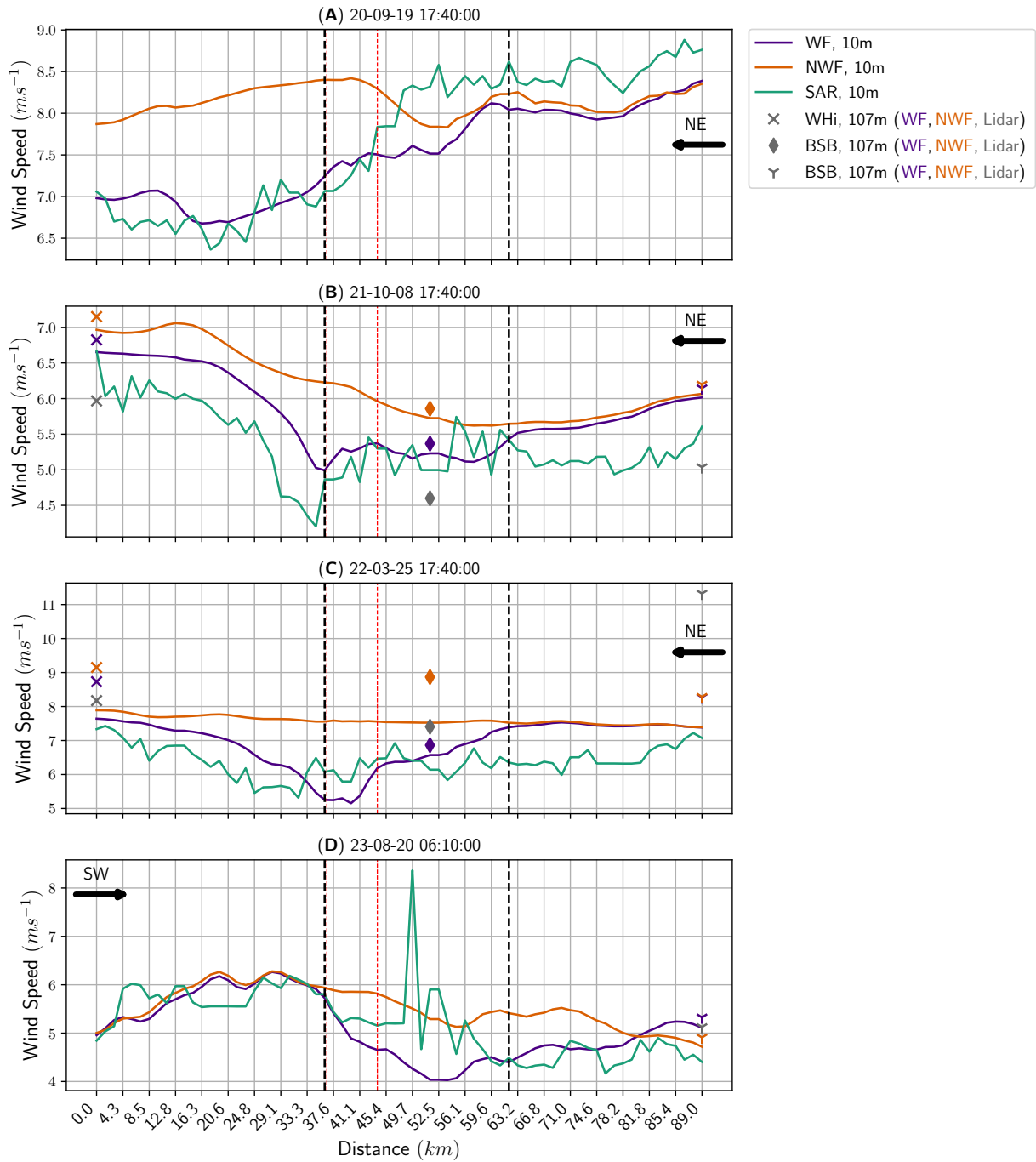


Figure 17. Wind speeds along WHi, BSB, and EPL transect. Comparison between WF (purple), NWF (orange), and SAR (green) at 10 meters height. Validation against WHi, BSB, and EPL lidars (scatter points, when available) at 107 meters height. Similar to Figures 12 and 13, the vertical black and red dashed lines indicate the Belgian-Dutch cluster and the Belgian zone only, respectively.

4 Conclusions

This study incorporates high-resolution mesoscale simulations using WRF coupled with the Fitch WFP scheme over a three-year-long period (2021-2023), focusing on the Southern Bight of the North Sea. The ~~model is systematically validated using both lidar measurements and synthetic aperture radar (SAR) imagery. More precisely, the~~ performance of the model is evaluated ~~over the~~ across the full three-year simulation period, ~~while additional analysis with additional analysis presented~~ under varying ABL stability conditions and wind speed magnitudes ~~is presented~~. Furthermore, the model-simulated wind speeds are compared against 10-meter wind speeds derived from SAR data for specific events. A key contribution lies in the detailed investigation of upstream, intra-farm, and downstream wake structures, utilizing both WRF model outputs and observational data at selected locations.

Our findings demonstrate that the use of the Fitch WFP scheme, in combination with this particular WRF configuration, ~~is largely able to capture captures the~~ wake effects and ~~improve the general accuracy over provides an improvement in model performance relative to~~ a simulation without wind farms ~~included at the intra-farm region~~. First, focusing on the time-averaged wind speeds over the full analysis period, the WF simulations ~~provide lower bias values (about 36% reduction) across the domain, along with reduced eRMSE (improved by 4% approximately), and EMD (a decrease of around 36%) yield a~~ substantial improvement in both bias and EMD, with reductions of approximately 82% and 73% compared with the NWF simulations, respectively, in the intra-cluster region (BSB location). Furthermore, when analyzing the wind speed bias under different wind directions, both NWF and WF configurations reduce the negative bias inherited from the ERA5 data, with the results indicating that the Fitch scheme introduces an additional deficit downstream of the Belgian-Dutch cluster. However, within the intra-farm area, the Fitch scheme provides a more accurate wind speed distribution across all wind directions, ~~underscoring its importance for representing strongly-waked environments. Beyond the improvements in bias and EMD, the WF simulations perform similarly to the NWF runs in terms of eRMSE and correlation, with only small and marginal differences.~~ Similarly, wind direction metrics are also improved in the WF simulations, as bias is reduced by approximately ~~65~~51 % at BSB, while ~~eRMSE and EMD are improved by approximately 8% and 15%, respectively. an analysis of wind direction biases by sector reveals that WF can perform better than ERA5 for wind directions from northeast to south.~~

The ABL classification based on the values of ~~MO~~ Obukhov length indicates that very unstable conditions prevail close to the Belgian-Dutch cluster. In addition, this work highlights that when the stability conditions are near-neutral, WF simulations provide an adequate comparison against the lidars, while during extreme stratification, the uncertainty of the model increases. Classifying wake events based on wind speed magnitude reveals that ~~, as wind speed increases, atmospheric stability transitions increasing wind speeds are associated with a transition in ABL stability~~ from very unstable toward neutral and stable ~~conditions. The regimes, accompanied by intensified wake intensity.~~

Extending the performance metrics to wake characteristics under different wind speed magnitudes, and focusing on SW and NE wind directions, the analysis revealed several consistent patterns. First, under SW wind direction, the WF simulations accurately capture the wake structure when wind speeds range between 5 to 8 ms⁻¹, providing an almost negligible bias at BSB and downstream at EPL. Under NE wind direction, the optimum performance of WF simulations occurs at wind

710 speeds between 8 and 11 ms⁻¹. Although the model tends to overestimate intra-farm wind speed deficits at BSB under higher wind speed conditions, it ~~accurately captures the~~ shows comparable improvements in long-distance downwind wakes at EPL (~~SW wind direction for SW winds~~) and WHi (~~NE wind direction~~), ~~yielding smaller discrepancies when compared to lidar measurements. The analysis of~~ for NE winds), where smaller bias and cRMSE values are obtained. The differences in wake structure and its evaluation under SW and NE wind ~~directions also provides insights into the development of blockage effects~~ in the Belgian-Dutch cluster. Specifically, ~~an~~ conditions likely reflect the influence of the densely built Belgian wind farm cluster compared with the coarser turbine spacing in the Borssele zone. Furthermore, with increasing wind speed, an overall enhancement in the 95% wake recovery area and maximum wake length is observed. In addition, an upstream wind speed reduction zone of about 5 ~~km to 8 km~~ km is observed when ~~the wind is SW, while in the case of NE wind direction, this zone can be shorter, around 3 km~~ wind speed is below 5 and 8 ms⁻¹, respectively. As the wind speed magnitude increases, the blockage effect weakens, and the flow remains more aligned with the turbine cluster, resulting in a more coherent downstream structure.

720 Furthermore, a comparison with SAR images at specific events shows that WF performs well in representing the wake structure generated by the Belgian-Dutch cluster. Both in the intra-farm and the wake recovery regions, WF provides a realistic wind speed deficit. ~~This work~~ To assess the performance of the model during these events, MAE and AE are computed. More specifically, MAE is estimated across the upstream, intra-farm, and downstream regions, while AE is calculated at each lidar location when measurements are available. Building on the previously discussed improvements in the qualitative wake-pattern representation, the error metrics further confirm that the WF simulations provide a better alignment with observations than the NWF runs across all locations, with the most pronounced improvements occurring in the intra-farm and downstream regions.

730 This study can accurately evaluate the model performance by utilizing upwind, intra-farm, and downwind lidar measurements as well as SAR images at specific events. Systematic biases in both wind speed and direction are evident, particularly in the wind speed metrics. However, it should be highlighted that the model is driven by ERA5 hourly data, which consistently introduce ~~a negative bias~~ biases, affecting the boundary conditions in WRF and propagating wind speed underestimations to the analyzed locations. In addition, due to uncertainties introduced by the PBL schemes in WRF, exploring alternative physics configurations in the future may be warranted to enhance simulation accuracy. ~~Furthermore, benchmarking different wind farm parameterization schemes for this case study is an interesting area of future research~~ The scope of this study is limited to using the Fitch WFP scheme combined with the MYNN 2.5 PBL scheme. Additional multi-year simulations using different WFP schemes, like the explicit wind farm (EWP) parametrization scheme (Volker et al., 2015; García-Santiago et al., 2024) applied with different PBL schemes or the induction correction to the original Fitch scheme (Vollmer et al., 2024), could also provide insights into the year-long effects of large wind-farm clusters.

740 This work may serve as a resource for future studies, offering a comprehensive three-year analysis of ABL stratification, wake dynamics, and model validation. The importance of mesoscale models is underscored ~~as~~ since they can adequately describe the wake effects at large scales, where high-fidelity simulations are still impractical. In addition, the availability of measurements is essential for ensuring the reliability of numerical simulations and for quantifying associated uncertainties. Finally, further improving our understanding of wind farm wake dynamics will require both advances in wind farm modelling and more extensive measurement campaigns.

745 *Code and data availability.* The ERA5 hourly reanalysis data (Hersbach et al., 2020) that have been used in this study are publicly available and they can be downloaded from the Copernicus Climate Data Store at <https://doi.org/10.24381/cds.bd0915c6>. WRF is an open source model and the version used in this study can be found in Github: <https://github.com/wrf-model/WRF/releases/tag/v4.5.2>. The files used to configure the WRF simulations can be shared upon request. The lidar profiles provided by TNO (EPL and LEG platforms) are publicly accessible: <https://offshorewind-measurements.tno.nl/en/data/>. The lidar profiles located at the BSB platform are provided by KNMI: <https://datapatform.knmi.nl/dataset/windlidar-nz-wp-platform-10min-1>. WHi lidar profiles remain confidential.

Appendix A: Validation of the model

A1 Evaluation metrics

The equations used to calculate the wind speed metrics:

$$\text{Bias}_V = \frac{\sum_i^N (V_{\text{WRF},i} - V_{\text{lidar},i})}{N}, \quad (\text{A1})$$

$$750 \quad \text{cRMSE}_V = \sqrt{\frac{\sum_i^N ((V_{\text{WRF},i} - \bar{V}_{\text{WRF}}) - (V_{\text{lidar},i} - \bar{V}_{\text{lidar}}))^2}{N}}, \quad (\text{A2})$$

$$r_V = \frac{\sum_i^N (V_{\text{WRF},i} - \bar{V}_{\text{WRF}}) - (V_{\text{lidar},i} - \bar{V}_{\text{lidar}})}{\sqrt{\sum_i^N (V_{\text{WRF},i} - \bar{V}_{\text{WRF}})^2} \sqrt{\sum_i^N (V_{\text{lidar},i} - \bar{V}_{\text{lidar}})^2}}. \quad (\text{A3})$$

The equations used to calculate the wind direction scores are defined in this [Section](#):

$$\text{circmean}(\theta) = \text{atan2} \left(\frac{1}{N} \sum_i^N \sin(\theta_i), \frac{1}{N} \sum_i^N \cos(\theta_i) \right), \quad (\text{A4})$$

$$\text{Bias}_\theta = \text{circmean}(\theta_{\text{WRF}} - \theta_{\text{lidar}}), \quad (\text{A5})$$

$$760 \quad \text{cRMSE}_\theta = \sqrt{\text{circmean}(|180^\circ - |(\theta_{\text{WRF},i} - \bar{\theta}_{\text{WRF}}) - (\theta_{\text{lidar},i} - \bar{\theta}_{\text{lidar}})| - 180^\circ|)^2}, \quad (\text{A6})$$

$$\rho_\theta = \frac{\sum_i^N \sin(\theta_{\text{WRF},i} - \text{circmean}(\theta_{\text{WRF}})) \sin(\theta_{\text{lidar},i} - \text{circmean}(\theta_{\text{lidar}}))}{\sqrt{\sum_i^N \sin^2(\theta_{\text{WRF},i} - \text{circmean}(\theta_{\text{WRF}}))} \sqrt{\sum_i^N \sin^2(\theta_{\text{lidar},i} - \text{circmean}(\theta_{\text{lidar}}))}}. \quad (\text{A7})$$

A2 Model Performance under various ABL Stratification conditions

Figures ??, ?? depict similar results with Figures 9, and 10, respectively. However, in this case we do not filter the wind speed and wind directions from WRF when $U_{\text{WRF}} < 0.5$. The Earth Mover's Distance is assessed using the Wasserstein first distance (WD). WD is defined as a distance between two probability measures P and $U_{\text{WRF}} > 70$. Compared to wind speed metrics in Figure 9, the application of filtering does not significantly affect the overall metrics. However, Figure 10 shows that cRMSE and ρ exhibit a significant improvement in wind direction when wind speed is filtered Q on a metric space $(\mathcal{R} \times \mathcal{R})$ by

$$\text{EMD}(P, Q) = \inf_{\gamma \in \Gamma(P, Q)} \int_{\mathcal{R} \times \mathcal{R}} \|x - y\| \, d\gamma(x, y), \quad (\text{A8})$$

where $\Gamma(P, Q)$ denotes the set of all couplings with marginals P and Q .

770 ~~WRF-assessed hub-height wind speed against lidar Locations: Bias (A), eRMSE (B), EMD (C), and r (D) scores. ABL classes are assessed at BSB in the NWF simulations. Distance from the black dashed line reflects the degree of misalignment with observations~~

~~WRF-assessed hub-height wind direction against lidar Locations: Bias (A), eRMSE (B), EMD (C), and r (D) scores. ABL classes are assessed at BSB in the NWF simulations. Distance from the black dashed line reflects degree of misalignment with~~
775 ~~observations~~

Appendix B: Tables

Author contributions. APP contributed to the conceptualization, investigation, methodology, software, data curation, writing (original draft), and writing (review and editing). SG contributed to the methodology and writing (review and editing). JvB contributed to funding acquisition, supervision, and writing (review and editing). LDC contributed to methodology, supervision, and writing (review and editing). WM
780 contributed to conceptualization, investigation, methodology, writing (review and editing), supervision, project administration, and funding acquisition.

Competing interests. The authors declare that they do not have any competing interests.

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Country	Wind Farm	Turbines (#)	Turbine-Capacity	Hub Height (m)	Rotor Diameter (m)
Belgium	C-Power I	6	Senvion-5.0 MW	93.3	126
Belgium	C-Power II & III	48	Senvion-6.15 MW	93.3	126
Belgium	Rentel	42	SWT-7.35 MW	102	154
Belgium	Northwind	72	Vestas-3.0 MW	80.1	112
Belgium	Northwester 2	23	Vestas-9.5 MW	107	164
Belgium	Norther	44	Vestas-8.4 MW	107	164
Belgium	Nobelwind	50	Vestas-3.3 MW	77.1	112
Belgium	Belwind I	55	Vestas-3.0 MW	70.1	112
Belgium	Belwind I	1	Alstom Hailiade-6.0 MW	98.1	150
Belgium	Seastar	30	SG-8.4 MW	107	164
Belgium	Mermaid	28	SG-8.4 MW	107	164
Netherlands	Borssele I & II	94	SWT-8.4 MW	107	164
Netherlands	Borssele III & IV	77	Vestas-9.5 MW	107	164
Netherlands	Borssele V	2	Vestas-9.5 MW	107	164
Netherlands	Luchterduinen	43	Vestas-3.0 MW	81	112
Netherlands	Egmond aan Zee	36	Vestas-3.0 MW	70	90
Netherlands	Princess Amalia	60	Vestas-2.0 MW	60	80
UK	Scroby Sands	30	Vestas-2.0 MW	68	80
UK	East Anglia ONE	102	SG-7.0 MW	120	154
UK	Galloper	56	SWT-6.0 MW	88	154
UK	Greater Gabbard	140	SWT-3.6 MW	78	107
UK	Gunfleet Sands I & 2	48	SWT-3.6 MW	78	107
UK	Gunfleet Sands III	2	SWT-6.0 MW	84	120
UK	London Array	175	SWT-3.6 MW	87	120
UK	Kentfish Flats I	30	Vestas-3.0 MW	70	90
UK	Kentfish Flats II	15	MHI Vestas-3.3 MW	83.6	112
UK	Thanet	100	Vestas 3.0 MW	70	90

Table A1. [Details on the wind farms used in the model set-up. Power and thrust curves remain confidential for most of the wind turbines used in the Fitch WFP.](#)

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